

# On the convergence and the application of evolutionary type stochastic particle models

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Workshop on Evolutionary Algorithms - Challenges in Theory and Practice

## Some references :

- Particle Methods: An introduction with applications. HAL-INRIA RR-699 (2009).
- Feynman-Kac formulae. Genealogical and interacting particle approximations. Springer New York, Series: Probability and Applications (2004).
- A Backward Particle Interpretation of Feynman-Kac Formulae HAL-INRIA RR-7019 (2009).
- Concentration Inequalities for Mean Field Particle Models HAL-INRIA RR-6901(2009).
- On the Convergence and the Applications of the Generalized Simulated Annealing. SIAM Journal on Control and Optimization, Vol. 37, No. 4, 1222-1250, (1999).

# Outline

- 1 A simple genetic particle model
- 2 Some convergence estimates
- 3 Some application domains

- 1 A simple genetic particle model
  - The mutation-selection transitions
  - The 3 types of particle approximation measures
  - The limiting Feynman-Kac or Boltzmann-Gibbs measures
- 2 Some convergence estimates
- 3 Some application domains

## A simple genetic particle model $\hookrightarrow$ Only 2 ingredients

- **Mutation**= A Markov chain  $X_n$  on some state space  $E_n$  ( $n$ =time index).

$$\mathbb{P}(X_n \in dx_n \mid X_{n-1} = x_{n-1}) = M_n(x_{n-1}, dx_n)$$

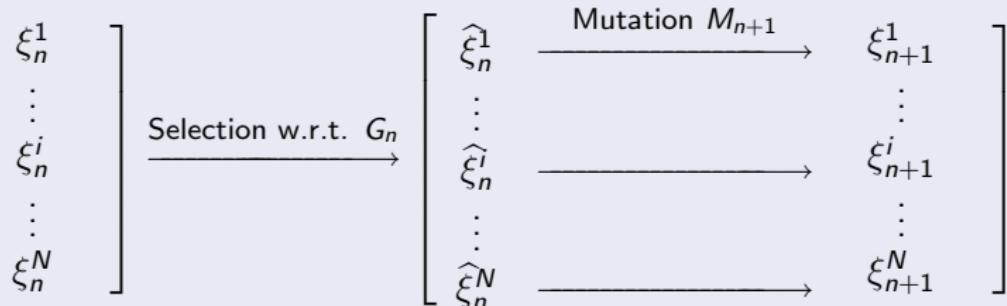
Examples:

- Simple random walk on  $\mathbb{Z}^d$ .
  - Markov chain on graphs with neighbourhood exploration strategies.
  - $X_n = F_n(X_{n-1}, W_n)$  with i.i.d. perturbations/random controls  $W_n$ .
  - Transition space  $X_n = (X'_{n-1}, X'_n)$ .
  - Path or excursion state space models  $X_n := (X'_0, X'_1, \dots, X'_n)$ .
- **Selection**=Fitness type potential functions  $G_n : x_n \in E_n \rightarrow G_n(x_n) \in [0, 1]$

Examples:

- Indicator functions  $G_n(x_n) = 1_{A_n}(x_n)$ .
- Boltzmann type exponentials  $G_n(x_n) = e^{-\beta_n V_n(x_n)}$ .
- Likelihood functions  $G_n(x_n) = p(y_n|x_n) = (2\pi)^{-1/2} e^{-\frac{1}{2}(y_n - h_n(x_n))^2}$ .
- On path space  $G_n(X'_0, X'_1, \dots, X'_n) = 1_{E_n - \{X'_0, X'_1, \dots, X'_{n-1}\}}(X'_n), \dots$

# Genetic Mutation-Selection type stochastic algorithm



Acceptance/Rejection-Selection :  $[\forall \epsilon_n \text{ that may depend on } (\xi_n^i)_{1 \leq i \leq N}]$

$$\begin{aligned} \widehat{\xi}_n^i &= \xi_n^i \quad \text{with probability } \epsilon_n G_n(\xi_n^i) \\ \widehat{\xi}_n^i &= \zeta_n^i \quad \text{with probability } 1 - \epsilon_n G_n(\xi_n^i) \end{aligned}$$

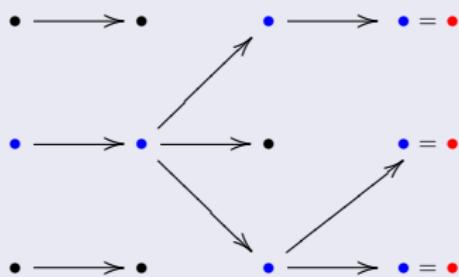
$$\zeta_n^i \text{ r.v. with law } \sum_{j=1}^N \frac{G_n(\xi_n^j)}{\sum_{k=1}^N G_n(\xi_n^k)} \delta_{\xi_n^j}(dx) \propto G_n(x) \times \frac{1}{N} \sum_{j=1}^N \delta_{\xi_n^j}(dx)$$

$\subset$  Mean field interacting particle system ( $\subset$  Nonlinear Markov chain)

Def. : Transitions  $\xi_n^i \rightsquigarrow \xi_{n+1}^i$  depending on  $\eta_n^N := \frac{1}{N} \sum_{j=1}^N \delta_{\xi_n^j} \simeq_{N \uparrow \infty} \text{Law}(\xi_n^i)$

# Interaction/branch. process $\hookrightarrow$ 3 types of occupation measures

$(N = 3)$



- **Current population**  $\hookrightarrow \eta_n^N := \frac{1}{N} \sum_{i=1}^N \delta_{\xi_n^i \leftarrow i\text{-th individual at time } n}$
- **Genealogical tree**  $\hookrightarrow \mathbb{Q}_n^N := \frac{1}{N} \sum_{i=1}^N \delta_{(\xi_{0,n}^i, \xi_{1,n}^i, \dots, \xi_{n,n}^i) \leftarrow \text{ancestral line of the } i\text{-th individual}}$
- **Ancestral tree**  $\hookrightarrow \mathbb{K}_n^N := \frac{1}{N} \sum_{i=1}^N \delta_{(\xi_0^i, \xi_1^i, \dots, \xi_n^i) \leftarrow i\text{-th ancestral line}}$
- $\oplus$  **Particle partition functions**  $\hookrightarrow \mathcal{Z}_n^N := \mathcal{Z}_{n-1}^N \times \underbrace{\left( \frac{1}{N} \sum_{i=1}^N G_n(\xi_n^i) \right)}_{\text{proportion of success}}$

## Equivalent Stochastic Algorithms :

- Genetic and evolutionary type algorithms.
- Sequential Monte Carlo methods.
- Population Monte Carlo models.
- Diffusion Monte Carlo (DMC), Quantum Monte Carlo (QMC), ...
- Some botanical names  $\sim \neq$  application domain areas :  
*particle filters, bootstrapping, selection, pruning-enrichment, reconfiguration, cloning, go with the winner, spawning, condensation, grouping, rejuvenations, harmony searches, biomimetics, splitting, ...*

$\Updownarrow$

1950  $\leq$  [(Meta)Heuristics]  $\leq$  1996  $\leq$  Feynman-Kac mean field particle model

# Limiting Feynman-Kac or Boltzmann-Gibbs measures

No choice! We have  $\mathbb{Q}_n^N \simeq_{N \uparrow \infty} \mathbb{Q}_n$  and  $\mathcal{Z}_n^N \simeq_{N \uparrow \infty} \mathcal{Z}_n$  and inversely!

$$\text{with } d\mathbb{Q}_n := \frac{1}{\mathcal{Z}_n} \left\{ \prod_{0 \leq p < n} G_p(X_p) \right\} d\mathbb{P}_n \quad \text{with } \mathbb{P}_n := \text{Law}(X_0, \dots, X_n)$$

Examples:

- Indicator functions  $G_n(x_n) = 1_{A_n}(x_n) \rightsquigarrow$  Confinement models

$$\mathbb{Q}_n = \text{Law}((X_0, \dots, X_n) \mid \forall 0 \leq p < n \ X_p \in A_p) \quad \mathcal{Z}_n = \mathbb{P}(\forall 0 \leq p < n \ X_p \in A_p)$$

- Likelihood functions  $G_n(x_n) = p(y_n|x_n) \rightsquigarrow$  Filtering models

$$\mathbb{Q}_n = \text{Law}((X_0, \dots, X_n) \mid \forall 0 \leq p < n \ Y_p = y_p)$$

- $X_n = (X'_p)_{0 \leq p \leq n}$ ,  $G_n(X_n) = 1_{E_n - \{X'_0, X'_1, \dots, X'_{n-1}\}}(X'_n) \rightsquigarrow$  Self-avoiding chains

$$\mathbb{Q}_n = \text{Law}((X'_0, X'_1, \dots, X'_n) \mid \forall 0 \leq p < q < n \ X'_p = X'_q)$$

- 1 A simple genetic particle model
- 2 Some convergence estimates
  - Non asymptotic theorems
  - Propagation of chaos estimates
- 3 Some application domains

## "Asympt." theo. TCL,PGD, PDM $\oplus$ (n,N) fixed $\rightsquigarrow$ some examples :

- Empirical processes (example  $E_n = \mathbb{R}^d$  &  $f_n \in \mathcal{F}_n = \{1_{[0,x]} , x \in \mathbb{R}^d\}$ )

$$\eta_n^N(f_n) := \frac{1}{N} \sum_{i=1}^N f_n(\xi_n^i) \simeq_{N \uparrow \infty} \int f_n(x_n) \eta_n(dx_n) := \eta_n(f_n)$$

$$\sup_{n \geq 0} \sup_{N \geq 1} \sqrt{N} \mathbb{E} \left( \sup_{f_n \in \mathcal{F}_n} |\eta_n^N(f_n) - \eta_n(f_n)|^p \right)^{1/p} \leq a(p) b$$

- Concentration inequalities uniform w.r.t. time :

$$\sup_{n \geq 0} \mathbb{P}(|\eta_n^N(f_n) - \eta_n(f_n)| > \epsilon) \leq a \exp(-(N\epsilon^2/b))$$

+ Guionnet  $\sup_{n \geq 0}$  (IHP 01) & Ledoux  $\sup_{\mathcal{F}_n}$  (JTP 00) & Rio hal-09

- Same results for  $\mathbb{Q}_n^N$  and  $\mathbb{Q}_n$  BUT not uniform w.r.t. the time  $n$  and the constant  $b$  is now replaced by  $b(n) = b \times n$ .

"Asympt." theo. TCL,PGD, PDM  $\oplus$  (n,N) fixed  $\rightsquigarrow$  some examples :

- Propagations of chaos exansions (+Patras,Rubenthaler (AAP 09-10) ) :

$$\begin{aligned}\mathbb{P}_{n,q}^N &:= \text{Law}(\xi_n^1, \dots, \xi_n^q) \\ &\simeq \eta_n^{\otimes q} + \frac{1}{N} \partial^1 \mathbb{P}_{n,q} + \dots + \frac{1}{N^k} \partial^k \mathbb{P}_{n,q} + \frac{1}{N^{k+1}} \partial^{k+1} \mathbb{P}_{n,q}^N\end{aligned}$$

with  $\sup_{N \geq 1} \|\partial^{k+1} \mathbb{P}_{n,q}^N\|_{\text{tv}} < \infty$  &  $\sup_{n \geq 0} \|\partial^1 \mathbb{P}_{n,q}\|_{\text{tv}} \leq c q^2$

- Normalizing Cts (+Cerou & Guyader Hal-INRIA 08 & IPH 2010) :

$$\mathbb{E}(\mathcal{Z}_n^N) = \mathcal{Z}_n \quad \text{and} \quad \mathbb{E} \left( [1 - \mathcal{Z}_n^N / \mathcal{Z}_n]^2 \right) \leq c n/N$$

Note : Traditional Monte Carlo methods

$$\mathbb{E} \left( [1 - \mathcal{Z}_n^N / \mathcal{Z}_n]^2 \right) = \frac{1}{N} \frac{1 - \mathcal{Z}_n}{\mathcal{Z}_n} \rightsquigarrow \text{Pb if } \mathcal{Z}_n \simeq 10^{-n}$$

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- Confinement, optimization, combinatorial pb, rare events.
- Filtering  $\Leftarrow$  Regulation
- Parameter estimation HMM
- Additive functionals

## Confinement, optimization, combinatorial pb, rare events.

- ①  $\eta_n = \text{Loi}((X_0, \dots, X_n) \mid \forall 0 \leq p \leq n \quad X_p \in A_p)$
- ②  $\eta_n(dx) \propto e^{-\beta_n V(x)} \lambda(dx)$  with  $\beta_n \uparrow$
- ③  $\eta_n(dx) \propto 1_{A_n}(x) \lambda(dx)$  with  $A_n \downarrow$
- ④  $\eta_n = \text{Loi}_\pi((X_0, \dots, X_n) \mid X_n = x_n).$
- ⑤  $\eta_n = \text{Loi}(X \text{ hits } B_n \mid X \text{ hits } B_n \text{ before } A)$

## Stochastic particle algorithms

- ①  $X_n$ -local moves  $\oplus$  individual selections  $\in A_n$  i.e.  $\sim G_n = 1_{A_n}$
- ②  $\eta_n$ -MCMC local moves (i.e.  $\eta_n$ -shakers)  $\oplus$  selections  $G_n = e^{-(\beta_{n+1} - \beta_n)V}$
- ③  $\eta_n$ -MCMC local moves (i.e.  $\eta_n$ -shakers)  $\oplus$  selections w.r.t.  $G_n = 1_{A_{n+1}}$
- ④  $X_n$ -local moves  $\oplus$  Selection w.r.t.  $G(x_1, x_2) = \frac{\pi(dx_2)M(x_2, dx_1)}{\pi(dx_1)M(x_1, dx_2)}$
- ⑤  $X_n$ -local moves  $\oplus$  Selection-branching on upper/lower levels  $B_n$ .

## Filtering (max likelihood path) $\Leftarrow$ Regulation

Signal-Observation  $(X, Y) \rightsquigarrow$  reference path  $Y = y$

$$X_n = F_n(X_{n-1}, W_n) \quad \text{and} \quad Y_n = H_n(X_n) + V_n$$

If  $W_n, V_n$  centered Gaussian r.v.

$$\begin{aligned} \mathbb{Q}_n &:= \text{Law}((W_0, \dots, W_n) \mid (Y_0, \dots, Y_n) = (y_0, \dots, y_n)) \\ &\propto \exp\left(-\frac{1}{2} \sum_{p=0}^n \|W_p\|^2 - \frac{1}{2} \sum_{p=0}^n \|y_p - H_p(X_p)\|^2\right) \end{aligned}$$

Genealogical tree associated with  $(W_0, \dots, W_n)$  = **Control Tree Chart (open loop)**

$$\mathbb{Q}_n^N := \frac{1}{N} \sum_{i=1}^N \delta_{(W_{0,n}^i, W_{1,n}^i, \dots, W_{n,n}^i)}$$

# Parameter estimation HMM

- Boltzmann-Gibbs measures

$$\eta_n(d\theta) \propto G_n(\theta) p(d\theta) \quad \text{with} \quad G_n(\theta) = G_{n-1}(\theta) \times g_n(\theta)$$

$\implies \eta_n$ -MCMC mutations (shakers)  $\oplus$  Selections w.r.t.  $g_n$

- Example:  $\Theta$  r.v. with law  $p(d\theta)$  & Linear-Gaussian HMM model

$$X_n = A_n(\Theta)X_{n-1} + B_n(\Theta)W_n \quad \text{and} \quad Y_n = C_n(\Theta)X_n + D_n(\Theta)V_n$$

Given the data  $Y = y$ , if we set  $g_n(\theta) = p(y_n|\theta, y_0, \dots, y_{n-1})$ , then we have

$$G_n(\theta) = p(y_0, \dots, y_n|\theta) \quad \text{and} \quad \eta_n = \text{Law}(\Theta|y_0, \dots, y_n)$$

- Nonlinear HMM :  $G_n(\theta) = p(y_0, \dots, y_n|\theta) = \mathcal{Z}_n(\theta)$  normalizing Cts of

$$\mathbb{Q}_n^\theta := \text{Law}((X_0, \dots, X_n) \mid \theta, (y_0, \dots, y_n))$$

$\rightsquigarrow$  3 Solutions:

As above with  $\mathcal{Z}_n^N(\theta)$  or Particle MCMC models (Andrieu, Doucet, Holenstein, JRSS B (2010)) or Gradient algo. w.r.t. additive functionals.

# Additive functionals (with Doucet & Singh Hal-INRIA 09, to appear in M2AN (2010))

- Hypothesis :

$$\begin{aligned}\mathbb{P}(X_n \in dx_n | X_{n-1} = x_{n-1}) &= H_n(x_{n-1}, x_n) \lambda_n(dx_n) \\ &\stackrel{\text{ex.}}{=} \frac{1}{\sqrt{2\pi}} e^{-\frac{1}{2}(x_n - F_n(x_{n-1}))^2} dx_n\end{aligned}$$

$$\Rightarrow \mathbb{Q}_n(d(x_0, \dots, x_n)) = \eta_n(dx_n) M_{n, \eta_{n-1}}(x_n, dx_{n-1}) \dots M_{1, \eta_0}(x_1, dx_0)$$

with the backward transitions :

$$M_{p+1, \eta}(x, dx') \propto G_p(x') H_{p+1}(x', x) \eta(dx')$$

- Particle estimates  $\sim$  complete genealogical tree :

$$\mathbb{Q}_n^N(d(x_0, \dots, x_n)) = \eta_n^N(dx_n) M_{n, \eta_{n-1}^N}(x_n, dx_{n-1}) \dots M_{1, \eta_0^N}(x_1, dx_0)$$

## Some non asymptotic estimates

Test functions: Additive functionals  $F_n(x_0, \dots, x_n) := \frac{1}{n+1} \sum_{0 \leq p \leq n} f_p(x_p)$

- Bias estimate + uniform  $\mathbb{L}_p$ -bounds + variance

$$N \mathbb{E} \left( [(\mathbb{Q}_n^N - \mathbb{Q}_n)(F_n)]^2 \right) \leq c \times (1/n + 1/N)$$

- Uniform exponential concentration

$$\frac{1}{N} \log \sup_{n \geq 0} \mathbb{P} \left( |[\mathbb{Q}_n^N - \mathbb{Q}_n](F_n)| \geq \frac{b}{\sqrt{N}} + \epsilon \right) \leq -\epsilon^2/(2b^2)$$

- Illustration  $(G_n, \mathbb{Q}_n, \mathcal{Z}_n) \rightsquigarrow (G_n^\theta, \mathbb{Q}_n^\theta, \mathcal{Z}_n^\theta)$  with some varying  $\theta$

$$\frac{1}{n+1} \frac{\partial}{\partial \theta} \log \mathcal{Z}_{n+1}^\theta = \mathbb{Q}_{n+1}^\theta(F_n^\theta) \quad \text{with} \quad f_p^\theta = \frac{\partial \log G_p^\theta}{\partial \theta}$$