

On the concentration of interacting particle processes

Part II : Application domains

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Boltzmann-Gibbs measures

- Interacting Markov chain Monte Carlo
- Subset methodology
- Interacting simulated annealing
- Interacting Island models

Rare event analysis

- Tail probabilities
- Level crossing probabilities
- Excursion level crossing

Sensitivity measures

- Parameter derivatives
- Gradient of Markov semigroup

Estimation with partial observation

- Nonlinear filtering
- Hidden Markov chain problems

Particle absorption models

- QMC & DMC algorithms
- Doob h-processes
- Ground states-Quasi-invariant-Yaglom measures

Boltzmann-Gibbs measures

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Boltzmann-Gibbs measures

$$\mu_n(dx) = \frac{1}{Z_n} \left\{ \prod_{0 \leq p < n} h_p(x) \right\} \lambda(dx)$$

- ▶ Markov chain Monte Carlo moves

$$\mathbb{P}(X_n \in dx | X_{n-1}) = M_n(X_{n-1}, dx) \quad \text{s.t.} \quad \mu_n M_n = \mu_n$$

- ▶ Updating transitions

$$\mu_{n+1} = \Psi_{h_n}(\mu_n)$$

⇓

$$\mu_{n+1} = \mu_{n+1} M_{n+1} = \Psi_{h_n}(\mu_n) M_{n+1}$$

⇓

$$\mu_n(f_n) \propto \mathbb{E} \left(f_n(X_n) \prod_{0 \leq p < n} h_p(X_p) \right) \rightsquigarrow \text{Interacting MCMC}$$

Subset methodology

A_n decreasing sequence of subset levels

$$\mu_n(dx) = \frac{1}{Z_n} \left\{ \prod_{0 \leq p < n} 1_{A_{p+1}}(x) \right\} \lambda(dx) = \frac{1}{\lambda(A_n)} 1_{A_n}(x) \lambda(dx)$$

- ▶ Markov chain Monte Carlo moves in each set A_n

$$\mathbb{P}(X_n \in dx | X_{n-1}) = M_n(X_{n-1}, dx) \quad \text{s.t.} \quad \mu_n M_n = \mu_n$$

- ▶ Updating transitions $\in A_{n+1}$

$$\mu_{n+1} = \Psi_{1_{A_{n+1}}}(\mu_n)$$

Important observation: [counting pb, volume computation, tail event probability]

$$\lambda(A_n) = \lambda(A_0) \quad Z_n = \lambda(A_0) \prod_{0 \leq p < n} \mu_p(1_{A_{p+1}})$$

Interacting simulated annealing

$$h_p(x) = \exp(-(\beta_{p+1} - \beta_p)V(x))$$

$$\Downarrow (\beta_0 = 0)$$

$$\mu_n(dx) = \frac{1}{Z_n} \left\{ \prod_{0 \leq p < n} h_p(x) \right\} \lambda(dx) = \frac{1}{\lambda(e^{-\beta_n V})} e^{-\beta_n V(x)} \lambda(dx)$$

- ▶ Simulated annealing style moves at temperature $1/\beta_n$

$$\mathbb{P}(X_n \in dx | X_{n-1}) = M_n(X_{n-1}, dx) \quad \text{s.t.} \quad \mu_n M_n = \mu_n$$

- ▶ Updating transitions w.r.t. inverse temperature variations $(\beta_{n+1} - \beta_n)$

$$\mu_{n+1} = \Psi_{e^{-(\beta_{n+1} - \beta_n)V}}(\mu_n)$$

Interacting Island models

$\xi_{\theta,n}$ = particle Feynman-Kac model $\sim (M_{\theta,n}, G_{\theta,n})$ and $\Theta \sim \nu(d\theta)$

$$\left. \begin{aligned} x &= (\theta, (\xi_{\theta,n})_{n \in [0, T]}) \\ h_n(x) &= \eta_{\theta,n}^N(G_{\theta,n}) \end{aligned} \right\} \rightarrow \mu_n(dx) = \frac{1}{Z_n} \left\{ \prod_{0 \leq p < n} h_p(x) \right\} \lambda(dx)$$

By the unbiased property (cf. lecture I)

$$\mu_n \circ \Theta^{-1} = \frac{1}{Z_n} \left\{ \prod_{0 \leq p < n} \eta_{\theta,n}(G_{\theta,n}) \right\} \nu(d\theta)$$

- ▶ MCMC shaking moves in (parameter-island)-spaces

$$\mathbb{P}(X_n \in dx | X_{n-1}) = M_n(X_{n-1}, dx) \quad \text{s.t.} \quad \mu_n M_n = \mu_n$$

- ▶ Updating w.r.t. the average fitness of the islands $\eta_{\theta,n}^N(G_{\theta,n})$

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3 type of events:

- ▶ red Tail probabilities

$$\mathbb{P}(X \in A) \quad \& \quad \text{Law}(X \mid X \in A) \subset \text{Boltzmann-Gibbs models}$$

- ▶ Level crossing at a fixed given time

$$\mathbb{P}(V_n(X_n) \geq a) \quad \& \quad \text{Law}((X_0, \dots, X_n) \mid V_n(X_n) \geq a)$$

- ▶ Excursion level crossing

$$\mathbb{P}(X \text{ hits } A_n \text{ before } B) \quad \text{Law}((X_n)_{0 \leq n \leq T_{A_n}} \mid X \text{ hits } A_n \text{ before } B)$$

Examples:

Networks overload, breakdowns, failures, uncertainty propagation in numerical codes, ruin-default probabilities.

Level crossing probabilities



- ▶ Level crossing at a fixed given time

$$\begin{aligned}\mathbb{P}(V_n(X_n) \geq a) &= \mathbb{E}\left(f_n(\mathbf{X}_n) e^{V_n(X_n)}\right) \\ &= \mathbb{E}\left(\mathbf{f}_n(\mathbf{X}_n) \prod_{0 \leq p < n} G_p(\mathbf{X}_p)\right)\end{aligned}$$

with

$$\mathbf{X}_n = (X_n, X_{n+1}) \quad \text{and} \quad G_n(\mathbf{X}_n) = e^{V_{n+1}(X_{n+1}) - V_n(X_n)}$$

and the test function

$$f_n(\mathbf{X}_n) = 1_{V_n(X_n) \geq a} e^{-V_n(X_n)}$$

Level crossing probabilities

- ▶ Level crossing at a fixed given time

$$\begin{aligned}\mathbb{P}(V_n(X_n) \geq a) &= \mathbb{E}\left(f_n(\mathbf{X}_n) e^{V_n(X_n)}\right) \\ &= \mathbb{E}\left(\mathbf{f}_n(\mathbf{X}_n) \prod_{0 \leq p < n} G_p(\mathbf{X}_p)\right)\end{aligned}$$

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$$\mathbf{X}_n = (X_n, X_{n+1}) \quad \text{and} \quad G_n(\mathbf{X}_n) = e^{V_{n+1}(X_{n+1}) - V_n(X_n)}$$

and the test function

$$f_n(\mathbf{X}_n) = \mathbf{1}_{V_n(X_n) \geq a} e^{-V_n(X_n)}$$

Level crossing probabilities

- ▶ Level crossing at a fixed given time (continued)

$$\mathbf{X}_n = (X_n, X_{n+1}) \quad \text{and} \quad G_n(\mathbf{X}_n) = e^{V_{n+1}(X_{n+1}) - V_n(X_n)}$$

Conditional distributions w.r.t. the critical event

$$\begin{aligned} & \mathbb{E}(\varphi_n(X_0, \dots, X_n) \mid V_n(X_n) \geq a) \\ &= \mathbb{E}(F_{n, \varphi_n}(X_0, \dots, X_n) e^{V_n(X_n)}) / \mathbb{E}(F_{n, 1}(X_0, \dots, X_n) e^{V_n(X_n)}) \\ &= \mathbb{Q}_n(F_{n, \varphi_n}) / \mathbb{Q}_n(F_{n, 1}) \end{aligned}$$

with the function

$$F_{n, \varphi_n}(X_0, \dots, X_n) = \varphi_n(X_0, \dots, X_n) \mathbf{1}_{V_n(X_n) \geq a} e^{-V_n(X_n)}$$

Excursion level crossing

Multilevel decomposition $A_n \downarrow$, with B non critical recurrent subset.

$$\mathbb{P}(X \text{ hits } A_n \text{ before } B) = \mathbb{E} \left(\prod_{0 \leq p \leq n} 1_{A_p}(X_{T_p}) \right)$$

$$T_n := \inf \{p \geq T_{n-1} : X_p \in (A_n \cup B)\}$$

Feynman-Kac model in excursion spaces

$$\mathbb{E} \left(\prod_{0 \leq p \leq n} 1_{A_p}(X_{T_p}) \right) = \mathbb{E} \left(\prod_{0 \leq p < n} G_p(\mathbf{X}_p) \right)$$

with

$$\mathbf{X}_n = (X_p)_{p \in [T_n, T_{n+1}]} \quad \& \quad G_n(\mathbf{X}_n) = 1_{A_{n+1}}(X_{T_{n+1}})$$

Excursion level crossing

Multilevel decomposition $A_n \downarrow$, with B non critical recurrent subset.

$$\mathbb{P}(X \text{ hits } A_n \text{ before } B) = \mathbb{E} \left(\prod_{0 \leq p \leq n} 1_{A_p}(X_{T_p}) \right)$$

$$\mathbf{X}_n = (X_p)_{p \in [T_n, T_{n+1}]} \quad \& \quad G_n(\mathbf{X}_n) = 1_{A_{n+1}}(X_{T_{n+1}})$$

\Downarrow

Conditional distributions

$$\mathbb{E}(\mathbf{f}_n(X_{[0, T_{n+1}]}) \mid X \text{ hits } A_n \text{ before } B) = \mathbb{Q}_n(\mathbf{f}_n)$$

Boltzmann-Gibbs measures

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Sensitivity measures

Parameter derivatives

Gradient of Markov semigroup

Estimation with partial observation

Particle absorption models

Parameter derivatives

Derivation FK models = FK Integration w.r.t. additive functionals

Computation of Feynman-Kac semigroup derivatives w.r.t. some parameter $\theta \in \mathbb{R}^d$ (here $d = 1$)

$$Q_n^\theta(x_{n-1}, dx_n) = H_n^\theta(x_{n-1}, x_n) \nu_n(dx_n)$$

$$\Rightarrow \frac{\partial}{\partial \theta} \mathbb{E} \left(f_n(X_0^\theta, \dots, X_n^\theta) \prod_{0 \leq p < n} G_p^\theta(X_p^\theta) \right) \propto Q_n^\theta(f_n \times \Gamma_n^\theta)$$

with the additive functional

$$\Gamma_n^\theta(x_0, \dots, x_n) = \sum_{1 \leq p \leq n} \frac{\partial}{\partial \theta} \log H_p^\theta(x_{p-1}, x_p)$$

Parameter derivatives (continued)

Derivation FK models = FK Integration w.r.t. additive functionals

Example $d = 1$ & $(G_n^\theta, M_n^\theta) = (G_n^\theta, M_n)$

$$\frac{\partial}{\partial \theta} \log \mathcal{Z}_n^\theta = \mathbb{Q}_n^\theta(\Gamma_n^\theta) \quad \& \quad \frac{\partial}{\partial \theta} \mathbb{Q}_n^\theta(f_n) = \mathbb{Q}_n^\theta(f_n [\Gamma_n^\theta - \mathbb{Q}_n^\theta(\Gamma_n^\theta)])$$

with the additive functional

$$\Gamma_n^\theta(x_0, \dots, x_n) = \sum_{0 \leq p < n} \frac{\partial}{\partial \theta} \log G_p^\theta(x_p)$$

Markov semigroup derivation (here $d = 1$)

$$P_n(f)(x) := \mathbb{E}(f(X_n(x)))$$

with

$$X_{n+1}(x) = F_n(X_n(x), W_n) \quad X_0(x) = x$$

↓

1st order variational equation

$$\frac{\partial X_n}{\partial x} = \frac{\partial F_{n-1}}{\partial x}(X_{n-1}, W_{n-1}) \frac{\partial X_{n-1}}{\partial x} = \prod_{0 \leq p < n} G_p(X_p, W_p)$$

FK-representation formula

$$\nabla P_n(f)(x) := \mathbb{E}_x \left(\nabla f(X_n) \prod_{0 \leq p < n} G_p(X_p, W_p) \right)$$

$d > 1$ Noncommutative models \rightsquigarrow sequential proj. on the unit sphere

Boltzmann-Gibbs measures

Rare event analysis

Sensitivity measures

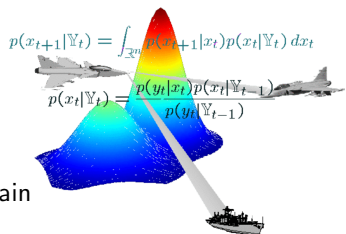
Estimation with partial observation

Nonlinear filtering

Hidden Markov chain problems

Particle absorption models

Nonlinear filtering and smoothing



Signal-Observation model: $(X, Y) =$ Markov chain

$$\mathbb{P}((X_n, Y_n) \in d(x, y) | (X_{n-1}, Y_{n-1})) := M_n(X_{n-1}, dx) g_n(x, y) \nu_n(dy)$$

- ▶ Conditional distributions: fixed obs. $Y = y$, $G_n(x_n) \propto g_n(x_n, y_n)$

$$\mathbb{Q}_n = \text{Law}((X_0, \dots, X_n) | \forall 0 \leq p < n \ Y_p = y_p)$$

- ▶ Normalizing constants:

$$Z_{n+1} \propto p_n(y_0, \dots, y_n)$$

Hidden Markov chain problems



$$\text{Pb : } \theta \mapsto (X^\theta, Y^\theta) \rightsquigarrow \text{Arg-max}_\theta p_n(y_0, \dots, y_n \mid \theta)$$

Bayesian formulation:

$$dp(\theta \mid (y_0, \dots, y_n)) = \frac{1}{Z_{n+1}} \mathcal{Z}_{n+1}(\theta) dp(\theta)$$

with

$$\begin{aligned} \mathcal{Z}_{n+1}(\theta) &= p_n(y_0, \dots, y_n \mid \theta) \\ &= \mathbb{E} \left(\prod_{0 \leq p \leq n} g_{p, \theta}(X_p^\theta, y_p) \right) \\ &= \prod_{0 \leq p \leq n} \eta_{\theta, p}(g_{p, \theta}) = \prod_{0 \leq p \leq n} h_p(\theta) \quad \subset \text{ Boltzmann-Gibbs models} \end{aligned}$$

NB.: Conditionally linear-Gaussian $\eta_{\theta, p}(g_{p, \theta})$ or Island-models $\eta_{\theta, p}^N(g_{p, \theta})$

Hidden Markov chains (continued)

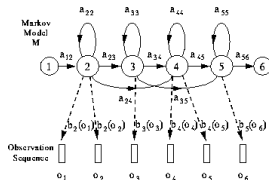


Fig. 1.3 The Markov Generation Model

Pb : $\theta \mapsto (X^\theta, Y^\theta) \rightsquigarrow \text{Arg-max}_\theta p_n(y_0, \dots, y_n | \theta)$

Frequentists formulation: EM style algo. \oplus Stochastic gradient

$$\theta_n = \theta_{n-1} + \tau_n \nabla \log \mathcal{Z}_n^{\theta_{n-1}}$$

Note:

Derivation FK models = FK Integration w.r.t. additive functionals

$$\frac{\partial}{\partial \theta} \log \mathcal{Z}_n^\theta = \mathbb{Q}_n^\theta(\Gamma_n^\theta)$$

Optimal stopping & Snell envelop

Optimal stopping time problems

$$\sup_{T \leq n} \mathbb{E} \left(f_T(X_T) \prod_{0 \leq p < T} G_p(X_p) \right)$$

Solution:

$$T^* = \inf \{0 \leq p \leq n : U_p(X_p) \leq f_p(X_p)\}$$

with the Snell envelop backward equation ($U_n = f_n$) :

$$\begin{aligned} U_p(x) &= f_p(x) \vee \int Q_{p+1}(x, dy) U_{p+1}(y) \\ &= f_p(x) \vee \int \eta_{p+1}(dy) \frac{dQ_{p+1}(x, \cdot)}{d\eta_{p+1}}(y) U_{p+1}(y) \\ &\simeq f_p(x) \vee \eta_p^N(G_p) \int \eta_{p+1}^N(dy) \frac{H_{p+1}(x, y)}{\eta_p^N(H_{p+1}(\cdot, y))} U_{p+1}(y) \end{aligned}$$

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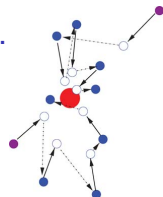
Particle absorption models

QMC & DMC algorithms

Doob h-processes

Ground states-Quasi-invariant-Yaglom measures

Absorption models \rightsquigarrow QMC+DMC algo.



- ▶ Sub Markov operators

$$Q_n(x, dy) = G_{n-1}(x) M_n(x, dy) \rightsquigarrow E_n^c = E_n \cup \{c\}$$

- ▶ Absorbed Markov chain model

$$X_n^c \in E_n^c \xrightarrow{\text{absorption} \sim (1-G_n)} \widehat{X}_n^c \xrightarrow{\text{exploration} \sim M_{n+1}} X_{n+1}^c$$

\Downarrow

$$\mathbb{Q}_n = \text{Loi}((X_0^c, \dots, X_n^c) \mid T^{\text{absorption}} \geq n)$$

et

$$\mathcal{Z}_n = \text{Proba} (T^{\text{absorption}} \geq n)$$

Doob h-processes $(G_n, M_n) = (G, M)$

- ▶ Reversibility condition : $\mu(dx)M(x, dy) = \mu(dy)M(y, dx)$

$$\text{Proba} (T^{\text{absorption}} \geq n) \simeq \lambda^n$$

with $\lambda = \text{top of the spectrum of}$

$$Q(x, dy) = G(x) M(x, dy)$$

- ▶ $Q(h) = \lambda h \rightsquigarrow$ Doob h -process X^h

$$M^h(x, dy) = \frac{1}{\lambda} h^{-1}(x) Q(x, dy) h(y) = \frac{Q(x, dy) h(y)}{Q(h)(x)} = \frac{M(x, dy) h(y)}{M(h)(x)}$$

Doob h-processes : FK formulation

$$\mathbb{Q}_n(d(x_0, \dots, x_n)) \propto \text{Proba}((X_0^h, \dots, X_n^h) \in d(x_0, \dots, x_n)) h^{-1}(x_n)$$

⇓

Correspondance formulae with the invariant measure $\mu_h = \mu_h M^h$

$$\eta_n = \Psi_{1/h}(\eta_n^h) \quad \& \quad \eta_n^h = \Psi_h(\eta_n)$$

and

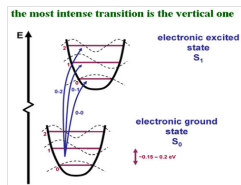
$$\eta_\infty = \Psi_{M(h)}(\mu) \quad \& \quad \eta_\infty^h := \Psi_h(\eta_\infty) = \Psi_{hM(h)}(\mu)$$

Physical interpretation $G = e^{-V}$:

$$\hat{\eta}_\infty = \Psi_G(\eta_\infty) = \Psi_h(\mu) \propto h d\mu$$

⇒ h = ground state energy

Mathematical biology: η_∞ = Quasi-inv. or Yaglom measure



Doob h-processes : Particle approximations

- ▶ Updated limiting population distribution:

$$\Psi_G(\eta_\infty) \simeq_N \Psi_G(\eta_\infty) = \Psi_h(\mu) \propto h d\mu$$

- ▶ Particle invariant measure approx.

$$\mu_h(f) \simeq_n \mathbb{Q}_n(\bar{F}_n) \simeq_N \mathbb{Q}_n^N(\bar{F}_n) \quad \text{with} \quad \bar{F}_n(\mathbf{x}_n) = \frac{1}{n+1} \sum_{0 \leq p \leq n} f(x_p)$$

- ▶ For $G = G^\theta$ related to $\theta \in \mathbb{R} \rightsquigarrow f := \frac{\partial}{\partial \theta} \log G^\theta$

$$\frac{\partial}{\partial \theta} \log \lambda^\theta \simeq_n \frac{1}{n+1} \frac{\partial}{\partial \theta} \log Z_{n+1}^\theta \simeq_N \mathbb{Q}_n^N(\bar{F}_n)$$