

Mean field simulation for Monte Carlo integration

Part I : Intro. nonlinear Markov models (+links integro-diff eq.)

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Some hyper-refs

- ▶ **Mean field simulation for Monte Carlo integration.** Chapman & Hall - Maths & Stats [600p.] (May 2013).
- ▶ **Feynman-Kac formulae,** Genealogical & Interacting Particle Systems with appl., Springer [573p.] (2004)
- ▶ **Concentration Inequalities for Mean Field Particle Models.** Ann. Appl. Probab (2011). (+ Rio).
- ▶ **Coalescent tree based functional representations for some Feynman-Kac particle models** Annals of Applied Probability (2009) (+ Patras, Rubenthaler)
- ▶ **Particle approximations of a class of branching distribution flows arising in multi-target tracking.** SIAM Control. & Opt. (2011). (joint work with Caron, Doucet, Pace)
- ▶ **On the stability & the approximation of branching distribution flows, with applications to nonlinear multiple target filtering.** Stoch. Analysis and Appl. (2011). (joint work with Caron, Pace, Vo).
- ▶ **More references on the website**<http://www.math.u-bordeaux1.fr/~delmoral/index.html> [+ Links]

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Some basic notation

Markov chains

Nonlinear Markov models

How & Why it works?

Lebesgue integral on a measurable state space E

$(\mu, f) = (\text{measure, function}) \in (\mathcal{M}(E) \times \mathcal{B}_b(E))$

$$\mu(f) = \int \mu(dx) f(x)$$

Delta-Dirac Measure at $a \in E$

$$\mu = \delta_a \Rightarrow \delta_a(f) = \int f(x) \delta_a(dx) = f(a)$$

Normalization of a positive measure $\mu \in \mathcal{M}_+(E)$ (when $\mu(1) \neq 0$)

$$\bar{\mu}(dx) := \mu(dx) / \mu(1) = \text{probability} \in \mathcal{P}(E)$$

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Example

$$\mu = 10 \times \text{Law}(X)$$

\Downarrow

$$\mu(1) = 10 \quad \& \quad \bar{\mu} = \text{Law}(X) \quad \& \quad \bar{\mu}(f) = \mathbb{E}(f(X))$$

Examples

- $E = \{1, \dots, d\} \rightsquigarrow$ Matrix-Vector notation

$$\mu := [\mu(1), \dots, \mu(d)] \quad \text{and} \quad f := \begin{bmatrix} f(1) \\ \vdots \\ f(d) \end{bmatrix} \Rightarrow \mu(f) := \sum_{i=1}^d \mu(i) f(i)$$

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- $\mathcal{X} = \sum_{1 \leq i \leq N} \delta_{X^i}$ spatial Poisson point process with intensity μ



$N =$ Poisson random variable with $\mathbb{E}(N) = \mu(1)$ and $X^i \text{ iid } \sim \bar{\mu}$



$$\mathbb{E}(\mathcal{X}(f)) = \mathbb{E}(\mathbb{E}(\mathcal{X}(f) \mid N)) = \mathbb{E}(N \bar{\mu}(f)) = \mu(1) \bar{\mu}(f) = \mu(f)$$

$Q(x, dy)$ integral operator from E into E'

Two operator actions :

$$f \in \mathcal{B}_b(E') \mapsto Q(f) \in \mathcal{B}_b(E) \quad \text{and} \quad \mu \in \mathcal{M}(E) \mapsto \mu Q \in \mathcal{M}(E')$$

with

$$Q(f)(x) = \int Q(x, dx') f(x')$$

$$[\mu Q](dx') = \int \mu(dx) Q(x, dx') \quad (\iff [\mu Q](f) := \mu[Q(f)])$$

and the composition

$$(Q_1 Q_2)(x, dx'') = \int Q_1(x, dx') Q_2(x', dx'')$$

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Notation (used in variance descriptions)

$$Q([f - Q(f)]^2)(x) := \int Q(x, dy) [f(y) - Q(f)(x)]^2$$

Q Markov operator $\iff \forall x \quad Q(x, dy) \in \mathcal{P}(E)$

\rightsquigarrow notation : M or K (Markov transitions-kernel / Stochastic matrices)

Finite state spaces $E = \{1, \dots, d\}$ and $E' = \{1, \dots, d'\}$:

Action on the right

$$f := \begin{bmatrix} f(1) \\ \vdots \\ f(d') \end{bmatrix} \in \mathcal{B}_b(E') \mapsto Q(f) = \begin{bmatrix} Q(f)(1) \\ \vdots \\ Q(f)(d) \end{bmatrix} \in \mathcal{B}_b(E)$$

Matrix operation

$$Q(f) = \begin{bmatrix} Q(f)(1) \\ \vdots \\ Q(f)(d) \end{bmatrix} = \begin{bmatrix} Q(1,1) & \dots & Q(1,d') \\ \vdots & \dots & \vdots \\ Q(d,1) & \dots & Q(d,d') \end{bmatrix} \begin{bmatrix} f(1) \\ \vdots \\ f(d') \end{bmatrix}$$

Finite state spaces $E = \{1, \dots, d\}$ and $E' = \{1, \dots, d'\}$:

Action on the left

$$\mu = [\mu(1), \dots, \mu(d)] \in \mathcal{M}(E) \mapsto \mu Q = [(\mu Q)(1), \dots, (\mu Q)(d')] \in \mathcal{M}(E')$$

Matrix operation

$$\mu Q = [\mu(1), \dots, \mu(d)] \begin{bmatrix} Q(1,1) & \dots & Q(1,d') \\ \vdots & \dots & \vdots \\ Q(d,1) & \dots & Q(d,d') \end{bmatrix}$$

Boltzmann-Gibbs transformation : $G \geq 0$ s.t. $\mu(G) > 0$

$$\Psi_G(\mu)(dx) = \frac{1}{\mu(G)} G(x) \mu(dx)$$

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Bayes' rule (with fixed observation y)

$$\mu(dx) = p(x)dx \quad \text{and} \quad G(x) = p(y|x)$$

↓

$$\Psi_G(\mu)(dx) = \frac{1}{p(y)} p(y|x) p(x)dx = p(x|y) dx$$

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Restriction

$$\mu(dx) = \mathbb{P}(X \in dx) = p(x)dx \quad \text{and} \quad G(x) = 1_A(x)$$

\Downarrow

$$\Psi_G(\mu)(dx) = \frac{1}{\mathbb{P}(X \in A)} 1_A(x) p(x)dx = \mathbb{P}(X \in dx \mid X \in A)$$

Boltzmann-Gibbs transformation : $G \geq 0$ s.t. $\mu(G) > 0$

$$\Psi_G(\mu)(dx) = \frac{1}{\mu(G)} G(x) \mu(dx)$$

↓

∃ **Markov transport equation**

$$\Psi_G(\mu)(dy) = \int \mu(dx) S_\mu(x, dy) \iff \Psi_G(\mu) = \mu S_\mu$$

Example 1 : ($G \leq 1$) \rightsquigarrow accept/reject/recycling/interacting jumps

$$S_\mu(x, dy) = G(x)\delta_x(dy) + (1 - G(x)) \Psi_G(\mu)(dy)$$

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Example 1 : ($G \leq 1$) \rightsquigarrow accept/reject/recycling/interacting jumps

$$S_\mu(x, dy) = G(x) \delta_x(dy) + (1 - G(x)) \Psi_G(\mu)(dy)$$

Note :

$$\begin{aligned} & S_{\frac{1}{N} \sum_{1 \leq j \leq N} \delta_{X^j}}(X^i, dy) \\ &= G(X^i) \delta_{X^i}(dy) + (1 - G(X^i)) \sum_{1 \leq j \leq N} \frac{G(X^j)}{\sum_{1 \leq k \leq N} G(X^k)} \delta_{X^j}(dy) \end{aligned}$$

Other examples of transport equations $\Psi_G(\mu) = \mu S_\mu$

Example 2 : $\forall \epsilon_\mu$ s.t. $\epsilon_\mu G \leq 1$ μ - a.e.

$$S_\mu(x, dy) = \epsilon_\mu G(x) \delta_x(dy) + (1 - \epsilon_\mu G(x)) \Psi_G(\mu)(dy)$$

Example 3 : $\forall a$ s.t. $G > a$

$$S_\mu(x, dy) = \frac{a}{\mu(G)} \delta_x(dy) + \left(1 - \frac{a}{\mu(G)}\right) \Psi_{G-a}(\mu)(dy)$$

Example 4 : $\forall G$

$$S_\mu(x, dy) = \alpha(x) \delta_x(dy) + (1 - \alpha(x)) \Psi_{[G-G(x)]_+}(\mu)(dy)$$

with the acceptance rate

$$\alpha(x) = \mu[G \wedge G(x)]/\mu(G)$$

Some basic notation

Markov chains

- Linear evolution equations

- Finite state space models

- Monte Carlo methods

- Links with linear integro-diff. eq.

Nonlinear Markov models

How & Why it works?

Example: Markov chain $X_{n+1} = F_n(X_n, W_n)$

$$\begin{aligned} \eta_0 &= \text{Law}(X_0) & \text{and} & & M_n(x_{n-1}, dx_n) &= \mathbb{P}(X_n \in dx_n \mid X_{n-1} = x_{n-1}) \\ \eta_0 M_1 &= \text{Law}(X_1) & \text{and} & & M_n(f)(x) &= \mathbb{E}(f(X_n) \mid X_{n-1} = x) \end{aligned}$$

Example: Markov chain $X_{n+1} = F_n(X_n, W_n)$

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as well as

$$\begin{aligned}(M_1 \dots M_n)(x_0, dx_n) &= \mathbb{P}(X_n \in dx_n \mid X_0 = x_0) \\ \eta_0 M_1 \dots M_n &= \text{Law}(X_n)\end{aligned}$$

$E = \{1, \dots, d\} \rightsquigarrow$ Matrix-Vector notation

Markov chain models $X_{n+1} = F_n(X_n, W_n)$

Linear evolution equations Law(X_n) := η_n

$$\eta_{n+1} = \eta_n M_{n+1}$$

\Downarrow

$E = \{1, \dots, d\}$ \rightsquigarrow simple matrix computations

$$\eta_{n+1} = [\eta_n(1), \dots, \eta_n(d)] \begin{bmatrix} M_{n+1}(1, 1) & \dots & M_{n+1}(1, d) \\ \vdots & \dots & \vdots \\ M_{n+1}(d, 1) & \dots & M_{n+1}(d, d) \end{bmatrix}$$

Markov chain models $X_{n+1} = F_n(X_n, W_n)$

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Note :

Same equations for $X_n \in E_n = \{1, \dots, d_n\}$ with $M_{n+1} \in \mathbb{R}_+^{(d_n \times d_{n+1})}$

(Crude) Monte Carlo methods : Markov chain $X_{n+1} = F_n(X_n, W_n) \in E_n$

Linear evolution equations Law(X_n) := η_n

$$\eta_{n+1} = \eta_n M_{n+1}$$

\Downarrow

N iid copies/samples $X_{n+1}^i = F_n(X_n^i, W_n^i)$, $1 \leq i \leq N$

\Downarrow

$$\eta_n^N := \frac{1}{N} \sum_{1 \leq i \leq N} \delta_{X_n^i} \simeq_{N \uparrow \infty} \eta_n$$

\Updownarrow

$$\eta_n^N(f) = \frac{1}{N} \sum_{1 \leq i \leq N} f(X_n^i) \simeq_{N \uparrow \infty} \eta_n(f) = \mathbb{E}(f(X_n))$$

(Crude) Monte Carlo methods : Markov chain $X_n \in E_n$ with transitions M_n

Path space models

$$\mathbb{P}_n^N := \frac{1}{N} \sum_{1 \leq i \leq N} \delta_{(X_0^i, \dots, X_n^i)} \simeq_{N \uparrow \infty} \mathbb{P}_n = \text{Law}(X_0, \dots, X_n)$$

Historical process

$$\mathbf{X}_n = (X_0, \dots, X_n) \in \mathbf{E}_{n+1} = \prod_{0 \leq p \leq n} E_p \quad \text{with Markov transition } \mathbf{M}_n$$



Same model as before

$$\mathbb{P}_{n+1} = \eta_{n+1} = \eta_n \mathbf{M}_{n+1}$$

and

$$\eta_n^N := \frac{1}{N} \sum_{1 \leq i \leq N} \delta_{\mathbf{X}_n^i} = \mathbb{P}_n^N \simeq_{N \uparrow \infty} \mathbb{P}_n = \eta_n$$

with N iid copies of the historical process

$$\mathbf{X}_n^i = (X_0^i, \dots, X_n^i)$$

Diffusion type & discrete generation models (d=1)

Markov chain with Gaussian perturbations

$$\begin{aligned}X_{n+1} &= F_n(X_n, W_n) \\ &= X_n + a_n(X_n)\Delta + b_n(X_n) \sqrt{\Delta} W_n\end{aligned}$$

with the Gaussian random variable

$$\mathbb{P}(W_n \in dw) = \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{w^2}{2}\right)$$

↓

Diffusion limits when $(t_{n+1} - t_n) = \Delta \downarrow 0$ & $(a_n, b_n, X_n) = (a'_{t_n}, b'_{t_n}, X'_{t_n})$

↓

$$dX'_t = a'_t(X'_t)dt + b'_t(X'_t)dW_t$$

Diffusion type & discrete generation models (d=1)

Diffusion model

$$dX'_t = a'_t(X'_t)dt + b'_t(X'_t)dW_t$$

Taylor expansion (Ito's formula)

$$f(X'_t + dX'_t) - f(X'_t) = \partial f(X'_t) dX'_t + \frac{1}{2} \partial^2 f(X'_t) dX'_t dX'_t + \dots$$

Diffusion type & discrete generation models (d=1)

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Taylor expansion (Ito's formula)

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with the infinitesimal generator

$$L_t(f) = a'_t \partial f + \frac{1}{2} (b'_t)^2 \partial^2 f$$

↓

Weak parabolic PDE

$$\eta_t = \text{Law}(X'_t) \Leftrightarrow \frac{d}{dt} \eta_t(f) = \eta_t(L_t(f))$$

Two-steps jump-diffusion type model (d=1)

$$X_n \rightarrow X_{n+1/2} = F_n(X_n, W_n) \rightarrow X_{n+1} = \epsilon_{n+1} X_{n+1/2} + (1 - \epsilon_{n+1}) Y_{n+1}$$

$$\epsilon_{n+1} \sim e^{-V_n(X_{n+1/2}) \Delta} \delta_1 + \left(1 - e^{-V_n(X_{n+1/2}) \Delta}\right) \delta_0$$

$$Y_{n+1} \sim P_n(X_{n+1/2}, dy)$$

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$$Y_{n+1} \sim P_n(X_{n+1/2}, dy)$$

Jump-diffusion limits $(a_n, b_n, V_n, P_n, X_n) = (a'_{t_n}, b'_{t_n}, V'_{t_n}, P'_{t_n}, X'_{t_n})$

between jumps = diffusion as before, and jumps times

$$T_{n+1} = \inf \left\{ t \geq T_n : \int_{T_n}^t V'_s(X'_s) ds \geq e_n \right\} \quad e_n \text{ iid } \text{exp}(\lambda = 1)$$

Two-steps jump-diffusion type model (d=1)

$$X_n \xrightarrow{M_{n+1}} X_{n+1/2} \xrightarrow{J_{n+1}} X_{n+1}$$

with the diffusion part

$$M_{n+1}(f)(x) \simeq f(x) + L_t^{diff}(f)(x) \Delta$$

and the jump part

$$\begin{aligned} J_{n+1}(f)(x) &= e^{-V'_{t_n}(x) \Delta} f(x) + \left(1 - e^{-V'_{t_n}(x) \Delta}\right) P'_{t_n}(f)(x) \\ &= f(x) + \underbrace{V'_{t_n}(x) [P'_{t_n}(f)(x) - f(x)]}_{=L_t^{jump}(f)(x)} \Delta \end{aligned}$$

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$$[MJ = (I + L^{diff} \Delta) (I + L^{jump} \Delta) \simeq I + (L^{diff} + L^{jump}) \Delta]$$

Two-steps jump-diffusion type model (d=1)

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$$[MJ = (I + L^{diff} \Delta) (I + L^{jump} \Delta) \simeq I + (L^{diff} + L^{jump}) \Delta]$$

⇒ **Weak integro-differential equation**

$$\eta_t = \text{Law}(X'_t) \Leftrightarrow \frac{d}{dt} \eta_t(f) = \eta_t(L_t(f))$$

with the infinitesimal generator

$$L_t(f)(x) = a'_t(x) \partial f(x) + \frac{1}{2} (b'_t(x))^2 \partial^2 f(x) + V'_t(x) \int (f(y) - f(x)) P'_t(x, dy)$$

Some basic notation

Markov chains

Nonlinear Markov models

- Nonlinear evolution equations

- Mean field particle models

- Graphical illustration

- Links with nonlinear integro-diff. eq.

How & Why it works?

Mean field models : Markov chain $X_{n+1} = F_n(X_n, \eta_n, W_n)$

Nonlinear evolution equations $\text{Law}(X_n) := \eta_n$

$$\eta_{n+1} = \Phi_{n+1}(\eta_n) := \eta_n K_{n+1, \eta_n}$$

with Markov transitions $K_{n, \eta}$ indexed by the simplex $\eta \in \mathbb{S}^{(d-1)} \subset \mathbb{R}_+^d$



$$K_{n+1, \eta_n}(x_n, dx_{n+1}) = \mathbb{P}(X_{n+1} \in dx_{n+1} \mid X_n = x_n)$$

Mean field models : Markov chain $X_{n+1} = F_n(X_n, \eta_n, W_n)$

Nonlinear evolution equations Law(X_n) := η_n

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$$K_{n+1, \eta_n}(x_n, dx_{n+1}) = \mathbb{P}(X_{n+1} \in dx_{n+1} \mid X_n = x_n)$$



When $E = \{1, \dots, d\} \rightsquigarrow$ simple matrix computations

$$\eta_{n+1} = [\eta_n(1), \dots, \eta_n(d)] \begin{bmatrix} K_{n+1, \eta_n}(1, 1) & \dots & K_{n+1, \eta_n}(1, d) \\ \vdots & \dots & \vdots \\ K_{n+1, \eta_n}(d, 1) & \dots & K_{n+1, \eta_n}(d, d) \end{bmatrix}$$

Example 1 : Markov chain $X_{n+1} = F_n(X_n, \eta_n, W_n) \in E := \{-1, 1\}$

McKean's two velocities of gases :

$$F_n(X_n, \eta_n, W_n) = X_n 1_{W_n \leq \eta_n(1)} + (-X_n) 1_{W_n > \eta_n(1)} \iff X_{n+1} = \epsilon_n X_n$$

with the Bernoulli random variable

$$\mathbb{P}(\epsilon_n = 1) = 1 - \mathbb{P}(\epsilon_n = -1) = \eta_n(1)$$

\Downarrow

Nonlinear equation on the simplex $\mathbb{S}^{(0)} = [0, 1]$:

$$\eta_{n+1}(1) = \eta_n(1)^2 + \eta_n(-1)^2 = \eta_n(1)^2 + (1 - \eta_n(1))^2$$

Example 1 : Markov chain $X_{n+1} = F_n(X_n, \eta_n, W_n) \in E := \{-1, 1\}$

McKean's two velocities of gases :

$$F_n(X_n, \eta_n, W_n) = X_n 1_{W_n \leq \eta_n(1)} + (-X_n) 1_{W_n > \eta_n(1)} \iff X_{n+1} = \epsilon_n X_n$$

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\Downarrow

Nonlinear equation on the simplex $\mathbb{S}^{(0)} = [0, 1]$:

$$\begin{aligned} \eta_{n+1}(1) &= \eta_n(1)^2 + \eta_n(-1)^2 &= & \eta_n(1)^2 + (1 - \eta_n(1))^2 \\ & \rightarrow_{n \uparrow \infty} 1/2 & \text{ if } & \eta_0(1) \notin \{0, 1\} \end{aligned}$$

Example 2 : $G_n(i) \stackrel{\text{ex.}}{=} e^{-V_n(i)} \in]0, 1]$ & $(M_{n+1}(i, j))_{i, j=1, \dots, d}$ **Markov transition**

$$K_{n+1, \eta_n}(i, j) = G_n(i) M_{n+1}(i, j) + (1 - G_n(i)) \sum_k \frac{\eta_n(k) G_n(k)}{\sum_l \eta_n(l) G_n(l)} M_{n+1}(k, j)$$

Example 2 : $G_n(i)$ (ex. $e^{-V_n(i)} \in]0, 1]$) & $(M_{n+1}(i, j))_{i, j=1, \dots, d}$ Markov transition

$$K_{n+1, \eta_n}(i, j) = G_n(i) M_{n+1}(i, j) + (1 - G_n(i)) \sum_k \frac{\eta_n(k) G_n(k)}{\sum_l \eta_n(l) G_n(l)} M_{n+1}(k, j)$$

↓

$$\sum_k \eta_n(k) K_{n+1, \eta_n}(k, j)$$

$$= \sum_k \eta_n(k) G_n(k) M_{n+1}(k, j) + [1 - \sum_l \eta_n(l) G_n(l)] \times \sum_k \frac{\eta_n(k) G_n(k)}{\sum_l \eta_n(l) G_n(l)} M_{n+1}(k, j)$$

$$= \sum_k \frac{\eta_n(k) G_n(k)}{\sum_l \eta_n(l) G_n(l)} M_{n+1}(k, j)$$

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$$= \sum_k \frac{\eta_n(k) G_n(k)}{\sum_l \eta_n(l) G_n(l)} M_{n+1}(k, j) \propto \sum_k \eta_n(k) G_n(k) M_{n+1}(k, j)$$

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↓

$$\eta_{n+1} \propto \eta_n \underbrace{\begin{bmatrix} G_n(1) & 0 & \dots & 0 & 0 \\ \vdots & & \dots & & \vdots \\ 0 & 0 & \dots & 0 & G_n(d) \end{bmatrix}}_{\text{Multiplication}} \underbrace{\begin{bmatrix} M_{n+1}(1, 1) & \dots & M_{n+1}(1, d) \\ \vdots & \dots & \vdots \\ M_{n+1}(d, 1) & \dots & M_{n+1}(d, d) \end{bmatrix}}_{\text{Markov transport}}$$

Example 2 : $G_n(i) \stackrel{\text{ex.}}{=} e^{-V_n(i)} \in]0, 1]$ & $(M_{n+1}(i, j))_{i, j=1, \dots, d}$ **Markov transition**

$$\eta_{n+1} = [\Psi_{G_n}(\eta_n)(1), \dots, \Psi_{G_n}(\eta_n)(d)] \begin{bmatrix} M_{n+1}(1, 1) & \dots & M_{n+1}(1, d) \\ \vdots & \dots & \vdots \\ M_{n+1}(d, 1) & \dots & M_{n+1}(d, d) \end{bmatrix}$$

with the Boltzmann-Gibbs transformation

$$\Psi_{G_n} : \eta \in \mathcal{M}(E) \mapsto \Psi_{G_n}(\eta) \in \mathcal{M}(E)$$

defined by

$$\Psi_{G_n}(\eta)(i) = \frac{1}{\eta_n(G_n)} G_n(i) \eta(i)$$

\Downarrow

Nonlinear evolution eq. on the $(d-1)$ -simplex $\eta_n \in \mathbb{S}^{(d-1)} \subset \mathbb{R}_+^d$

$$\eta_{n+1} = \Phi_{n+1}(\eta_n) := \Psi_{G_n}(\eta_n) M_{n+1}$$

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$$\eta_{n+1} = \Phi_{n+1}(\eta_n) := \Psi_{G_n}(\eta_n) M_{n+1} \Leftrightarrow \text{Feynman-Kac models}$$

Mean field models : Markov $X_{n+1} = F_n(X_n, \eta_n, W_n) \in E = \mathbb{R}^d$

Nonlinear evolution equations $\text{Law}(X_n) := \eta_n$

$$\eta_{n+1} = \Phi_{n+1}(\eta_n) := \eta_n K_{n+1, \eta_n}$$

\Downarrow

Mean field particle-simulation models:

N almost iid copies/samples $X_{n+1}^i = F_n(X_n^i, \eta_n^N, W_n^i), 1 \leq i \leq N$

with the occupation measure of the system at time n :

$$\eta_n^N := \frac{1}{N} \sum_{1 \leq i \leq N} \delta_{X_n^i} \simeq_{N \uparrow \infty} \eta_n$$

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\Downarrow [by induction on n]

$$\eta_{n+1}^N = \frac{1}{N} \sum_{1 \leq i \leq N} \delta_{X_{n+1}^i} \quad \text{with} \quad X_{n+1}^i \simeq F_n(X_n^i, \eta_n, W_n^i) \Rightarrow \eta_{n+1}^N \simeq_{N \uparrow \infty} \eta_{n+1}$$

An abstract mathematical model

Nonlinear evolution equation

$$\eta_{n+1} = \Phi_{n+1}(\eta_n) := \eta_n K_{n+1, \eta_n}$$



Nonlinear Markov model interpretation (not unique)

$$K_{n+1, \eta_n}(x_n, dx_{n+1}) = \mathbb{P}(X_{n+1} \in dx_{n+1} \mid X_n = x_n) \quad \text{with Law}(X_n) := \eta_n$$



Mean field particle-simulation model

$$X_n^i \rightsquigarrow X_{n+1}^i = \text{r.v. with law } K_{n+1, \eta_n^N}(X_n^i, dx) \quad \text{where } \eta_n^N = \frac{1}{N} \sum_{i=1}^N \delta_{X_n^i}$$

Local sampling errors

Nonlinear evolution equation

$$\eta_{n+1} = \Phi_{n+1}(\eta_n)$$

Mean field particle model

$$V_{n+1}^N := \sqrt{N} (\eta_{n+1}^N - \Phi_{n+1}(\eta_n^N)) \Leftrightarrow \eta_{n+1}^N = \Phi_{n+1}(\eta_n^N) + \frac{1}{\sqrt{N}} V_{n+1}^N$$

Note $\forall f : \text{osc}(f) := \sup_{x,y} (f(x) - f(y)) \leq 1$

$$\mathbb{E} (\eta_{n+1}^N(f) \mid \eta_n^N) = \eta_n^N K_{n+1, \eta_n^N}(f) = \Phi_{n+1}(\eta_n^N)(f)$$

$$N \mathbb{E} ([\eta_{n+1}^N - \Phi_{n+1}(\eta_n^N)](f)^2 \mid \eta_n^N) = \eta_n^N [K_{n+1, \eta_n^N}[f - K_{n+1, \eta_n^N}(f)]^2] \leq 1$$

McKean measures : Markov chain $X_n \in E_n$ with transitions $K_{n,\eta_{n-1}}$

$$\mathbb{P}_n^N := \frac{1}{N} \sum_{1 \leq i \leq N} \delta_{(X_0^i, \dots, X_n^i)} \simeq_{N \uparrow \infty} \mathbb{P}_n = \text{Law}(X_0, \dots, X_n)$$

with the McKean measures

$$\mathbb{P}_n(d(x_0, \dots, x_n)) = \eta_0(dx_0) \prod_{1 \leq p \leq n} K_{p,\eta_{p-1}}(x_{p-1}, dx_p)$$

McKean measures : Markov chain $X_n \in E_n$ with transitions $K_{n,\eta_{n-1}}$

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Historical process

$$\mathbf{X}_n = (X_0, \dots, X_n) \in \mathbf{E}_{n+1} = \prod_{0 \leq p \leq n} E_p \quad \text{with Markov transition } \mathbf{K}_{n,\eta_{n-1}}$$

McKean measures : Markov chain $X_n \in E_n$ with transitions $K_{n,\eta_{n-1}}$

$$\mathbb{P}_n^N := \frac{1}{N} \sum_{1 \leq i \leq N} \delta_{(X_0^i, \dots, X_n^i)} \simeq_{N \uparrow \infty} \mathbb{P}_n = \text{Law}(X_0, \dots, X_n)$$

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$$\mathbb{P}_n(d(x_0, \dots, x_n)) = \eta_0(dx_0) \prod_{1 \leq p \leq n} K_{p,\eta_{p-1}}(x_{p-1}, dx_p)$$

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↓

Same mathematical model as before

$$\mathbb{P}_{n+1} = \eta_{n+1} = \eta_n \mathbf{K}_{n+1,\eta_n}$$

and

$$\eta_n^N := \frac{1}{N} \sum_{1 \leq i \leq N} \delta_{\mathbf{X}_n^i} = \mathbb{P}_n^N \simeq_{N \uparrow \infty} \mathbb{P}_n = \eta_n$$

with almost N iid copies of the historical process $\mathbf{X}_n^i = (X_0^i, \dots, X_n^i)$.

Example 1 : Markov chain $X_{n+1} = F_n(X_n, \eta_n, W_n) \in E = \mathbb{R}^{d=1}$

McKean-Vlasov diffusion type & discrete generation models

$$X_{n+1} = F_n(X_n, \eta_n, W_n) = a_n(X_n, \eta_n) + b_n(X_n, \eta_n) W_n$$

with the Gaussian random variable

$$\mathbb{P}(W_n \in dw) = \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{w^2}{2}\right)$$

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Two-steps jump type model

$$X_n \rightarrow X_{n+1/2} = F_n(X_n, \eta_n, W_n) \rightarrow X_{n+1} = \epsilon_{n+1} X_{n+1/2} + (1 - \epsilon_{n+1}) Y_{n+1}$$

with

$$\epsilon_{n+1} \sim e^{-V_{\eta_{n+1/2}}(X_{n+1/2})} \delta_1 + \left(1 - e^{-V_{\eta_{n+1/2}}(X_{n+1/2})}\right) \delta_0$$

$$Y_{n+1} \sim P_{\eta_{n+1/2}}(X_{n+1/2}, dy)$$

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McKean-Vlasov diffusion type & discrete generation models

$$a_n(X_n, \eta_n) = \int \eta_n(dy) a'_n(X_n, y) \quad \& \quad b_n(X_n, \eta_n) = \int \eta_n(dy) b'_n(X_n, y)$$

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$$X_{n+1}^i = F_n(X_n^i, \eta_n^N, W_n^i) = \frac{1}{N} \sum_{j=1}^N a'_n(X_n^i, X_n^j) + \frac{1}{N} \sum_{j=1}^N b'_n(X_n^i, X_n^j) W_n^i$$

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McKean-Vlasov diffusion type & discrete generation models

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In the same vein : Two-steps mean field jump type model

$$X_n^i \rightarrow X_{n+1/2}^i = F_n(X_n^i, \eta_n^N, W_n^i) \rightarrow X_{n+1}^i = \epsilon_{n+1}^i X_{n+1/2}^i + (1 - \epsilon_{n+1}^i) Y_{n+1}^i$$

with

$$\epsilon_{n+1}^i \sim e^{-V_{\eta_{n+1/2}^N}(X_{n+1/2}^i)} \delta_1 + \left(1 - e^{-V_{\eta_{n+1/2}^N}(X_{n+1/2}^i)}\right) \delta_0$$

$$Y_{n+1}^i \sim P_{\eta_{n+1/2}^N}(X_{n+1/2}^i, dy)$$

Example 2 : Back to the multiplication-transport model $\eta_{n+1} = \Psi_{G_n}(\eta_n)M_{n+1}$

Nonlinear transport equation

$$\Psi_{G_n}(\mu) = \mu S_{n,\mu} \quad \text{with} \quad S_{n,\mu}(x, \cdot) = G_n(x)\delta_x + (1 - G_n(x)) \Psi_{G_n}(\mu)$$

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↓

Nonlinear Markov chain model

$$\eta_{n+1} = \Phi_{n+1}(\eta_n) := \eta_n K_{n+1,\eta_n} \quad \text{with} \quad K_{n+1,\eta_n} := S_{n,\eta_n} M_{n+1}$$

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⇓

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⇓

Mean field particle model = Genetic type interacting jump model

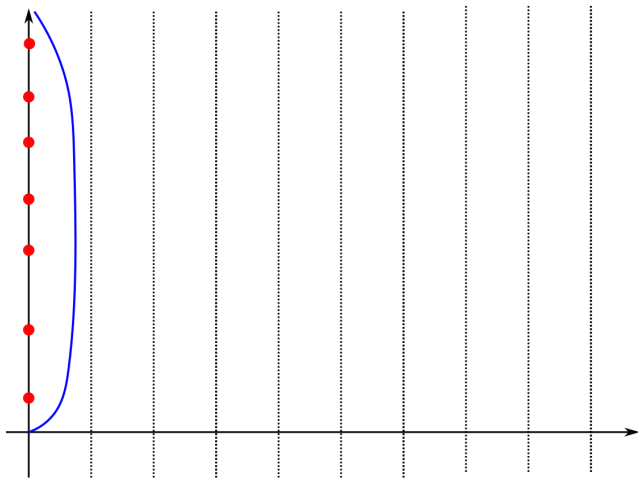
$$X_n^i \xrightarrow{S_{n,\eta_n^N}} \widehat{X}_n^i \xrightarrow{M_{n+1}} X_{n+1}^i$$

$\underbrace{\hspace{15em}}_{K_{n+1,\eta_n^N}}$

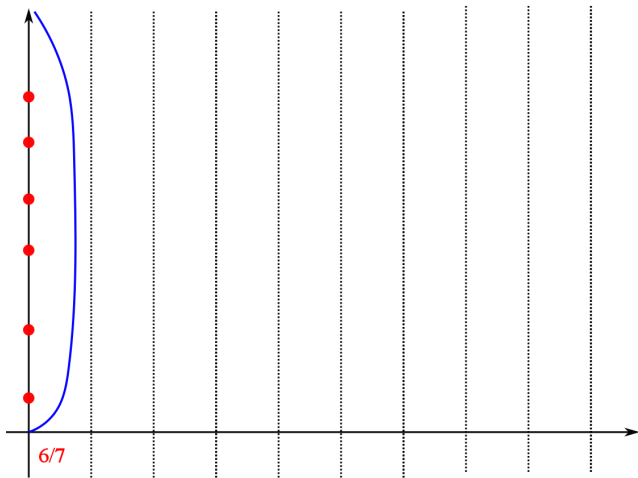
with

$$S_{n,\eta_n^N}(X_n^i, dy) = G_n(X_n^i)\delta_{X_n^i}(dy) + (1 - G_n(X_n^i)) \sum_{1 \leq j \leq N} \frac{G_n(X_n^j)}{\sum_{1 \leq k \leq N} G_n(X_n^k)} \delta_{X_n^j}(dy)$$

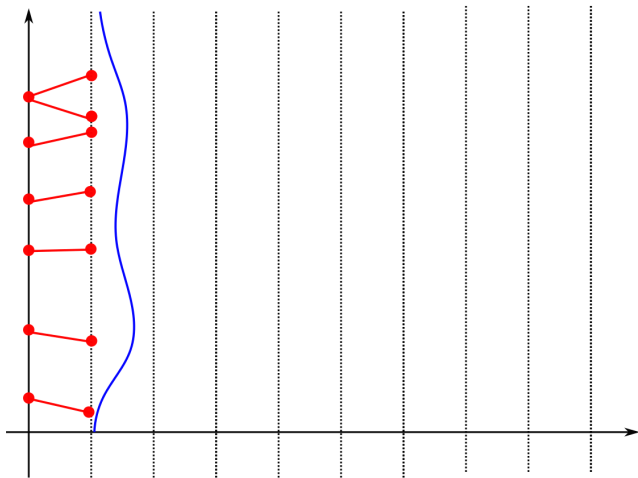
Graphical illustration : $\eta_n \simeq \eta_n^N := \frac{1}{N} \sum_{1 \leq i \leq N} \delta_{x_n^i}$



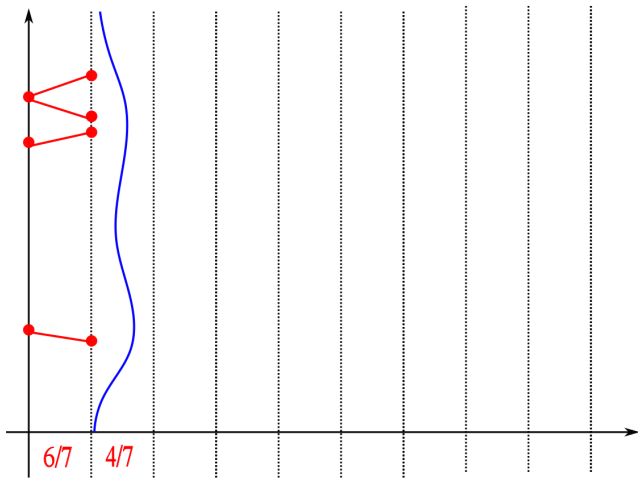
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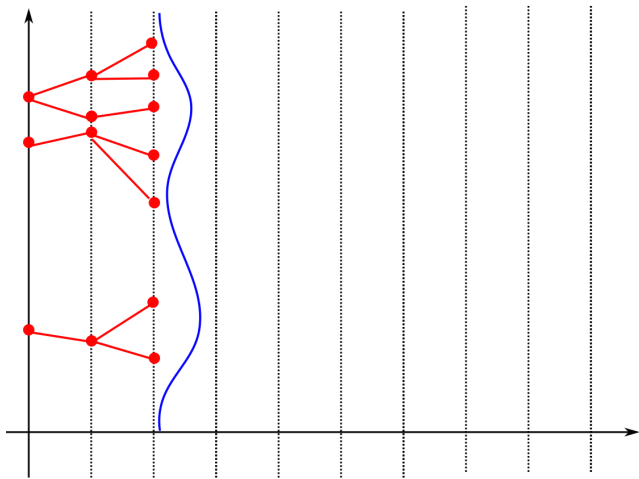
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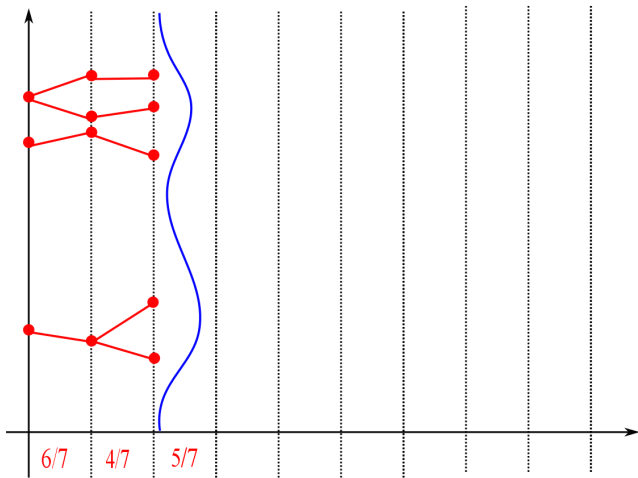
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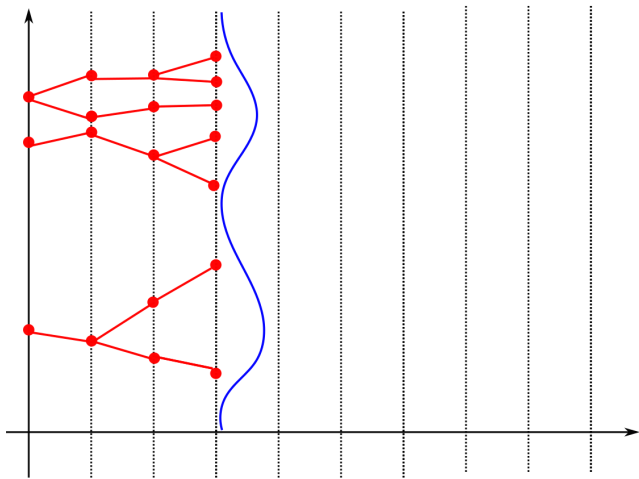
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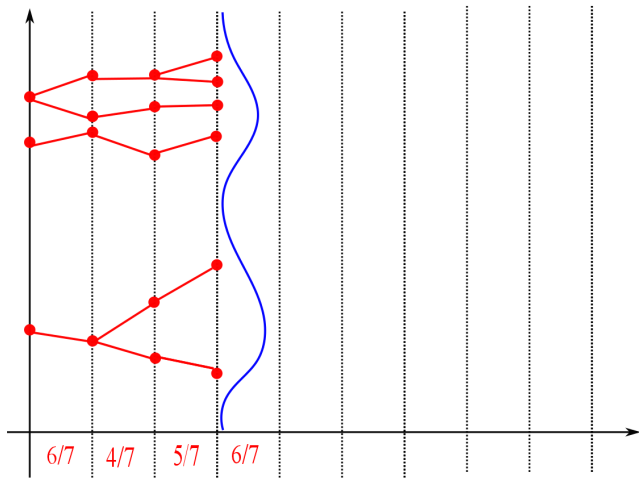
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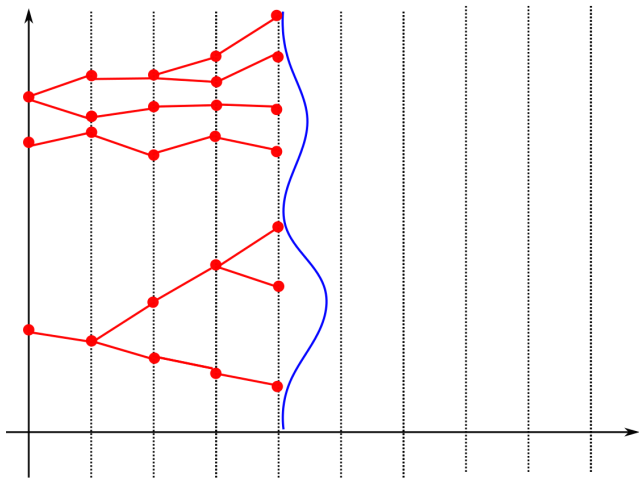
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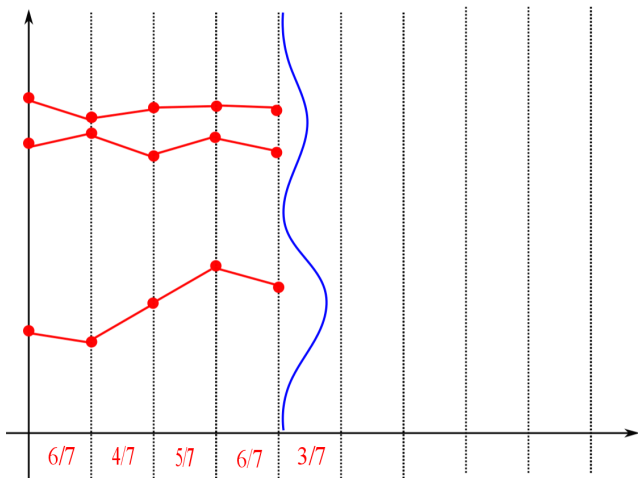
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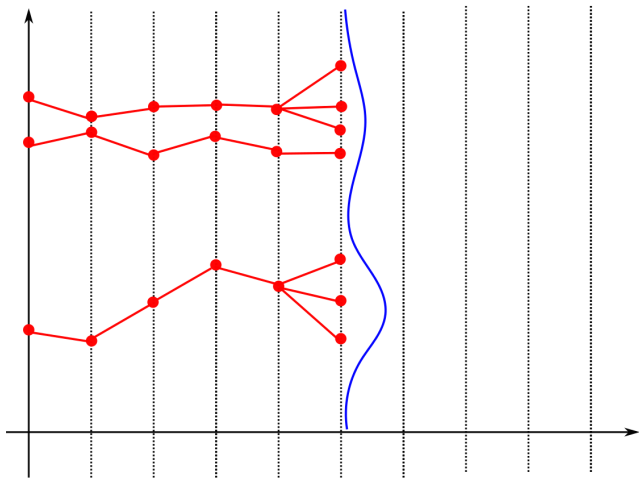
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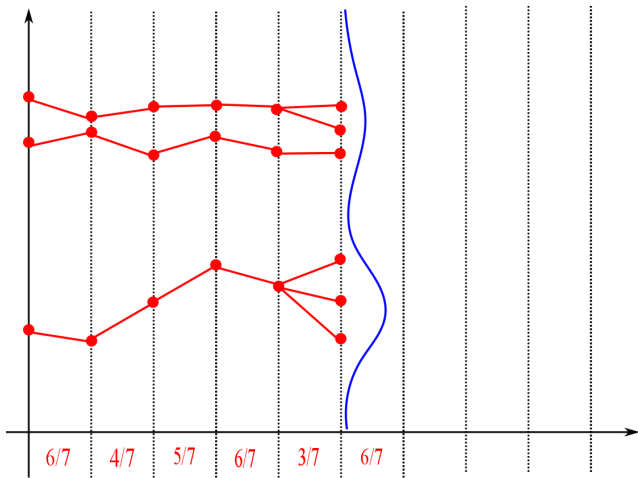
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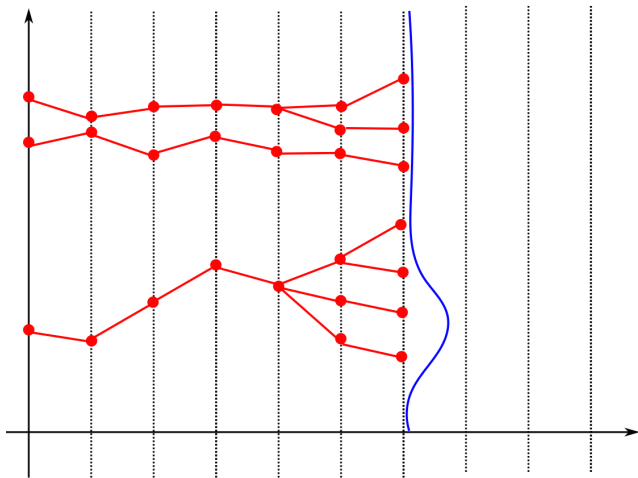
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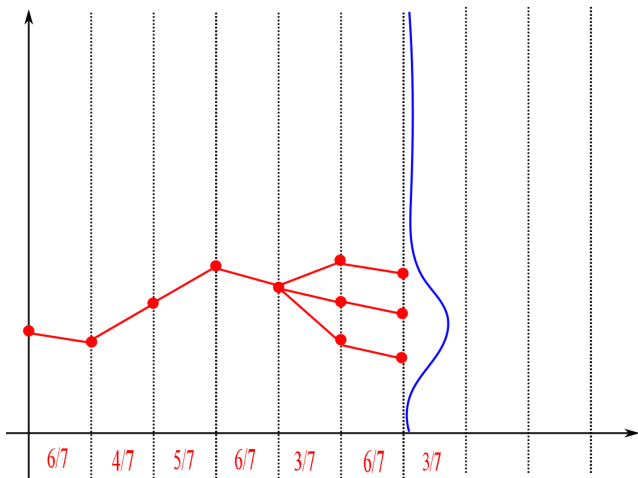
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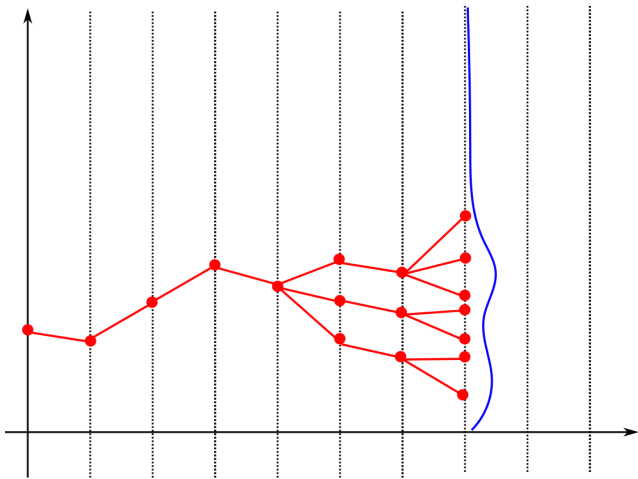
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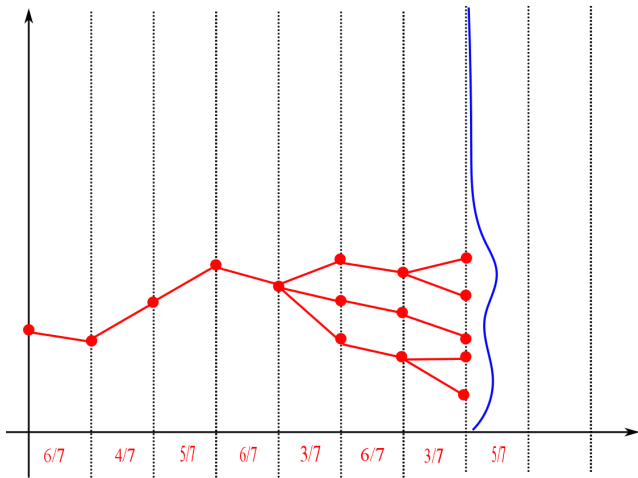
Graphical illustration : $\eta_n \simeq \eta_n^N := \frac{1}{N} \sum_{1 \leq i \leq N} \delta_{X_n^i}$



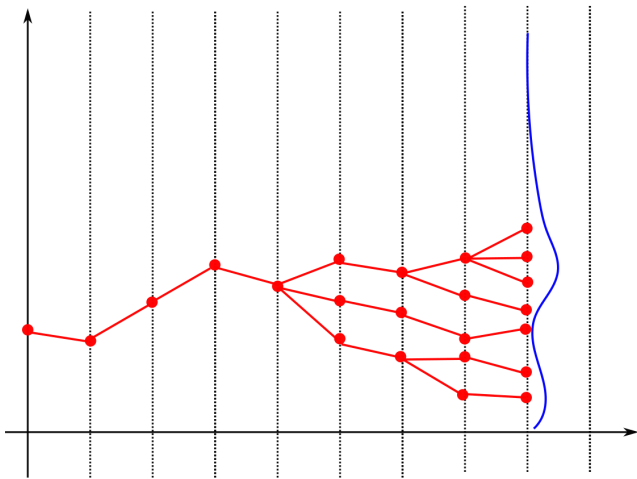
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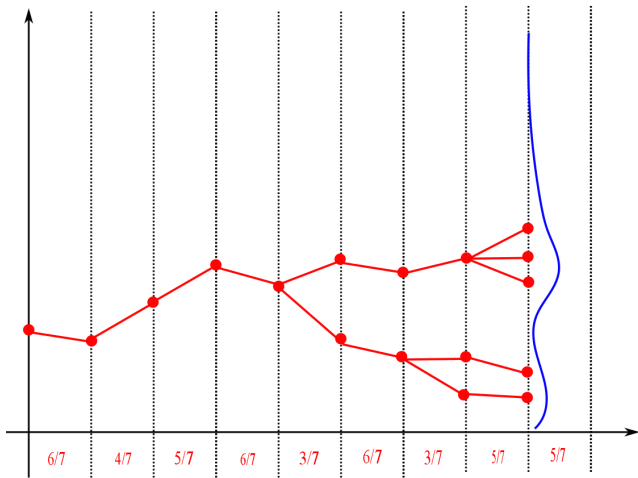
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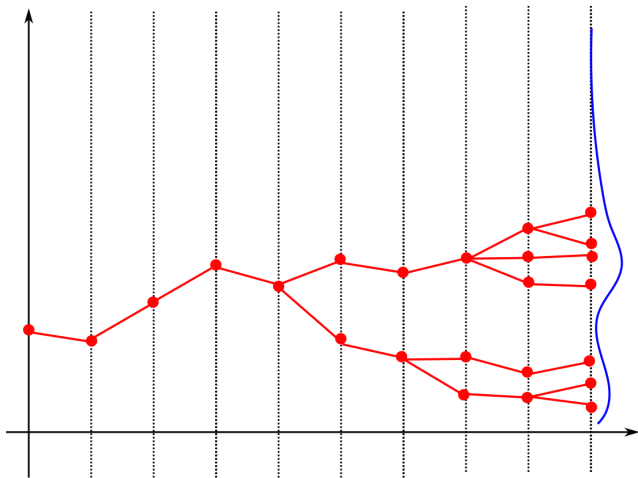
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Some questions

- ▶ $\text{Law}(X_n^i \mid \text{acceptance}) = \eta_n?$
- ▶ Convergence of the occupation measures of the genealogical trees?
- ▶ Use of the occupation measures of the complete ancestral tree?
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↪ **Feynman-Kac integration models on path spaces**

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⊂ **Part II & Part III (Application areas) & Part V (Theoretical results)**

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- ▶ Nonlinear evolution equations on $\mathcal{M}(E_n)$

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- ▶ **Link with nonlinear integro-differential equations?**

Nonlinear diffusion type models (d=1)

$$X_{n+1} = F_n(X_n, \eta_n, W_n) = X_n + a_n(X_n, \eta_n)\Delta + b_n(X_n, \eta_n) \sqrt{\Delta} W_n$$

with the Gaussian random variable

$$\mathbb{P}(W_n \in dw) = \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{w^2}{2}\right)$$

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$$(t_{n+1} - t_n) = \Delta \downarrow 0 \text{ \& } (a_n, b_n, X_n, \eta_n) = (a'_{t_n}, b'_{t_n}, X'_{t_n}, \eta'_{t_n})$$

$$dX'_t = a'_t(X'_t, \eta'_t)dt + b'_t(X'_t, \eta'_t)dW_t$$

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\Downarrow

Weak parabolic nonlinear PDE

$$\eta'_t = \text{Law}(X'_t) \Leftrightarrow \frac{d}{dt}\eta'_t(f) = \eta'_t(L_{t,\eta'_t}(f))$$

with the infinitesimal generator

$$L_{t,\eta'_t}(f)(x) = a'_t(x, \eta'_t) \partial f(x) + \frac{1}{2} (b'_t(x, \eta'_t))^2 \partial^2 f(x)$$

Two-steps jump-diffusion type model (d=1)

$$X_n \rightarrow X_{n+1/2} = F_n(X_n, \eta_n, W_n) \rightarrow X_{n+1} = \epsilon_{n+1} X_{n+1/2} + (1 - \epsilon_{n+1}) Y_{n+1}$$

$$\epsilon_{n+1} \sim e^{-V_{\eta_{n+1/2}}(X_{n+1/2}) \Delta} \delta_1 + \left(1 - e^{-V_{\eta_{n+1/2}}(X_{n+1/2}) \Delta}\right) \delta_0$$

$$Y_{n+1} \sim P_{\eta_{n+1/2}}(X_{n+1/2}, dy)$$

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Jump-diffusion limits

$$(a_n, b_n, V_n, P_n, X_n, \eta_n) = (a'_{t_n}, b'_{t_n}, V'_{\eta_{t_n}}, P'_{\eta_{t_n}}, X'_{t_n}, \eta'_{t_n})$$

between jumps = nonlinear diffusion as before, and jumps times

$$T_{n+1} = \inf \left\{ t \geq T_n : \int_{T_n}^t V'_s(X'_s, \eta'_s) ds \geq e_n \right\} \quad e_n \text{ iid } \text{expo}(\lambda = 1)$$

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Weak integro-differential equation $\frac{d}{dt} \eta'_t(f) = \eta'_t(L_{t, \eta'_t}(f))$

$$\begin{aligned} & L_{t, \eta'_t}(f)(x) \\ &= a'_t(x, \eta'_t) \partial f(x) + \frac{1}{2} (b'_t(x, \eta'_t))^2 \partial^2 f(x) + V'_{\eta'_t}(x) \int (f(y) - f(x)) P'_{\eta'_t}(x, dy) \end{aligned}$$

An abstract mathematical model

Nonlinear evolution equation $\in \mathcal{P}(E)$

$$\frac{d}{dt}\eta_t(f) = \eta_t(L_{t,\eta_t}(f))$$

\Downarrow

Mean field particle-simulation model = Markov $\in E^N$ with generator

$$\mathcal{L}_t(\varphi)(x^1, \dots, x^N) = \sum_{1 \leq i \leq N} L_{t, \frac{1}{N} \sum_{1 \leq j \leq N} \delta_{x^j}}^{(i)}(\varphi)(x^1, \dots, x^i, \dots, x^N)$$

Local sampling errors

Nonlinear evolution equation

$$d\eta_t(f) = \eta_t(L_{t,\eta_t}(f)) dt$$

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Mean field particle model (useless in practice)

$$d\eta_t^N(f) = \eta_t^N(L_{t,\eta_t^N}(f)) dt + \frac{1}{\sqrt{N}} dM_t^N(f)$$

with a sequence of martingales M_t^N with predictable increasing process

$$\langle M^N(f) \rangle_t = \int_0^t \eta_s^N \Gamma_{L_{s,\eta_s^N}}(f, f) ds$$

where Γ_L stands for the "carré du champ" operator

$$\Gamma_L(f, f) := L([f - f(x)]^2)(x) = L(f^2)(x) - 2f(x)L(f)(x)$$

Some basic notation

Markov chains

Nonlinear Markov models

How & Why it works?

- Some interpretations

- A stochastic perturbation analysis

- Uniform concentration inequalities

How & Why it works?

- ▶ (Biology) Individual based models (IBM).
- ▶ (Physics) Mean field approximation schemes.
- ▶ (Computer Sciences) Stochastic adaptive grid approximation.
- ▶ (Stats) Universal acceptance-rejection-recycling sampling schemes.
- ▶ (Probab) Stochastic linearization/perturbation technique.

$$\begin{aligned}\eta_n &= \Phi_n(\eta_{n-1}) \\ \eta_n^N &= \Phi_n(\eta_{n-1}^N) + \frac{1}{\sqrt{N}} V_n^N\end{aligned}$$

Theorem: $(V_n^N)_n \simeq_{N \uparrow \infty} (V_n)_n$ independent centered Gaussian fields.

$\Phi_{p,n}(\eta_p) = \eta_n$ stable sg \iff No propagation of local errors
 \implies Uniform control w.r.t. the time horizon

\rightsquigarrow New concentration inequalities for (general) interacting processes

Stochastic perturbation analysis = Taylor expansion

Gâteaux derivative of $\Phi_n : \mathcal{P}(E_{n-1}) \rightarrow \mathcal{P}(E_n)$

$$\frac{\partial}{\partial \epsilon} \Phi_n(\eta + \epsilon\mu)(f)|_{\epsilon=0} = \mu[d_\eta \Phi_n(f)]$$

with the first order linear/integral operator

$$d_\eta \Phi_n : f \in \mathcal{B}_b(E_n) \mapsto d_\eta \Phi_n(f) \in \mathcal{B}_b(E_{n-1})$$

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\Downarrow

Differential rule

$$d_\eta (\Phi_{n+1} \circ \Phi_n) = d_\eta \Phi_n \circ d_{\Phi_n(\eta)} \Phi_{n+1}$$

\Downarrow

Semigroup derivatives

$$\Phi_{\rho,n}(\mu) - \Phi_{\rho,n}(\eta) \simeq (\mu - \eta) d_\eta \Phi_{\rho,n}$$

Key idea = First order expansions

Key telescoping decomposition

$$\eta_n^N - \eta_n = \sum_{p=0}^n [\Phi_{p,n}(\eta_p^N) - \Phi_{p,n}(\Phi_p(\eta_{p-1}^N))]$$

⊕ First order expansion

$$\begin{aligned} & \sqrt{N} [\Phi_{p,n}(\eta_p^N) - \Phi_{p,n}(\Phi_p(\eta_{p-1}^N))] \\ &= \sqrt{N} \left[\Phi_{p,n} \left(\Phi_p(\eta_{p-1}^N) + \frac{1}{\sqrt{N}} V_p^N \right) - \Phi_{p,n}(\Phi_p(\eta_{p-1}^N)) \right] \\ &\simeq V_p^N D_{p,n} + \frac{1}{\sqrt{N}} R_{p,n}^N \end{aligned}$$

with $\underbrace{\text{a predictable } D_{p,n} - \text{first order operator}}_{\text{fluctuation term}} \oplus \underbrace{\text{2nd-order measure } R_{p,n}^N}_{\text{bias-term}}$

Stochastic perturbation model

Stochastic perturbation model

$$W_n^{\eta, N} := \sqrt{N} [\eta_n^N - \eta_n] = \sum_{0 \leq p \leq n} V_p^N D_{p,n} + \frac{1}{\sqrt{N}} R_n^N$$

Under some mixing condition on the limiting semigroups $\Phi_{p,n}$

$$\text{osc}(D_{p,n}(f)) \leq Cte e^{-(n-p)\alpha}$$

and

$$\mathbb{E} (|R_n^N(f)|^m) \leq Cte 2^{-m}(2m)!/m!$$

↓

Uniform concentration estimates w.r.t. the time parameter

Uniform concentration inequalities

Constants (c_1, c_2) related to (**bias, variance**), c finite constant
Test functions/observables $\|f_n\| \leq 1, \forall (x \geq 0, n \geq 0, N \geq 1)$.

When $E_n = \mathbb{R}^d$:

$$F_n(y) := \eta_n(1_{(-\infty, y]}) \quad \text{and} \quad F_n^N(y) := \eta_n^N(1_{(-\infty, y]}) \quad \text{with } y \in \mathbb{R}^d$$

The probability of any of the following events is greater than $1 - e^{-x}$.

$$|\eta_n^N - \eta_n|(f_n) \leq \frac{c_1}{N} (1 + x + \sqrt{x}) + \frac{c_2}{\sqrt{N}} \sqrt{x}$$

$$\sup_{0 \leq p \leq n} |[\eta_p^N - \eta_p](f_p)| \leq c \sqrt{x \log(n+e)/N}$$

$$\|F_n^N - F_n\| \leq c \sqrt{d(x+1)/N}$$

Coalescent tree based expansions

Weak propagation of chaos Taylor's type expansions:

$$\begin{aligned}\mathbb{P}_n^{(N,q)} &= \text{Law of the first } q \text{ ancestral lines } (q \leq N) \\ &= \mathbb{Q}_n^{\otimes q} + \sum_{1 \leq l \leq m} \frac{1}{N^l} d_l \mathbb{P}_n^{(q)} + O\left(\frac{1}{N^{m+1}}\right)\end{aligned}$$

with signed measures $d_l \mathbb{P}_n^{(q)}$ expressed in terms of **coalescent trees**.

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Romberg-Richardson interpolation: For any order $l \geq 1$

$$\sum_{1 \leq m \leq l} \frac{(-1)^{l-m}}{m!} \frac{m^l}{(l-m)!} \mathbb{P}_n^{(mN,q)} = \mathbb{Q}_n^{\otimes q} + O(1/N^l)$$