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Feynman-Kac particle models Coalescent tree based functional representations

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 \hookrightarrow Coalescent tree based functional representations for some Feynman-Kac particle models

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Introduction

- Evolutionary models and Feynman-Kac formulae
- Genetic genealogical models and Feynman-Kac limiting measures
- Functional representations \simeq precise propagations of chaos expansions.
 - Combinatorial differential calculus
 - Permutation group analysis of (colored) forests
 (wreath product of permutation groups, Hilbert series techniques,...)
- (Applications).

Discrete time models \rightsquigarrow Continuous time version = Moran type genetic models

(~ joint works with L. Miclo, see also [PhD \oplus articles] M. Rousset)

Evolutionary type models

Simple Genetic Branching Algo.	Mutation	Selection/Branching
Metropolis-Hastings Algo.	Proposal	Acceptance/Rejection
Sequential Monte Carlo methods	Sampling	Resampling (SIR)
Filtering/Smoothing	Prediction	Updating/Correction
Particle \in Absorbing Medium	Evolution	Killing/Creation/Anhiling

<u>Other Botanical Names</u>: multi-level splitting (Khan-Harris 51), prune enrichment (Rosenbluth 1955), switching algo. (Magill 65), matrix reconfiguration (Hetherington 84), restart (Villen-Altamirano 91), particle filters (Rigal-Salut-DM 92), SIR filters (Gordon-Salmon-Smith 93, Kitagawa 96), go-with-the-winner (Vazirani-Aldous 94), ensemble Kalman-filters (Evensen 1994), quantum Monte Carlo methods (Melik-Nightingale 1999), sequential Monte Carlo Methods (Arnaud Doucet 2001), spawning filters (Fisher-Maybeck 2002), SIR Pilot Exploration Resampling (Liu-Zhang 2002),...

\iff Particle Interpretations of Feynman-Kac models

Since R. Feynman's phD. on path integrals 1942

 $\mathsf{Physics} \longleftrightarrow \mathsf{Biology} \longleftrightarrow \mathsf{Engineering} \ \mathsf{Sciences} \longleftrightarrow \mathsf{Probability}/\mathsf{Statistics}$

- Physics :
 - $FKS \in$ nonlinear integro-diff. éq. (~ generalized Boltzmann models).
 - Spectral analysis of Schrödinger operators and large matrices with nonnegative entries. (particle evolutions in disordered/absorbing media)
 - Multiplicative Dirichlet problems with boundary conditions.
 - Microscopic and macroscopic interacting particle interpretations.
- Biology:
 - Self-avoiding walks, macromolecular polymerizations.
 - Branching and genetic population models.
 - Coalescent and Genealogical evolutions.

- Rare events analysis:
 - Multisplitting and branching particle models (Restart).
 - Importance sampling and twisted probability measures.
 - Genealogical tree based simulation methods.
- Advanced Signal processing:
 - Optimal filtering/smoothing/regulation, open loop optimal control.
 - Interacting Kalman-Bucy filters.
 - Stochastic and adaptative grid approximation-models

• Statistics/Probability:

- Restricted Markov chains (w.r.t terminal values, visiting regions,...)
- Analysis of Boltzmann-Gibbs type distributions (simulation, partition functions,...).
- Random search evolutionary algorithms, interacting Metropolis/simulated annealing algo.

Simple Genetic evolution/simulation models — only 2 ingredients!!

(Discrete time parameter $n \in \mathbb{N} = \{0, 1, 2, ...\}$, state spaces E_n ($\in \{\mathbb{Z}^d, \mathbb{R}^d, \underbrace{\mathbb{R}^d \times \ldots \times \mathbb{R}^d}_{(n+1)-times}$, ...})

• *Mutation/exploration/prediction/proposal* :

 \rightarrow Markov transitions $M_n(x_{n-1}, dx_n)$ from E_{n-1} into E_n .

• Selection/absorption/updating/acceptance :

 \rightarrow Potential functions G_n from E_n into [0,1].

A Genetic Evolution Model \Rightarrow Markov chain $\xi_n = (\xi_n^1, \dots, \xi_n^N) \in E_n^N = \underbrace{E_n \times \dots \times E_n}_{N-times}$

$$\xi_n \in E_n^N \xrightarrow{\text{selection}} \widehat{\xi_n} \in E_n^N \xrightarrow{\text{mutation}} \xi_{n+1} \in E_{n+1}^N$$

• Selection transition ($\exists \neq types \rightarrow Ex.: accept/reject$)

 $\xi_n^i \rightsquigarrow \widehat{\xi}_n^i = \xi_n^i$ with proba. $G_n(\xi_n^i)$ [Acceptance]

Otherwise we select a better fitted individual in the current configuration

$$\widehat{\xi}_n^i = \xi_n^j$$
 with proba. $G_n(\xi_n^j) / \sum_{k=1}^N G_n(\xi_n^k)$ [Rejection + Selection]

• Mutation transition

$$\widehat{\xi}_n^i \rightsquigarrow \xi_{n+1}^i \sim M_{n+1}(\widehat{\xi}_n^i, \bullet)$$

A Genealogical tree model

Important observation [Historical process]

$$X'_n\in E'_n$$
 Markov chain $onumber \ X_n=(X'_0,\ldots,X'_n)\in E_n=(E'_0 imes\ldots imes E'_n)$ Markov chain \in path spaces

 \rightarrow Markov transitions $M_n(x_{n-1}, dx_n)$ [elementary extensions]

$$X_{n+1} = ((X'_0, \dots, X'_n), X'_{n+1}) = (X_n, X'_{n+1})$$

Genetic Evolution Model on Path Spaces=Genealogical tree model

$$X_n = (X'_0, \dots, X'_n)$$
 Markov transitions M_n and $G_n(X_n) = G'_n(X'_n)$
 \downarrow

Genetic path-valued particle Model

$$\begin{cases} \xi_n^i = (\xi_{0,n}^i, \xi_{1,n}^i, \dots, \xi_{n,n}^i) \\ \widehat{\xi}_n^i = (\widehat{\xi}_{0,n}^i, \widehat{\xi}_{1,n}^i, \dots, \widehat{\xi}_{n,n}^i) \in E_n = (E'_0 \times \dots \times E'_n) \end{cases}$$

- Path acceptance/(rejection+selection).
- Path mutation = path elementary extensions.

Occupation/Empirical measures ($\forall f_n$ test function on E_n)

$$\eta_n^N(f_n) = \frac{1}{N} \sum_{i=1}^N f_n(\xi_n^i) = \frac{1}{N} \sum_{i=1}^N f_n \underbrace{(\xi_{0,n}^i, \xi_{1,n}^i, \dots, \xi_{n,n}^i)}_{i-\text{th ancestral lines}}$$

 \downarrow Unbias-particle measures & Unnormalized Feynman-Kac measures :

$$\gamma_n^N(f_n) = \eta_n^N(f_n) \times \prod_{0 \le p < n} \eta_p^N(G_p) \longrightarrow_{N \to \infty} \gamma_n(f_n) = \mathbb{E}(f_n(X_n) \prod_{0 \le p < n} G_p(X_p))$$

Notes:

•
$$f_n = 1 \Rightarrow \gamma_n^N(1) = \prod_{0 \le p < n} \eta_p^N(G_p) \longrightarrow_{N \to \infty} \gamma_n(1) = \mathbb{E}(\prod_{0 \le p < n} G_p(X_p))$$

• Path-space models

$$[X_n = (X'_0, \dots, X'_n) \text{ and } G_n(X_n) = G'_n(X'_n)] \Rightarrow \gamma_n(f_n) = \mathbb{E}(f_n(X'_0, \dots, X'_n) \prod_{0 \le p < n} G'_p(X'_p))$$

 \implies Occupation measure & Normalized Feynman-Kac measures:

$$\eta_n^N(f_n) \hspace{0.1 in} = \hspace{0.1 in} rac{1}{N} \sum_{i=1}^N f_n(\xi_n^i) = \gamma_n^N(f_n)/\gamma_n^N(1) \longrightarrow_{N o \infty} \eta_n(f_n) = \gamma_n(f_n)/\gamma_n(1)$$

Path-space models

$$[X_n = (X'_0, \dots, X'_n) \text{ and } G_n(X_n) = G'_n(X'_n)]$$

$$\downarrow$$

$$\eta_n(f_n) = \frac{\mathbb{E}(f_n(X'_0, \dots, X'_n) \prod_{0 \le p < n} G'_p(X'_p))}{\mathbb{E}(\prod_{0 \le p < n} G'_p(X'_p))}$$

Note:

$$\gamma_n(f_n) = \eta_n(f_n) \times \prod_{0 \le p < n} \eta_p(G_p) \quad (\longleftarrow \gamma_n^N(f_n) = \eta_n^N(f_n) \times \prod_{0 \le p < n} \eta_p^N(G_p))$$

Motivating example \rightarrow filtering/hidden Markov chains/Bayesian Stat.Signal process $X_n =$ Markov chain $\in E_n$ Observation/Sensor eq. $Y_n = H_n(X_n, V_n) \in F_n$ with $\mathbb{P}(H_n(x_n, V_n) \in dy_n) = g_n(x_n, y_n) \lambda_n(dy_n)$

Example: $Y_n = h_n(X_n) + V_n \in F_n = \mathbb{R}$, with Gaussian noise $V_n = \mathcal{N}(0, 1)$

$$\mathbb{P}(h_n(x_n) + V_n \in dy_n) = (2\pi)^{-1/2} e^{-\frac{1}{2}(y_n - h_n(x_n))^2} \quad dy_n = \underbrace{\exp\left[h_n(x_n)y_n - h_n^2(x_n)/2\right]}_{g_n(x_n, y_n)} \quad \underbrace{\mathcal{N}(0, 1)(dy_n)}_{\lambda_n(dy_n)}$$

₩

Prediction/filtering/smoothing \rightarrow **Feynman-Kac representation** $G_n(x_n) = g_n(x_n, y_n)$

$$\eta_n = \text{Law}(X_n \mid Y_0 = y_0, \dots, Y_{n-1} = y_{n-1}) = \text{Law}(X'_0, \dots, X'_n \mid Y_0 = y_0, \dots, Y_{n-1} = y_{n-1})$$

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Rather complete asymptotic theory $(n, N) \rightarrow \infty$ (usual LLN, CLT, LDP,...) \hookrightarrow *F-K Formulae, Genealogical and IPS, Springer (2004)*+<u>References therein</u> Some examples:

• Weak convergence $[p \ge 1 + \mathcal{F}_n \text{ not too large } + \text{ regular mutations}]$ (JTP 2000, joint work with M. Ledoux)

$$\sup_{n \ge 0} \mathbb{E}(\sup_{f_n \in \mathcal{F}_n} |\eta_n^N(f_n) - \eta_n(f_n)|^p)^{1/p} \le c(p)/\sqrt{N}$$

Ex : $E_n = \mathbb{R}, \quad \mathcal{F}_n = \{1_{]-\infty,x]} ; \ x \in \mathbb{R}\} \Rightarrow \sup_{n \ge 0} \mathbb{E}(\sup_{x \in \mathbb{R}} |\eta_n^N(1_{]-\infty,x]}) - \eta_n(1_{]-\infty,x]})|^p)^{1/p} \le c(p)/\sqrt{N}$

• Propagation-of-chaos estimates $[q \le N \text{ finite block size}]$ (TVP+SIAM PTA 2006, joint work with A. Doucet)

$$\mathbb{P}^N_{n,q} := \mathsf{Law}(\xi^1_n, \dots, \xi^q_n) \simeq \eta^{\otimes q}_n + \frac{1}{N} \ \partial^1 \mathbb{P}_{n,q} \quad \text{with} \quad \partial^1 \mathbb{P}_{n,q} \quad \text{signed meas. s.t. } \sup_{n \ge 0} \|\partial^1 \mathbb{P}_{n,q}\|_{\mathsf{tv}} \le c \ q^2$$

Problem :

$$\begin{split} \mathbf{Pb}: \text{Find a functional representation at any order?} \\ \mathbb{P}_{n,q}^{N} \simeq \eta_{n}^{\otimes q} + \frac{1}{N} \; \partial^{1} \mathbb{P}_{n,q} + \ldots + \frac{1}{N^{k}} \; \partial^{k} \mathbb{P}_{n,q} + \frac{1}{N^{k+1}} \; \partial^{k} \mathbb{P}_{n,q}^{N} \\ \text{with a bounded remainder measure } \sup_{N \geq 1} \|\partial^{k+1} \mathbb{P}_{n,q}^{N}\|_{\mathsf{tv}} < \infty \end{split}$$

Consequences :

- Sharp + strong propagations of chaos estimates at any order.
- Wick product formulae on forests.
- Sharp \mathbb{L}_p -mean error bounds.
- Law of large numbers for *U*-statistics for interacting processes.

• . . .

Tensor product measures

$$\rightsquigarrow \quad (\eta_n^N)^{\otimes q} = \frac{1}{N^q} \sum_{a \in [N]^{[q]}} \delta_{\xi_n^a} \quad \text{and} \quad (\eta_n^N)^{\odot q} = \frac{1}{(N)_q} \sum_{a \in \langle q, N \rangle} \delta_{\xi_n^a}$$

with

$$\begin{cases} \xi_n^a &:= (\xi_n^{a(1)}, \dots, \xi_n^{a(q)}) \\ [N]^{[q]} &:= N^q \text{ mappings } [q] := \{1, \dots, q\} \rightsquigarrow [N] := \{1, \dots, N\}; \\ \langle q, N \rangle &:= (N)_q := N!/(N-q)! \text{ one-to-one mappings} \end{cases}$$

Note:
$$\mathbb{E}((\eta_n^N)^{\odot q}(F)) = \mathbb{P}_{n,q}^N(F)$$
 and $(\eta_n^N)^{\otimes q} = (\eta_n^N)^{\odot q} \left(\frac{1}{N^q} \sum_{b \in [q]^{[q]}} \frac{(N)_{|b|}}{(q)_{|b|}} D_b \right)$

with |b| = Card(b([q])) and the coalescent-selection transitions

$$D_b(F)(x^1, \dots, x^q) := F(x^{b(1)}, \dots, x^{b(q)}) = F(x^b)$$

$$\Downarrow$$

$$\delta_{x^a} D_b(F) = D_a D_b(F)(x^a) = D_{ab}(F)(x) \iff D_a D_b = D_{ab}$$

Proof:

• $\forall c \in [N]^{[q]}$ $\exists (N - |c|)_{q-|c|} \times (q)_{|c|} \neq \text{ways to write } c = ab \in \langle q, N \rangle \circ [q]^{[q]}$

•
$$a \in \langle q, N \rangle \Longrightarrow |b| = |c| \text{ and } \frac{(N)_{|c|}}{(q)_{|c|}} \times \frac{(N-|c|)_{q-|c|} \times (q)_{|c|}}{(N)_q} = 1$$

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Unnormalized (tensor product) measures

$$\gamma_n^N(f) := \gamma_n^N(1) \times \eta_n^N(f) \quad \text{with} \quad \gamma_n^N(1) = \prod_{0 \le p < n} \eta_p^N(G_p) \Longrightarrow \eta_n^N(f) = \gamma_n^N(f) / \gamma_n^N(1)$$

 $\gamma_n^N \sim Martingale end point :$ $\mathbb{E}(\gamma_n^N(f)) = \gamma_n(f)$ but $\mathbb{E}(\eta_n^N(f)) = \mathbb{P}_{n,1}^N(f) \neq \eta_n(f) \Rightarrow$ bias

Proof:

$$\mathbb{E}(\gamma_n^N(f) \mid \xi_{n-1}) = \gamma_{n-1}^N Q_n(f) \quad \text{and} \quad \eta_n^N(f) - \eta_n(f) = \underbrace{\frac{\gamma_n^N(1)}{\gamma_n(1)}}_{\neq 1} \times \gamma_n^N \left(\frac{1}{\gamma_n(1)}(f - \eta_n(f))\right)$$

with the positive FKS operator $Q_n(x, dy) = G_{n-1}(x)M_n(x, dy) \quad (\rightarrow \gamma_n = \gamma_{n-1}Q_n)$

Unnormalized tensor product measures

$$\rightsquigarrow$$
 $(\gamma_n^N)^{\otimes q} := \gamma_n^N(1)^q \times (\eta_n^N)^{\otimes q}$ and $(\gamma_n^N)^{\odot q} := \gamma_n^N(1)^q \times (\eta_n^N)^{\odot q}$

Lemma

$$\mathbb{Q}_{n,q}^{N}(F) := \mathbb{E}((\gamma_{n}^{N})^{\otimes q}(F)) \\
= \frac{1}{N^{q}} \sum_{a \in [q]^{[q]}} \frac{(N)_{|a|}}{(q)_{|a|}} \mathbb{Q}_{n-1,q}^{N}(Q_{n}^{\otimes q}D_{a}F) = \dots = \frac{1}{N^{q(n+1)}} \sum_{\mathbf{a} \in \mathcal{A}_{n,q}} \frac{(\mathbf{N})_{|\mathbf{a}|}}{(\mathbf{q})_{|\mathbf{a}|}} \Delta_{n,q}^{\mathbf{a}}(F)$$

with the measure-valued functional

$$\Delta_{n,q} : \mathbf{a} = (a_0, \dots, a_n) \in \mathcal{A}_{n,q} \mapsto \Delta_{n,q}^{\mathbf{a}} = \left(\eta_0^{\otimes q} D_{a_0} Q_1^{\otimes q} D_{a_1} \dots Q_n^{\otimes q} D_{a_n}\right) \in \mathcal{M}(E_n^q)$$

Traditional multi-index notation :

$$|\mathbf{a}| = (|a_0|, \dots, |a_n|)$$
 and $(\mathbf{N})_{|\mathbf{a}|} = (N)_{|a_0|} \dots (N)_{|a_n|}$ and $|\mathbf{a}|! = |a_0|! \dots |a_n|!$ and so on.



$$\mathbf{a} = (a_0, a_1) \Rightarrow \Delta_{n,q}^{\mathbf{a}}(F) = \int \eta_0(dx^1)\eta_0(dx^2)\eta_0(dx^3)$$
$$Q_1(x^1, dy^1)Q_1(x^1, dy^2)Q_1(x^3, dy^3)$$

 $Q_2(y^1, dz^2)Q_2(y^1, dz^3)Q_2(y^2, dz^1)F(z^1, z^2, z^3)$

Stirling Formula

$$(N)_p = \sum_{l \le p} s(p, l) N^l \Longrightarrow \forall \mathbf{p} = (p_0, \dots, p_{n+1}) \quad (\mathbf{N})_{\mathbf{p}} = \sum_{l \le \mathbf{p}} s(\mathbf{p}, l) N^{|\mathbf{l}|}$$

Consequence :

(with
$$|\mathbf{p}| =: \sum_{0 \le k \le n} p_k$$
 and $\mathbf{q} = (q)_{0 \le k \le n}$)

$$\mathbb{Q}_{n,q}^N(F) = \sum_{\mathbf{r} < \mathbf{q}} \sum_{\mathbf{q} - \mathbf{r} \leq \mathbf{p} \leq \mathbf{q}} s(\mathbf{p}, \mathbf{q} - \mathbf{r}) \; rac{1}{N^{|\mathbf{r}|}} rac{1}{(\mathbf{q})_\mathbf{p}} \; \sum_{\mathbf{a} \in \mathcal{A}_{n,q}: |\mathbf{a}| = \mathbf{p}} \Delta_{n,q}^\mathbf{a}(F)$$

Def :

 $\mathcal{A}_{n,q}(\mathbf{r}) := \{\mathbf{a} \in \mathcal{A}_{n,q} : |\mathbf{a}| \ge \mathbf{q} - \mathbf{r}\}$ (less than \mathbf{r} coalescences) \Downarrow

Th: $\mathbb{Q}_{n,q}^{N} = \gamma_{n}^{\otimes q} + \sum_{1 \leq k \leq (q-1)(n+1)} \frac{1}{N^{k}} \partial^{k} \mathbb{Q}_{n,q}$ with the measure valued partial derivatives $\partial^{k} \mathbb{Q}_{n,q} = \sum_{\mathbf{r} < \mathbf{q} : |\mathbf{r}| = \mathbf{k}} \sum_{\mathbf{a} \in \mathcal{A}_{n,q}(\mathbf{r})} s(|\mathbf{a}|, \mathbf{q} - \mathbf{r}) \frac{1}{(\mathbf{q})_{|\mathbf{a}|}} \Delta_{n,q}^{\mathbf{a}}$



with $\#(\mathbf{f}) :=$ nb of elts in the equivalence class ($\mathcal{A}_{n,q} \simeq$ entangled graphs:=jungles)



Figure 1: The entangled graph representation of a jungle with the same underlying graph as the planar forest in Fig. 2.



Figure 2: a graphical representation of a planar forest $f = t_1 t_3 t_2 t_3 t_3 t_1$ in terms of planar trees (corresponding forest $t_1^2 t_2 t_3^3$ =normal form).

Definitions :

 $B(\mathbf{t}) =$ the forest deduced from cutting the root of tree \mathbf{t} $B^{-1}(\mathbf{f}) =$ the tree deduced from the forest \mathbf{f} by adding a root.

Symmetry multisets :

$$\mathbf{t} = B^{-1}(\mathbf{t}_1^{m_1} \dots \mathbf{t}_k^{m_k}) \Rightarrow \mathbf{S}(\mathbf{t}) \quad := \quad (m_1, \dots, m_k)$$
$$\mathbf{S}(\mathbf{t}_1^{m_1} \dots \mathbf{t}_k^{m_k}) \quad := \quad \left(\underbrace{\mathbf{S}(\mathbf{t}_1), \dots, \mathbf{S}(\mathbf{t}_1)}_{m_1 - \text{terms}}, \dots, \underbrace{\mathbf{S}(\mathbf{t}_k), \dots, \mathbf{S}(\mathbf{t}_k)}_{m_k - \text{terms}}\right)$$

 \Downarrow (class formula + recursive multiplication principles)

Th. [closed formula]: $\forall \mathbf{f} \in \mathcal{F}_{q,n} \qquad \#(\mathbf{f}) = (q!)^{n+2} / \prod_{i=-1}^{n} \mathbf{S}(B^{i}(\mathbf{f}))!$ $\oplus \text{ (Hilbert series tech.} \iff \# \text{ forests with a given type)}$

Definitions :

$$\begin{array}{rcl} \mathcal{B}_0^{sym}(E_n^q) &=& F \text{ on } E_n^q \text{ such that } \int F(x_1,\ldots,x_{q-1},x_q) \ \gamma_n(dx_q) = 0. \\ \mathbf{t}_k &=& \text{the tree with a single coal. at level } k \text{ (its two leaves at level } (n+1)) \\ \mathbf{u}_k &=& \text{the trivial tree of height } k. \end{array}$$

 \Downarrow

$$\begin{aligned} \text{Cor.: } \forall q \text{ even} &\leq N, \ F \in \mathcal{B}_0^{sym}(E_n^q) \\ \forall k < q/2 \quad \partial^k \mathbb{Q}_{n,q}(F) = 0, \quad \partial^{q/2} \mathbb{Q}_{n,q}(F) = \sum_{\mathbf{r} < \mathbf{q}, |\mathbf{r}| = \frac{q}{2}} \ \frac{q!}{2^{q/2} \mathbf{r}!} \ \Delta_{n,q}^{\mathbf{f_r}} F \\ \text{with} \\ \mathbf{r} &= (r_k)_{0 \leq k \leq n} < \mathbf{q} = (q)_{0 \leq k \leq n} \rightsquigarrow \mathbf{f_r} := \mathbf{t}_0^{r_0} \mathbf{u}_0^{r_0} \dots \mathbf{t}_n^{r_n} \mathbf{u}_n^{r_n} \end{aligned}$$

 $(\forall q \text{ odd} \leq N, \text{ the partial derivatives are the null measure on } \mathcal{B}_0^{sym}(E_n^q), \text{ up to any order } k \leq \lfloor q/2 \rfloor) \oplus (\exists \text{ Gaussian field interpretation})$

Extension $\mathbb{Q}_{n,q}^N \rightsquigarrow \mathbb{P}_{n,q}^N$:

Same type of results + a remainder unif. bounded measure

$\longrightarrow \sim$ techniques \oplus 3 main ingredients

- $\mathbb{E}((\gamma_n^N)^{\otimes q}(F)) \rightsquigarrow \mathbb{E}([(\gamma_0^N)^{\otimes q_0} \otimes \ldots \otimes (\gamma_n^N)^{\otimes q_n}](F))$
- Forests \rightsquigarrow colored forests
- $\gamma_n^N \rightsquigarrow \eta_n^N \Longrightarrow$ renormalisation techniques.

Applications :

- Particle physics (absorbing medium, ground states)
- Biology (polymers, macromolecules)
- Statistics (particle simulation, restricted Markov, target distributions)
- Rare event analysis (importance sampling, multilevel branching)
- Signal processing, filtering

Particle physics: Markov $X_n \in$ Absorbing medium $G(x) = e^{-V(x)} \in [0, 1]$

$$X_n^c \in E^c = E \cup \{c\} \xrightarrow{absorption} \widehat{X}_n^c \xrightarrow{exploration} X_{n+1}^c$$

Absorption/killing: $\longrightarrow \widehat{X}_n^c = X_n^c$, with proba $G(X_n^c)$; otherwise the particle is killed and $\widehat{X}_n^c = c$.

\Downarrow

$$A = \{x : G(x) = 0\} \longrightarrow \text{Hard obstacles}$$

$$T = \inf\{n \ge 0; \widehat{X}_n^c = c\} \longrightarrow \text{Absorption time } X_{T+n}^c = \widehat{X}_{T+n}^c = c$$

 \implies **Feynman-Kac models** (G, X_n) : $\gamma_n = Law(X_n^c; T \ge n)$ and $\gamma_n(1) = Proba(T \ge n)$

$$\Downarrow$$
$$\eta_n = \mathsf{Law}(X_n^c \mid T \ge n) = \mathsf{Law}((X_0'^c, \dots, X_n'^c) \mid T \ge n)$$

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Biology: Macromolecules and Directed Polymers

• Self avoiding walks $X'_n \in \mathbb{Z}^d$

$$X_n = (X'_0, \dots, X'_n)$$
 and $G_n(X_n) = 1_{\notin \{X'_0, \dots, X'_{n-1}\}}(X'_n)$

 $\gamma_n(1) = \operatorname{Proba}(\forall 0 \le p \ne q \le n, \ X'_p \ne X'_q) \quad \text{and} \quad \eta_n = \operatorname{Law}(X'_0, \dots, X'_n \mid \forall 0 \le p \ne q \le n, \ X'_p \ne X'_q)$

• Edwards' model

$$X_n = (X'_0, \dots, X'_n)$$
 and $G_n(X_n) = \exp\{-\beta \sum_{0 \le p < n} \mathbf{1}_{X'_p}(X'_n)\}$

Statistics: Sequential MCMC and Feynman-Kac-Metropolis models

Metropolis potential [π target measure]+[(K, L) pair Markov transitions]

$$G(y_1, y_2) = \frac{\pi(dy_2)L(y_2, dy_1)}{\pi(dy_1)K(y_1, dy_2)}$$

Ex. π Gibbs measure:

$$\pi(dy) \propto e^{-V(y)} \ \lambda(dy) \Rightarrow G(y_1, y_2) = e^{(V(y_1) - V(y_2))} \ \frac{\lambda(dy_2) L(y_2, dy_1)}{\lambda(dy_1) K(y_1, dy_2)}$$

Note:
$$(K = L \ \lambda - \text{reversible})$$
 or $(\lambda K = \lambda \text{ and } L(y_2, dy_1) = \lambda(dy_1) \frac{dK(y_1, \bullet)}{d\lambda}(y_2))$
 \Downarrow
 $G(y_1, y_2) = \exp(V(y_1) - V(y_2))$

Notation $\mathbb{E}_{\nu}^{M}(\cdot)$ =Expectation w.r.t. Markov [transition M, initial condition ν] <u>Theorem:</u> (Time reversal formula), [A. Doucet, P.DM; (Séminaire Probab. 2003)]

$$\mathbb{E}_{\pi}^{L}(f_{n}(Y_{n}, Y_{n-1}..., Y_{0})|Y_{n} = y) = \frac{\mathbb{E}_{y}^{K}(f_{n}(Y_{0}, Y_{1}, ..., Y_{n}) \{\prod_{0 \le p < n} G(Y_{p}, Y_{p+1})\})}{\mathbb{E}_{y}^{K}(\{\prod_{0 \le p < n} G(Y_{p}, Y_{p+1})\})}$$

In addition :

- \oplus *FK-Metropolis n*-marginal: $\lim_{n\to\infty}\eta_n = \pi$ (cv. decays $\perp \pi$)
- \oplus Nonhomogeneous models: (π_n, L_n, K_n)

 $\pi_n(dy) \propto e^{-\beta_n V(y)} \lambda(dy)$, cooling schedule $\beta_n \uparrow \infty$, mutation s.t. $\pi_n = \pi_n K_n$, and Law $(X_0) = \pi_0$

$$\Downarrow$$

$$G_n(y_1, y_2) = \exp\left[-(\beta_{n+1} - \beta_n)V(y_1)\right] \Longrightarrow \eta_n = \pi_n$$

Rare events analysis

• Importance sampling and Twisted Feynman-Kac measures

$$\mathbb{P}(V_n(X_n) \geq a) \quad = \quad \mathbb{E}(\mathbf{1}_{V_n(X_n) \geq a} \ e^{-eta_n V_n(X_n)} \ e^{+eta_n V_n(X_n)})$$

 \Downarrow

Importance potentials/measures:

$$G_n(X_n, X_{n+1}) = e^{\beta_n(V_{n+1}(X_{n+1}) - V_n(X_n))} \Longrightarrow \mathbb{P}(V_n(X_n) \ge a) = \gamma_n(\mathbf{1}_{V_n \ge a} e^{-\beta_n V_n})$$

In addition:

$$\mathbb{E}(f_n(X_n) \mid V_n(X_n) \geq a) = \eta_n(f_n \mid \mathbb{1}_{V_n \geq a} e^{-eta_n V_n}) / \eta_n(\mathbb{1}_{V_n \geq a} e^{-eta_n V_n})$$

 \oplus Path-space models \Rightarrow weighted genealogies

$$X_n = (X'_0, \dots, X'_n)$$
 and $V_n(X_n) = V'_n(X'_n)$

$$\Downarrow$$
 $\mathbb{E}(f_n(X'_0,\ldots,X'_n)\mid V'_n(X'_n)\geq a)=\eta_n(f_n\;\mathbf{1}_{V_n\geq a}e^{-eta_nV_n})/\eta_n(\mathbf{1}_{V_n\geq a}e^{-eta_nV_n})$

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Multi-splitting Feynman-Kac models (≠ importance sampling)
 (E = A ∪ A^c), Y_n Markov, Y₀ ∈ A₀(⊂ A) → A^c = (B ∪ C), C = absorbing set/hard obstacle

Multi-level decomposition $B = B_m \subset \ldots \subset B_1 \subset B_0$ $(A_0 = B_1 - B_0, B_0 \cap C = \emptyset)$ \Downarrow

$$\mathbb{P}(Y_n \text{ hits } B \text{ before } C) = \mathbb{E}(\prod_{1 \le p \le m} G_p(X_p))$$

Inter-level excursions : $T_n = \inf \{ p \ge T_{n-1} : Y_p \in B_n \cup C \}$

$$X_n = (Y_p; T_{n-1} \le p \le T_n) \in \text{Excursion space} \quad G_n(X_n) = 1_{B_n}(Y_{T_n})$$

 \Downarrow

FK interpretation

$$\mathbb{E}(f(Y_0,\ldots,Y_{T_m}) \ \mathbf{1}_{B_m}(X_{T_m})) = \mathbb{E}(f(X_0,\ldots,X_m) \ \prod_{1 \le p \le m} G_p(X_p))$$

Advanced signal processing \rightarrow filtering/hidden Markov chains/Bayesian methodology <u>Signal process</u> $X_n =$ Markov chain $\in E_n$ <u>Observation/Sensor eq.</u> $Y_n = H_n(X_n, V_n) \in F_n$ with $\mathbb{P}(H_n(x_n, V_n) \in dy_n) = g_n(x_n, y_n) \lambda_n(dy_n)$ *Example:* $Y_n = h_n(X_n) + V_n \in F_n = \mathbb{R}$, with Gaussian noise $V_n = \mathcal{N}(0, 1)$ \Downarrow $\mathbb{P}(h_n(x_n) + V_n \in dy_n) = (2\pi)^{-1/2} e^{-\frac{1}{2}(y_n - h_n(x_n))^2} dy_n = \underbrace{\exp\left[h_n(x_n)y_n - h_n^2(x_n)/2\right]}_{g_n(x_n, y_n)} \underbrace{\mathcal{N}(0, 1)(dy_n)}_{\lambda_n(dy_n)}$

Prediction/filtering/smoothing \rightarrow **Feynman-Kac representation** $G_n(x_n) = g_n(x_n, y_n)$

$$\eta_n = \text{Law}(X_n \mid Y_0 = y_0, \dots, Y_{n-1} = y_{n-1}) = \text{Law}(X'_0, \dots, X'_n \mid Y_0 = y_0, \dots, Y_{n-1} = y_{n-1})$$

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Partially linear/Gaussian models

$$X_{n}^{1} = \text{Markov} \in E_{n} + \begin{cases} X_{n}^{2} = A_{n}(X_{n}^{1}) X_{n-1}^{2} + a_{n}(X_{n}^{1}) + B_{n}(X_{n}^{1}) W_{n} \in \mathbb{R}^{d} \\ Y_{n} = C_{n}(X_{n}^{1}) X_{n}^{2} + c_{n}(X_{n}^{1}) + D_{n}(X_{n}^{1}) V_{n} \in \mathbb{R}^{d'} \end{cases}$$

Given a realization $X^1 = x \rightarrow Kalman$ -Bucy optimal one step predictor

$$\widehat{X}_{x,n+1}^{2-} = \mathbb{E}(X_{n+1}^{2} \mid Y_{0}, \dots, Y_{n}, X^{1} = x) \text{ and } P_{x,n+1}^{-} = \mathbb{E}([X_{n+1}^{2} - \widehat{X}_{x,n+1}^{2-}][X_{n+1}^{2} - \widehat{X}_{x,n+1}^{2-}]')$$

$$\Downarrow$$

Quenched Kalman-Bucy recursion: $(\widehat{X}_{x,n+1}^{2}, P_{x,n+1}^{-}) = \mathcal{B}_{n+1}[(x_n, x_{n+1}), (\widehat{X}_{x,n}^{2}, P_{x,n}^{-})]$

Feynman-Kac representation: $\eta_n \sim (\mathbf{X}_n, \mathbf{G}_n)$ s.t.

$$\mathbf{X}_{n} = (X_{n}^{1}, (\widehat{X}_{X^{1}, n+1}^{2}, P_{X^{1}, n+1}^{-})) \text{ Markov chain} \in \mathbf{E}_{n} = (E_{n} \times \mathbb{R}^{d} \times \mathbb{R}^{d \times d})$$
$$\mathbf{G}_{n}(x, m, P) = \frac{d\mathcal{N}(C_{n}(x) \ m + c_{n}(x), C_{n}(x) \ P \ C_{n}(x)' + D_{n}(x)R_{n}^{v}D_{n}(x)')}{d\mathcal{N}(0, D_{n}(x)R_{n}^{v}D_{n}(x)')}(y_{n})$$

$$\Downarrow \quad [virtual \ sensor : \ Y_n = \{C_n(X_n^1) \ \widehat{X}_{X^1,n}^2 + c_n(X_n^1)\} + \widehat{V}_{X^1,n} \]$$

$$F_n(x,m,P) = f_n(x) \implies \eta_n(F_n) = \mathbb{E}(f_n(X_n^1) \mid Y_0, \dots, Y_{n-1})$$

$$F_n(x,m,P) = \mathcal{N}(m,P)(f_n) \implies \eta_n(F_n) = \mathbb{E}(f_n(X_n^2) \mid Y_0, \dots, Y_{n-1})$$

Note: \rightsquigarrow Interacting Kalman-Bucy filters and for path-space models we have

$$X_n^1 = (X_0^1 ', \dots, X_n^1 ') \rightsquigarrow \mathsf{Law}((X_0^1 ', \dots, X_n^1 ') \mid Y_0, \dots, Y_{n-1})$$