Particle Rare Event Stochastic Simulation

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Outline



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Some rare event models

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- Markov processes with fixed terminal values
- Multi-splitting rare events excursions
- Fixed time level set entrances
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Some motivations

Some typical rare events

- Physical/biological/economical stochastic process : atomic/molecular configurations fluctuations, queueing evolutions, communication network, portfolio and financial assets, ...
- Potential function-Event restrictions : Energy/Hamiltonian potential functions, overflows levels, critical thresholds, epidemic propagations, radiation dispersion, ruin levels.

Objectives

- Compute rare event probabilities.
- Find the law of the whole random process trajectories evolving in a critical regime → prediction ⊕ control.

→ Solution : Stochastic genealogical type tree fault model
 ~ Branching+interacting evolutionary particle model
 (Branching on "more likely" gateways to critical regimes)

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Some stochastic rare event models

Event restrictions

Event restrictions

• X r.v.
$$\in (E, \mathcal{E})$$
 with $\mu = \operatorname{Law}(X)$

•
$$A \in \mathcal{E}$$
 with $0 < \mu(A) = \mathbb{P}(X \in A) \simeq 10^{-p}$ and $p >> 1$

$$\eta(dx) = \frac{1}{\mu(A)} 1_A(x) \ \mu(dx) = \mathbb{P}(X \in dx \mid X \in A)$$

Examples

$$E = \mathbb{R}, \mathbb{R}^{d}, \mathbb{R}^{\{-n,\ldots,n\}^2}, \cup_{n \geq 0} (\mathbb{R}^{d})^{\{0,\ldots,n\}}, \ldots$$

$$A = [a, \infty[, V^{-1}([a, \infty[), \{\text{an excursion hits B before C}\}...$$

 μ = uniform on *E* finite \rightsquigarrow combinatorial counting pb

First heuristic $A_n \downarrow A$

 $\rightsquigarrow A_{n+1}$ -interacting MCMC with local targets $\propto 1_{A_n}(x) \ \mu(dx)$

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Some stochastic rare event models

A pair of more precise examples

• Non intersecting random walks/connectivity constants :

$$X = (X'_0, \dots, X'_n) \in E := (\mathbb{Z}^d \times \dots \times \mathbb{Z}^d)$$

$$A = \{(x'_0, \dots, x'_n) : \forall 0 \le p < q \le n \ x'_p \ne x'_q\}$$

$$\Rightarrow \mu(A) = \frac{1}{(2d)^n} \times \#\{ \text{not} \cap \text{ walks with length } n \}$$

$$\simeq \exp(\mathbf{c} \ n)$$

$$\Rightarrow \eta = \operatorname{Law}((X'_0, \dots, X'_n) \mid \forall p < q \le n \quad X'_p \neq X'_q)$$

Second heuristic \sim multiplicative structure

 \rightsquigarrow Accept-Reject interacting X'-motions

Some stochastic rare event models

• Random walk confinements/Lyap. exp. and top eigenval. :

$$A = \left\{ (x'_0, \dots, x'_n) \in (\mathbb{Z}^d \times \dots \times \mathbb{Z}^d) : \forall 0 \le p \le n \ x'_p \in A' \right\}$$
$$\Rightarrow \mu(A) = \mathbb{P}(\forall 0 \le p \le n \ X'_p \in A') \simeq e^{-\lambda(A') \ n}$$

and

$$\Rightarrow \eta = \operatorname{Law}((X'_0, \dots, X'_n) \mid \forall 0 \le p \le n \quad X'_p \in A')$$

Same heuristic \sim multiplicative structure .

 \rightsquigarrow Accept-Reject interacting X'-motions

Some stochastic rare event models

More examples of stochastic rare event models

•
$$\mathbb{P}(\bigcap_{0 \le p \le n} \{X_p \in A_p\}), \quad \operatorname{Law}((X_p)_{0 \le p \le n} \mid \bigcap_{0 \le p \le n} \{X_p \in A_p\})$$

• Ex.: Law(
$$(X'_0, \ldots, X'_n) \mid \bigcap_{0 \le p < q \le n} \{ \|X'_p - X'_q\| \ge \epsilon \}$$

- Soft penalization : $1_{A_n} \rightsquigarrow \exp\left(-\beta 1_{\notin A_n}\right)$
- Terminal level set conditioning :

$$\mathbb{P}(V_n(X_n) \ge a)$$
 & $\operatorname{Law}((X_0, \ldots, X_n) \mid V_n(X_n) \ge a)$

• Fixed terminal value : $Law_{\pi}((X_0, \ldots, X_n) | X_n = x_n)$.

• Critical excursion behavior : \cup in excursion space $\mathbb{P}(X \text{ hits } B \text{ before } C) \& \text{ Law}(X \mid X \text{ hits } B \text{ before } C)$

Last heuristic

 \rightarrow Interacting X-excursions on gateways levels \rightarrow B. → interacting X-transitions increasing the potential V_n . Introduction An introduction to interacting stochastic algorithms Some rare event models An introduction to continuous time models occorrection to continuous time models and the stochastic algorithms are event models are event models. An introduction to continuous time model are event models are event models are event models and the stochastic algorithms are event models. An introduction to continuous time model are event models are event models are event models. An introduction to continuous time model are event models are event models are event models. An introduction to continuous time model are event models are event models are event models. An introduction to continuous time model are event models are event models. An introduction to continuous time model are event models are event models. An introduction to continuous time model are event models are event models. An introduction to continuous time model are event models are event models. An introduction to continuous time model are event models are ev

Some stochastic rare event models

A single (sequential) Feynman-Kac/Boltzmann-Gibbs formulation:

$$d\eta_n = \frac{1}{Z_n} \left\{ \prod_{0 \le p < n} G_p(X_p) \right\} d\mathbb{P}_n^X$$

$$\stackrel{G_n = 1_{A_n}}{=} \operatorname{Law}((X_0, \dots, X_n) \mid X_0 \in A_0, \dots, X_n \in A_n)$$

and $\mathcal{Z}_n = \mathbb{P}(X_0 \in A_0, \dots, X_n \in A_n)$

Observation : η_n = "complex nonlinear" transformation of η_{n-1}

$$\left\{\prod_{0\leq p\leq n}G_p(X_p)\right\} = \left\{\prod_{0\leq p\leq (n-1)}G_p(X_p)\right\} G_n(X_n)$$

Same heuristic \sim multiplicative structure .

 \rightsquigarrow (Accept-Reject) *G*-interacting *X*-motions [and inversely!]

Stochastic sampling strategies

Stochastic modeling

- Rare event = cascade of intermediate (less) rare events (increasing energies, critical levels, multilevel gateways).
- η_n=Law(process | a series of n intermediate ↓ events)
 =nonlinear distribution flow with ↑ level of complexity.

$$\eta_0 \to \eta_1 \to \ldots \to \eta_{n-1} \to \eta_n(dx) = \frac{1}{\gamma_n(1)} \gamma_n(dx) \to \ldots$$

• Rare event probabilities = normalizing constants $\gamma_n(1) = Z_n$.

Interacting stochastic sampling strategy

- Interacting stoch. algo. = sampling w.r.t. a flow of meas.
 - Mean field particle models (sequential Monte Carlo, population Monte Carlo, particle filters, pruning, spawning, reconfiguration, quantum Monte carlo, go with the winner).
 - Interacting MCMC models (new i-MCMC technology).

Nonlinear distribution flows

• $\eta_n \in \mathcal{P}(E_n)$ probability measures on (E_n, \mathcal{E}_n) (\uparrow complexity).

$$\eta_n = \Phi_n(\eta_{n-1})$$
 with $\Phi_n : \mathcal{P}(E_{n-1}) \mapsto \mathcal{P}(E_n)$

Two important transformations

• Markov transport eq. : $M_n(x_{n-1}, dx_n)$ from E_{n-1} into E_n

$$(\eta_{n-1}M_n)(dx_n) := \int_{E_{n-1}} \eta_{n-1}(dx_{n-1}) M_n(x_{n-1}, dx_n)$$

• Boltzmann-Gibbs transformation : $G_n : E_n \to \mathbb{R}_+$

$$\Psi_{G_n}(\eta_n)(dx_n) := \frac{1}{\eta_n(G_n)} \ G_n(x_n) \ \eta_n(dx_n)$$

Feynman-Kac distribution flows

 $(Prédiction, Correction) = (Exploration, Selection) = (G_n, M_n)$

Heuristics \rightsquigarrow particle occupation measures $(\xi_n^i = i \text{-th walker/individual/particle time} = n)$

$$\eta_n^N := \frac{1}{N} \sum_{i=1}^N \delta_{\xi_n^i} \simeq_{N\uparrow\infty} \eta_n = \Phi_n(\eta_{n-1}) := \Psi_{G_{n-1}}(\eta_{n-1}) M_n$$

Solution : X_n Markov ~ transitions M_n

$$\gamma_n(f_n) = \frac{\gamma_n(f_n)}{\gamma_n(1)} \quad \text{with} \quad \gamma_n(f_n) = \mathbb{E}\left(f_n(X_n)\prod_{0 \le p < n} G_p(X_p)\right)$$

Multiplicative formula ~> Unbias estimation

$$\mathbb{E}\left(\prod_{0\leq p< n} G_p(X_p)\right) = \prod_{0\leq p< n} \eta_p(G_p) \simeq_{N\uparrow\infty} \prod_{0\leq p< n} \eta_p^{\mathsf{N}}(G_p)$$

Running example

Confinement potential

Running example : $G_n = 1_A$ (or 1_{A_n}) :

$$\Rightarrow \gamma_n(1) = \mathbb{P}(\forall 0 \le p < n \ X_p \in A)$$

$$\eta_n = \mathbb{P}(X_n \in dx_n \mid \forall 0 \le p < n \ X_p \in A)$$

Key multiplicative formula

$$\gamma_n(1) = \prod_{0 \leq p < n} \eta_p(G_p) = \prod_{0 \leq p < n} \mathbb{P}(X_p \in A \mid \forall 0 \leq q < p \mid X_q \in A)$$

Note :

 $\eta_n \neq \text{Law of a Markov process with local restrictions to } A.$

Structural stability properties

State space enlargements \rightsquigarrow same model!

$$X_n = (X'_{n-1}, X'_n)$$
 or $X_n = (X'_0, \dots, X'_n)$ or excursions
Ex.: $X_n = (X'_0, \dots, X'_n)$

$$\Rightarrow \eta_n(f_n) \propto \mathbb{E}\left(f_n(X'_0,\ldots,X'_n)\prod_{0\leq p< n}G_p(X'_0,\ldots,X'_p)\right)$$

Boltzmann-Gibbs' formulation :

$$d\eta_n = \frac{1}{\mathcal{Z}_n} \left\{ \prod_{0 \le p < n} G_p(X_p) \right\} d\mathbb{P}_n^X$$

Structural stability properties

Importance sampling distributions ~> same model!

• Change of proba. :
$$X_n = (X'_{n-1}, X'_n) \rightsquigarrow Y_n = (Y'_{n-1}, Y'_n)$$

$$\mathbb{E}\left(f_n(X_n)\prod_{0\leq p< n}G_p(X_p)\right)\propto \mathbb{E}\left(f_n(Y_n)\prod_{0\leq p< n}H_p(Y_p)\right)$$

• Related weighted meas. $G_n = G_n^{\epsilon_n} \times G_n^{1-\epsilon_n} = G_n^{(1)} \times G_n^{(2)} = \dots$

Complexity and Sampling problems

- Path integration formulae, infinite dimensional state spaces
- Nonlinear-Nongaussian models
- Complex probability mass variations

Some "Wrong" approximation ideas

• "Pure" weighted Monte Carlo methods : Xⁱ iid copies of X

$$\frac{1}{N}\sum_{i=1}^{N}f_n(X_n^i)\left\{\prod_{0\leq p< n}G_p(X_p^i)\right\} \simeq \mathbb{E}\left(f_n(X_n)\prod_{0\leq p< n}G_p(X_p)\right)$$

 \rightsquigarrow bad grids $X^i \oplus$ degenerate weights (running ex $G_n = 1_A$).

- Uncorrelated MCMC for each target measure η_n (\uparrow complex.).
- \bullet "Pure" branching interpretations \rightsquigarrow random population sizes

$$G_n(x) = \mathbb{E}(g_n(x))$$
 with $g_n(x)$ r.v. $\in \mathbb{N}$

- Harmonic/(Gaussian+linearisation) approximations.
- $G.M(H) \propto H \rightsquigarrow G \propto H/M(H) \rightsquigarrow H$ -process X^H (unknown).

Mean field particle methods

Nonlinear distribution flows

• Nonlinear Markov models : always $\exists K_{n,\eta}(x, dy)$ Markov s.t.

$$\eta_n = \Phi_n(\eta_{n-1}) = \eta_{n-1} K_{n,\eta_{n-1}} = \operatorname{Law}\left(\overline{X}_n\right)$$

i.e. :

$$\mathbb{P}(\overline{X}_n \in dx_n \mid \overline{X}_{n-1}) = K_{n,\eta_{n-1}}(\overline{X}_{n-1}, dx_n)$$

Mean field particle interpretation

• Markov chain $\xi_n = (\xi_n^1, \dots, \xi_n^N) \in E_n^N$ s.t.

$$\eta_n^N := \frac{1}{N} \sum_{1 \le i \le N} \delta_{\xi_n^i} \simeq_{N \uparrow \infty} \eta_n$$

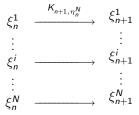
• Particle approximation transitions ($\forall 1 \leq i \leq N$)

$$\xi_{n-1}^{i} \rightsquigarrow \xi_{n}^{i} \sim K_{n,\eta_{n-1}^{N}}(\xi_{n-1}^{i}, dx_{n})$$

Mean field particle methods

Discrete generation mean field particle model

Schematic picture : $\xi_n \in E_n^N \rightsquigarrow \xi_{n+1} \in E_{n+1}^N$



Rationale :

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Mean field particle methods

Advantages

• Mean field model=Stoch. linearization/perturbation tech. :

$$\eta_n^N = \Phi_n(\eta_{n-1}^N) + \frac{1}{\sqrt{N}} W_n^N$$

with $W_n^N \simeq W_n$ independent and centered Gauss field.

• $\eta_n = \Phi_n(\eta_{n-1})$ stable \Rightarrow local errors do not propagate

 \implies uniform control of errors w.r.t. the time parameter

- "No need" to study the cv of equilibrium of MCMC models.
- Adaptive stochastic grid approximations
- Take advantage of the nonlinearity of the system to define beneficial interactions. Non intrusive methods.
- Natural and easy to implement, etc.

Mean field particle methods

"Intuitive picture" \rightsquigarrow nonlinear sg : $\eta_n = \Phi_n(\eta_{n-1}) = \Phi_{p,n}(\eta_p) = \eta_n$ Local errors

$$W_n^N := \sqrt{N} \; \left[\eta_n^N - \Phi_n \left(\eta_{n-1}^N \right) \right] \simeq W_n \; \perp \; \text{Gaussian field}$$

Local transport formulation :

~ Key decomposition formula

$$\begin{split} \eta_n^N - \eta_n &= \sum_{q=0}^n \left[\Phi_{q,n}(\eta_q^N) - \Phi_{q,n}(\Phi_q(\eta_{q-1}^N)) \right] \\ &\simeq \frac{1}{\sqrt{N}} \sum_{q=0}^n W_q^N D_{q,n} \quad \text{first order decomp. } \Phi_{p,n}(\eta) - \Phi_{p,n}(\mu) \simeq (\eta - \mu) D_{p,n} + (\eta - \mu)^{\otimes 2} \dots \\ &\Rightarrow \quad \text{Example CLT} : \quad \sqrt{N} \left[\eta_n^N - \eta_n \right] \simeq \sum_{q=0}^n W_q D_{q,n} \end{split}$$

Introduction An introduction to interacting stochastic algorithms Some rare event models An introduction to continuous time models occorrection to continuous time models and the stochastic algorithms are event models are event models. An introduction to continuous time model are event models are event models are event models are event models. An introduction to continuous time model are event models are event models are event models. An introduction to continuous time model are event models are event models are event models. An introduction to continuous time model are event models are event models are event models. An introduction to continuous time model are event models are event models. An introduction to continuous time model are event models are event models. An introduction to continuous time model are event models are event models. An introduction to continuous time model are event models are event models. An introduction to continuous time model are event models are event models. An introduction to continuous time model are event models are event models are event models are event models. An introduction to continuous time model are event models are event models

Mean field particle methods

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Some Theoretical results : TCL,PGD, PDM,...(n,N) :

• McKean particle measure

$$\frac{1}{N}\sum_{i=1}^N \delta_{(\xi_0^i,\ldots,\xi_n^i)} \simeq_N \operatorname{Law}(\overline{X}_0,\ldots,\overline{X}_n) \& \eta_n^N = \frac{1}{N}\sum_{i=1}^N \delta_{\xi_n^i} \simeq_N \eta_n$$

- Empirical Processes : $\sup_{n\geq 0} \sup_{N\geq 1} \sqrt{N} \mathbb{E}(\|\eta_n^N \eta_n\|_{\mathcal{F}_n}^p) < \infty$
- Uniform concentration inequalities :

$$\sup_{n\geq 0} \mathbb{P}(|\eta_n^N(f_n) - \eta_n(f_n)| > \epsilon) \le c \exp\left\{-(N\epsilon^2)/(2\sigma^2)\right\}$$

• Propagations of chaos : $\mathbb{P}_{n,q}^N := \operatorname{Law}(\xi_n^1, \dots, \xi_n^q)$

$$\mathbb{P}_{n,q}^{N} \simeq \eta_{n}^{\otimes q} + \frac{1}{N} \ \partial^{1} \mathbb{P}_{n,q} + \ldots + \frac{1}{N^{k}} \ \partial^{k} \mathbb{P}_{n,q} + \frac{1}{N^{k+1}} \ \partial^{k+1} \mathbb{P}_{n,q}^{N}$$

ith $\sup_{N>1} \|\partial^{k+1} \mathbb{P}_{n,q}^{N}\|_{\mathrm{ty}} < \infty \ \& \ \sup_{n>0} \|\partial^{1} \mathbb{P}_{n,q}\|_{\mathrm{ty}} \le c \ q^{2}.$

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Mean field particle methods

Ex.: Feynman-Kac distribution flows

• FK-Nonlinear Markov models :

$$\epsilon_n = \epsilon_n(\eta_n) \ge 0$$
 s.t. η_n -a.e. $\epsilon_n G_n \in [0,1]$ ($\epsilon_n = 0$ not excluded)

$$K_{n+1,\eta_n}(x, dz) = \int S_{n,\eta_n}(x, dy) M_{n+1}(y, dz)$$

$$S_{n,\eta_n}(x,dy) := \epsilon_n G_n(x) \ \delta_x(dy) + (1 - \epsilon_n G_n(x)) \ \Psi_{G_n}(\eta_n)(dy)$$

• Mean field genetic type particle model :

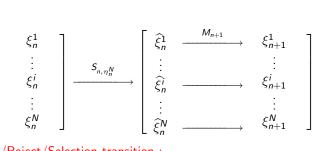
$$\xi_n^i \in E_n \xrightarrow{\text{accept/reject/selection}} \widehat{\xi_n^i} \in E_n \xrightarrow{\text{proposal/mutation}} \xi_{n+1}^i \in E_{n+1}$$

• Running ex. : $G_n = 1_A \rightsquigarrow$ killing with uniform replacement.

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Mean field particle methods

Mean field genetic type particle model :



Accept/Reject/Selection transition :

 $S_{n,\eta_n^N}(\xi_n^i,dx)$

$$:= \epsilon_n G_n(\xi_n^i) \, \delta_{\xi_n^i}(dx) + \left(1 - \epsilon_n G_n(\xi_n^i)\right) \, \sum_{j=1}^N \frac{G_n(\xi_n^j)}{\sum_{k=1}^N G_n(\xi_n^k)} \delta_{\xi_n^j}(dx)$$

Running Ex. : $G_n = 1_A \rightsquigarrow G_n(\xi_n^i) = 1_A(\xi_n^i)$

Mean field particle methods

Path space models

• $X_n = (X'_0, \dots, X'_n) \rightsquigarrow$ genealogical tree/ancestral lines

$$\eta_n^N := \frac{1}{N} \sum_{1 \le i \le N} \delta_{\xi_n^i} = \frac{1}{N} \sum_{1 \le i \le N} \delta_{(\xi_{0,n}^i, \xi_{1,n}^i, \dots, \xi_{n,n}^i)} \simeq_{N \uparrow \infty} \eta_n$$

• Unbias particle approximations :

$$\gamma_n^N(1) = \prod_{0 \le p < n} \eta_p^N(G_p) \simeq_{N \uparrow \infty} \gamma_n(1) = \prod_{0 \le p < n} \eta_p(G_p)$$

• Running ex. $G_n = 1_A$:

$$\Rightarrow \gamma_n^N(1) = \prod_{0 \le p < n} (\text{success \% at p})$$

Interacting Markov chain Monte Carlo models (i-MCMC)

Objective

• Find a series of MCMC models $X^{(n)} := (X_k^{(n)})_{k \ge 0}$ s.t.

$$\begin{split} \eta_k^{(n)} &= \frac{1}{k+1} \sum_{0 \le l \le k} \delta_{X_l^{(n)}} \\ &\simeq {}_{k\uparrow\infty} \eta_n \\ &\Rightarrow \text{ Use } \eta_k^{(n)} \simeq \eta_n \text{ to define } X^{(n+1)} \text{ with target } \eta_{n+1} \end{split}$$

Advantages

- Using η_n the sampling η_{n+1} is often easier.
- Improve the proposition step in any Metropolis type model with target η_{n+1} (→ enters the stability prop. of the flow η_n)
- Increases the precision at every time step. But CLT variance often \geq CLT variance mean field models.
- Easy to combine with mean field stochastic algorithms.

Interacting Markov chain Monte Carlo models (i-MCMC)

Interacting Markov chain Monte Carlo models

• Find M_0 and a collection of transitions $M_{n,\mu}$ s.t.

$$\eta_0 = \eta_0 M_0$$
 and $\Phi_n(\mu) = \Phi_n(\mu) M_{n,\mu}$

•
$$(X_k^{(0)})_{k\geq 0}$$
 Markov chain $\sim M_0$.

• Given $X^{(n)}$, we let $X_k^{(n+1)}$ with Markov transtions $M_{n+1,\eta_k^{(n)}}$

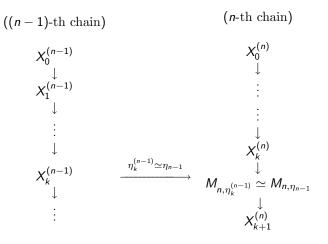
Rationale :

(0)

$$\begin{split} \eta_k^{(n)} \simeq \eta_n &\implies \Phi_{n+1}(\eta_k^{(n)}) \simeq \Phi_{n+1}(\eta_n) = \eta_{n+1} \\ &\implies M_{n+1,\eta_k^{(n)}} \simeq M_{n+1,\eta_n} & \text{fixed point } \eta_{n+1} \end{split}$$

	An introduction to interacting stochastic algorithms $000000000000000000000000000000000000$	Some rare event models	An introduction to continuous time mod
Interacting Markov chain Monte Carlo models (i-MCMC)			

i-MCMC



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Interacting Markov chain Monte Carlo models (i-MCMC)

Feynman-Kac particle sampling recipes

Nonlinear Feynman-Kac type flow $\sim (G_n, M_n)$

$$\eta_n = \Phi_n(\eta_{n-1}) = \Psi_{G_{n-1}}(\eta_{n-1})M_n$$

$$\Uparrow$$

• Interacting stochastic algorithm (mean field or i-MCMC)

acceptance/rejection/selection/branching $\rightsquigarrow G_n$ exploration/proposition/mutation/prediction $\rightsquigarrow M_n$

- Normalizing constants ~> key multiplicative formula.
- Path space models ~> path-particles=ancestral lines

Occupation meas. of genealogical trees $\simeq \eta_n \in \text{path-space}$

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Boltzmann-Gibbs distribution flows

Boltzmann-Gibbs distribution flows

Boltzmann-Gibbs measures

- X r.v. $\in (E, \mathcal{E})$ with $\mu = \text{Law}(X)$
- Target measures associated with $g_n: E \to \mathbb{R}_+$

$$\eta_n(dx) := \Psi_{g_n}(\mu)(dx) = \frac{1}{\mu(g_n)} g_n(x) \mu(dx)$$

Running examples :

$$g_n = 1_{A_n} \Rightarrow \eta_n(dx) \propto 1_{A_n}(x) \ \mu(dx)$$

$$g_n = e^{-\beta_n V} \Rightarrow \eta_n(dx) \propto e^{-\beta_n V(x)} \ \mu(dx)$$

$$g_n = \prod_{0 \le p \le n} h_p \Rightarrow \eta_n(dx) \propto \left\{ \prod_{0 \le p \le n} h_p(x) \right\} \ \mu(dx)$$

Applications : global optimization pb., tails distributions, hidden Markov chain models, etc.

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Boltzmann-Gibbs distribution flows

Boltzmann-Gibbs distribution flows

Boltzmann-Gibbs distribution flows

- Target distribution flow : $\eta_n(dx) \propto g_n(x) \mu(dx)$
- Product hypothesis :

$$g_n = g_{n-1} \times G_{n-1} \Longrightarrow \eta_n = \Psi_{G_{n-1}}(\eta_{n-1})$$

Running Ex.:

$$\begin{array}{rcl} g_n &=& 1_{A_n} \quad \text{with } A_n \downarrow &\Rightarrow & G_{n-1} = 1_{A_n} \\ g_n &=& e^{-\beta_n V} \text{ with } \beta_n \uparrow &\Rightarrow & G_{n-1} = e^{-(\beta_n - \beta_{n-1})V} \\ g_n &=& \prod_{0 \leq p \leq n} h_p &\Rightarrow & G_{n-1} = h_n \end{array}$$

• Problem : $\eta_n = \Psi_{G_{n-1}}(\eta_{n-1}) =$ unstable equation.

Boltzmann-Gibbs distribution flows

Feynman-Kac distribution flows

FK-stabilization

- Choose $M_n(x, dy)$ s.t. local fixed point eq. $\rightarrow \eta_n = \eta_n M_n$ (Metropolis, Gibbs,...)
- Stable equation :

$$g_n = g_{n-1} \times G_{n-1} \implies \eta_n = \Psi_{G_{n-1}}(\eta_{n-1})$$
$$\implies \eta_n = \eta_n M_n = \Psi_{G_{n-1}}(\eta_{n-1}) M_n$$

• Feynman-Kac "dynamical" formulation (X_n Markov M_n)

$$\int f(x) g_n(x) \mu(dx) \propto \mathbb{E}\left(f(X_n) \prod_{0 \leq p < n} G_p(X_p)\right)$$

• ~> Interacting Metropolis/Gibbs/... stochastic algorithms.

Markov processes with fixed terminal values

Objectives - Markov processes with fixed terminal values

- X_n Markov with transitions L(x, dy) on E
- $Law(X_0) = \pi$ only known up to a normalizing constant.
- For a given fixed terminal value x solve/sample inductively the following flow of measures

$$n \mapsto \operatorname{Law}_{\pi}((X_0,\ldots,X_n) \mid X_n = x)$$

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Markov processes with fixed terminal values

FK-formulation - Markov processes with fixed terminal values

• π "target type" measure+(K, L) pair Markov transitions

Metropolis potential
$$G(x_1, x_2) = \frac{\pi(dx_2)L(x_2, dx_1)}{\pi(dx_1)K(x_1, dx_2)}$$

• Theorem [Time reversal formula] :

$$\mathbb{E}_{\pi}^{L}(f_{n}(X_{n}, X_{n-1}..., X_{0})|X_{n} = x)$$

$$= \frac{\mathbb{E}_{x}^{K}(f_{n}(X_{0}, X_{1}, ..., X_{n}) \{\prod_{0 \le p < n} G(X_{p}, X_{p+1})\}}{\mathbb{E}_{x}^{K}(\{\prod_{0 \le p < n} G(X_{p}, X_{p+1})\})}$$

 $\bullet \rightsquigarrow$ time reversal genealogical tree simulation

Multi-splitting rare events excursions

Rare event excursions

•
$$(E = A \cup A^c)$$
, Y_n Markov, $C \subset A^c$ absorbing set

$$Y_0 \in A_0(\subset A) \rightsquigarrow A^c = (B \cup C)$$

• Objectives :

 $\mathbb{P}(Y \text{ hits } B \text{ before } C)$ and $\text{Law}(Y \mid Y \text{ hits } B \text{ before } C)$

Multi-splitting rare events excursions

Multi-splitting rare events

• Multi-level decomposition
$$B_0 \supset B_1 \supset \ldots \supset B_m = B$$

 $(A_0 = B_1 - B_0, B_0 \cap C = \emptyset)$

• Inter-level excursions : $T_n = \inf \{ p \ge T_{n-1} : Y_p \in B_n \cup C \}$

$$X_n = (Y_p ; T_{n-1} \leq p \leq T_n) \text{ and } G_n(X_n) = \mathbb{1}_{B_n}(Y_{T_n})$$

Feynman-Kac formulations :

$$\mathbb{P}(Y \text{ hits } B \text{ before } C) = \mathbb{E}(\prod_{1 \le p \le m} G_p(X_p))$$
$$\mathbb{E}(f(Y_0, \dots, Y_{T_m}) \ 1_{B_m}(Y_{T_m})) = \mathbb{E}(f(X_0, \dots, X_m) \ \prod_{1 \le p \le m} G_p(X_p))$$

 \rightsquigarrow genealogical tree in excursion space.

Fixed time level set entrances

Fixed time level set entrances

Fixed time level set entrances

• X_n Markov $\in E_n$, $V_n : E_n \to \mathbb{R}_+$, $a \in \mathbb{R}$

• Objectives :

 $\mathbb{P}(V_n(X_n) \ge a)$ and $Law((X_0, \ldots, X_n) \mid V_n(X_n) \ge a)$

Fixed time level set entrances

Large deviation analysis

Large deviation analysis

$$\begin{split} \mathbb{P}(V_n(X_n) \geq a) &\stackrel{\forall \lambda}{=} & \mathbb{E}\left(\mathbf{1}_{V_n(X_n) \geq a} \ e^{\lambda V_n(X_n)} \ e^{-\lambda V_n(X_n)}\right) \\ &\leq & e^{-(\lambda a - \Lambda_n(\lambda))} \text{ with } \Lambda_n(\lambda) = \log \mathbb{E}(e^{\lambda V_n(X_n)}) \\ &\text{Ex.:} \quad V_n(X_n) = X_n \quad \text{and} \quad \Delta X_n = N(0, 1) \Longrightarrow \lambda^* = a/n \end{split}$$

Twisted measure

$$\eta_n(dx_n) \propto e^{\lambda V_n(x_n)} \mathbb{P}(X_n \in dx_n) := \gamma_n(dx_n)$$

 $\Rightarrow \mathbb{P}(V_n(X_n) \ge a) = \eta_n(1_{V_n \ge a} e^{-\lambda V_n}) \times \gamma_n(1)$

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Fixed time level set entrances

Feynman-Kac representation formula

Feynman-Kac twisted measures ($V_{-1} = 0$)

$$\mathbb{E}(f_n(X_n) \ e^{\lambda V_n(X_n)}) = \mathbb{E}\left(f_n(X_n) \ \prod_{0 \le p \le n} e^{\lambda (V_p(X_p) - V_{p-1}(X_{p-1}))}\right)$$

and

$$\begin{split} & \mathbb{E}(f_n(X_0,\ldots,X_n) \mid V_n(X_n) \geq a) \\ & \propto \\ & \mathbb{E}\left(T_n(f_n)(X_0,\ldots,X_n) \prod_{0 \leq p \leq n} e^{\lambda(V_p(X_p) - V_{p-1}(X_{p-1}))}\right) \end{split}$$

with

$$T_n(f_n)(X_0,\ldots,X_n) = f_n(X_0,\ldots,X_n)e^{-\lambda V_n(X_n)} \mathbb{1}_{V_n(X_n)\geq a}$$

Particle absorption models

Particle absorption models

Sub-Markov ~> Markov

•
$$X_n$$
 Markov $\in (E_n, \mathcal{E}_n)$ with transitions M_n , and $G_n : E_n \rightarrow [0, 1]$

 $Q_n(x, dy) = G_{n-1}(x) M_n(x, dy)$ sub-Markov operator

•
$$\rightsquigarrow E_n^c = E_n \cup \{c\}.$$

$$X_n^c \in E_n^c \xrightarrow{absorption \sim G_n} \widehat{X}_n^c \xrightarrow{exploration \sim M_n} X_{n+1}^c$$

Absorption: X̂^c_n = X^c_n, with proba G(X^c_n); otherwise X̂^c_n = c.
Exploration: like X_n → X_{n+1}

Particle absorption models

Feynman-Kac formulation

Feynman-Kac integral model

•
$$T = \inf \{n : \widehat{X}_n^c = c\}$$
 absorption time : $\forall f_n \in \mathcal{B}_b(E_n)$

$$\mathbb{P}(T \ge n) = \gamma_n(1) := \mathbb{E}\left(\prod_{0 \le p < n} G(X_p)\right)$$
$$\mathbb{E}(f_n(X_n^c) ; (T \ge n)) = \gamma_n(f_n) := \mathbb{E}\left(f_n(X_n) \prod_{0 \le p < n} G_p(X_p)\right)$$

• Continuous time models : $\Delta = time step$

$$(M,G) = (Id + \Delta L, e^{-V\Delta})$$

 \rightsquigarrow *L*-motions \oplus expo. clocks rate $V \oplus$ Uniform selection.

Particle absorption models

Ex.: Feynman-Kac-Shrdinger ground states energies

Spectral radius-Lyapunov exponents

- Q(x, dy) = G(x)M(x, dy) sub-Markov operator on $\mathcal{B}_b(E)$
- Normalized FK-model : $\eta_n(f) = \gamma_n(f)/\gamma_n(1)$.

$$\mathbb{P}(T \ge n) = \mathbb{E}\left(\prod_{0 \le p \le n} G(X_p)\right) = \prod_{0 \le p \le n} \eta_p(G) \simeq e^{-\lambda n}$$

with $e^{-\lambda} \stackrel{M \text{ reg.}}{=} Q$ -top eigenvalue or

$$\lambda = -\text{LogLyap}(Q) = \lim_{n \to \infty} -\frac{1}{n} \log |||Q^n|||$$
$$= -\frac{1}{n} \log \mathbb{P}(T \ge n) = -\frac{1}{n} \sum_{0 \le p \le n} \log \eta_p(G) = -\log \eta_\infty(G)$$

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Particle absorption models

Ex.: Feynman-Kac-Shrdinger ground states energies

Limiting Feynman-Kac measures

 $M \quad \mu - \text{reversible}$:

$$\Rightarrow \mathbb{E}(f(X_n^c) \mid T > n) \simeq \frac{\mu(H \ f)}{\mu(H)} \quad \text{with} \quad Q(H) = e^{-\lambda}H$$

Limiting FK-measures

$$\eta_n = \Phi(\eta_{n-1}) \to_{n\uparrow\infty} \eta_\infty \quad \text{with} \quad \frac{\eta_\infty(G f)}{\eta_\infty(G)} = \frac{\mu(H f)}{\mu(H)}$$

leadsto Particle approximations :

$$\lambda \simeq_{n,N\uparrow} \lambda_n^N := \frac{1}{n} \sum_{0 \le p \le n} \log \eta_p^N(G) \text{ and } \eta_\infty \simeq_{n,N\uparrow} \eta_n^N$$

 $\mathrm{Law}((X_0^c,\ldots,X_n^c)\mid (\mathcal{T}\geq n))\simeq \mathrm{Genealogical\ tree\ measures}$

Distribution flows (nonlinear sg.)

• (weak sense) : infinitesimal generators $L_{t,\eta}$

$$\frac{d}{dt}\eta_t(f) = \eta_t L_{t,\eta_t}(f) := \int_E \eta_t(dx) \ L_{t,\eta_t}(f)(x)$$

• Example FKS :
$$X_t \simeq \left(L \stackrel{\text{ex.}}{=} \frac{1}{2}\Delta\right) - ext{process} \oplus ext{potential} V$$

$$\eta_t(f) := rac{\gamma_t(f)}{\gamma_t(1)} \quad ext{avec} \quad \gamma_t(f) = \mathbb{E}\left(f(X_t)\exp\left\{-\int_0^t V(X_s)ds
ight\}
ight)$$

$$\begin{aligned} \frac{d}{dt}\gamma_t(f) &= \gamma_t(L^V(f)) & \text{Schrodinger op.} \quad L^V := L - V \\ \frac{d}{dt}\eta_t(f) &= \eta_t L_{\eta_t}(f) \\ &:= \int \eta_t(dx) \left\{ L(f)(x) + V(x) \int (f(y) - f(x))\eta_t(dy) \right\} \end{aligned}$$

Mean field particle interpretation

• Markov process $\xi_t = (\xi_t^i)_{1 \le i \le N}$ with infinitesimal generator

$$\mathcal{L}_{t}(F)(x^{1},...,x^{N}) := \sum_{i=1}^{N} L_{t,\frac{1}{N}\sum_{i=1}^{N}\delta_{x^{i}}}^{(i)} F(x^{1},...,x^{i},...,x^{N})$$

• Occupation measures evolution $\eta_t^N := \frac{1}{N} \sum_{i=1}^N \delta_{\xi_t^i}$

$$d\eta_t^N(f) = \eta_t^N L_{t,\eta_t^N}(f) dt + rac{1}{\sqrt{N}} \ dM_t^N(f)$$

with

$$\langle M^N(f) \rangle_t = \int_0^t \eta_s^N \Gamma_{L_{s,\eta_s^N}}(f,f) ds$$

Example : FKS model ~ Moran type particle systems

•
$$(\xi_t^i)_{1 \le i \le N} = L$$
-explorations \oplus interacting jumps (V-intensity)

$$\mathcal{L}_t(F)(x^1,\ldots,x^N)$$

$$= \sum_{i=1}^{N} L^{(i)} F(x^{1}, \dots, x^{i}, \dots, x^{N}) + \sum_{i=1}^{N} V(x^{i})$$

$$\times \int \left(F(x^1,\ldots,y^i,\ldots,x^N) - F(x^1,\ldots,x^i,\ldots,x^N) \right) m(x) (dy^i)$$

with $m(x) = N^{-1} \sum_{i=1}^{N} \delta_{x^{i}}$.

 $\bullet\,$ Asymptotic theory " \sim " discrete time models

Geometric clocks \rightarrow Exponential clocks

Asymptotic theory

FKS-model \oplus Moran type particle systems

• Particle estimations

$$\mathbb{E}\left(f(X_t)e^{\int_0^t V(X_s)ds}\right) = \eta_t(f) \ e^{-\int_0^t \eta_s(V)ds}$$
$$\simeq_N \ \eta_t^N(f) \ e^{-\int_0^t \eta_s^N(V)ds} \ \text{(unbias)}$$

 Ground states of Schrodinger op. : (⊃ DMC, QMC) (v.p. λ ⊕ ground state h (L μ-reversible))

$$\lim_{N,t\to\infty}\eta_t^N(dx)\propto h(x)\ \mu(dx)\qquad {\rm et}\quad e^{-\int_0^t\eta_s^N(V)ds}\simeq e^{-\lambda t}$$

• Asymptotic theory "~" discrete time models.

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