

# Concentration $\leq$ for Mean Field Particle Models

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- Concentration Inequalities for Mean Field Particle Models [HAL-INRIA RR-6901 (09)]. To appear in the Annals of Applied Probability (2010).
- DM, A. Doucet and S.S. Singh A Backward Particle Interpretation of Feynman-Kac Formulae HAL-INRIA RR-7019 (09). To appear in M2AN (2010)

# Outline

- 1 Introduction, motivations
- 2 Mean field particle models
- 3 Convergence analysis

## 1 Introduction, motivations

- Some notation
- Running ex. : Feynman-Kac models
- Nonlinear McKean type models

## 2 Mean field particle models

## 3 Convergence analysis

## Some notation

$E$  measurable state space,  $\mathcal{M}(E)$  &  $\mathcal{P}(E)$  measures & probabilities on  $E$   
 $\mathcal{B}(E)$  bounded meas. functions

- $(\mu, f) \in \mathcal{M}(E) \times \mathcal{B}(E) \quad \mapsto \quad \mu(f) = \int \mu(dx) f(x)$
- $M(x, dy)$  **integral operator over E**

$$\begin{aligned} M(f)(x) &= \int M(x, dy)f(y) \\ [\mu M](dy) &= \int \mu(dx)M(x, dy) \quad (\implies [\mu M](f) = \mu[M(f)]) \end{aligned}$$

- **Composition:**  $(M_1 M_2)(x, dz) = \int M_1(x, dy)M_2(y, dz)$
- **Boltzmann-Gibbs transformation :**  $G : E \rightarrow [0, \infty[$  with  $\mu(G) > 0$

$$\Psi_G(\mu)(dx) = \frac{1}{\mu(G)} G(x) \mu(dx)$$

## Running example : Feynman-Kac integration models

- Markov chain  $X_n$  on some state spaces  $E_n$ ,  $n=\text{time index}$  .
- Potential functions  $G_n$  :  $x_n \in E_n \rightarrow G_n(x_n) \in [0, 1]$

**Feynman-Kac path measures:**

$$d\mathbb{Q}_n := \frac{1}{Z_n} \left\{ \prod_{0 \leq p < n} G_p(X_p) \right\} d\mathbb{P}_n \quad \text{with} \quad \mathbb{P}_n := \text{Law}(X_0, \dots, X_n)$$

**The  $n$ -time marginals:**  $\forall f_n \in \mathcal{B}(E_n)$

$$\eta_n(f_n) := \frac{\gamma_n(f_n)}{\gamma_n(1)} \quad \text{with} \quad \gamma_n(f_n) := \mathbb{E} \left( f_n(X_n) \prod_{0 \leq p < n} G_p(X_p) \right)$$

## Example: Filtering, Hidden Markov Chains, Bayesian Inference

### Signal-observation type model

$$\mathbb{P}((X_n, Y_n) \in d(x, y) | (X_{n-1}, Y_{n-1})) := M_n(X_{n-1}, dx) g_n(x, y) \lambda_n(dy)$$

- Given the observation sequence  $Y = y$  with  $G_n(x_n) = g_n(x_n, y_n)$

$$\eta_n = \text{Law}(X_n \mid \forall 0 \leq p < n \quad Y_p = y_p) \quad \text{and} \quad \mathcal{Z}_{n+1} \propto p_n(y_0, \dots, y_n)$$

- In path space settings

$$\mathbb{Q}_n = \text{Law}((X_0, \dots, X_n) \mid \forall 0 \leq p < n \quad Y_p = y_p)$$

### Other examples of conditioning:

↪ rare event analysis, confinements problems, polymers, self-avoiding walks, ..

Ex.:  $G_n = 1_{A_n} \Rightarrow \mathbb{Q}_n = \text{Law}((X_0, \dots, X_n) \mid \forall 0 \leq p < n \quad X_p \in A_p)$

## Some continuous time models

$$\frac{d}{dt} \gamma_t(f) := \gamma_t(L^V(f)) \quad \text{with the Schroedinger operator} \quad L^V = L - V$$

- Feynman-Kac representation  $\gamma_t = \gamma_0 P_t^V$  with

$$\begin{aligned} P_t^V(f)(x) &= \mathbb{E}_x \left( f(X'_t) \exp \left\{ - \int_0^t V(X'_s) ds \right\} \right) \\ &\stackrel{t=t_n}{=} \mathbb{E}_x \left( f_n(X'_{[t_{n-1}, t_n]}) \prod_{0 \leq p < n} G_p(X_p) \right) \end{aligned}$$

with  $X_n = X'_{[t_n, t_{n+1}]}$  and  $G_n(X_n) = e^{- \int_{t_n}^{t_{n+1}} V(X'_s) ds}$ .

- Application areas : financial option pricing, ground state energies, particle non absorption models, Yaglom type quasi-invariant measures...

## Some continuous time models [Continuous time filtering models]

(X,Y)=(Signal-Observation)     $X_n = X'_{[t_n, t_{n+1}]}$     and     $dY_t = H(X'_t) dt + \sigma dV_t$

$$G_n(X_n) = e^{\int_{t_n}^{t_{n+1}} [H^*(X'_n(s))dY_s - \frac{1}{2}H^*(X'_n(s))H(X'_n(s))ds]}$$

⇓

$$\mathbb{Q}_n = \text{Law}((X'_{[0, t_{n+1}]}) \mid Y_s, s \leq t_n)$$

The  $t_n$ -marginals  $\eta_{t_n} \rightsquigarrow$  Kushner-Stratonovich SPDE

$$\eta_{t_n}(f) = \nu_0(f) + \int_0^{t_n} \eta_s(L(f))ds + \int_0^{t_n} [\eta_s(H^*f) - \eta_s(H^*)\eta_s(f)] (dY_s - \eta_s(H)ds)$$

*Note: Euler time discretization ↼ full discrete time model*

### 3 Key observations

$$\eta_n(f_n) := \frac{\gamma_n(f_n)}{\gamma_n(1)} \quad \text{with} \quad \gamma_n(f_n) := \mathbb{E} \left( f_n(X_n) \prod_{0 \leq p < n} G_p(X_p) \right)$$

- **First important observation:**

$$[ X_n := (X'_0, \dots, X'_n) \quad \& \quad G_n(X_n) := G'_n(X'_n)] \implies \eta_n = \mathbb{Q}'_n$$

- **Second important observation:**

$$\mathcal{Z}_n = \gamma_n(1) = \mathbb{E} \left( \prod_{0 \leq p < n} G_p(X_p) \right) = \prod_{0 \leq p < n} \eta_p(G_p)$$

**Proof:**

$$\gamma_n(1) = \gamma_{n-1}(G_{n-1}) = \eta_{n-1}(G_{n-1}) \gamma_{n-1}(1)$$

## 3 Key observations

- **Third important observation:** (H)  $M_n(x, dx') = H_n(x, x') \lambda_n(dx')$

$$\begin{aligned}\mathbb{Q}_n(d(x_0, \dots, x_n)) &= \frac{1}{\mathcal{Z}_n} \left\{ \prod_{0 \leq p < n} G_p(x_p) \right\} \mathbb{P}_n(d(x_0, \dots, x_n)) \\ &= \eta_n(dx_n) M_{n, \eta_{n-1}}(x_n, dx_{n-1}) \dots M_{1, \eta_0}(x_1, dx_0)\end{aligned}$$

with the backward Markov transitions :

$$M_{n, \eta}(x, dx') := \frac{\eta(dx') G_{n-1}(x') H_n(x', x)}{\eta(G_{n-1} H_n(., x))}$$

## Flows of Feynman-Kac measures

- A two step correction prediction model

$$\eta_n \xrightarrow{\text{Updating-correction}} \widehat{\eta}_n = \Psi_{G_n}(\eta_n) \xrightarrow{\text{Prediction/Markov transport}} \eta_{n+1} = \widehat{\eta}_n M_{n+1}$$

- Selection nonlinear transport formulae

$$\Psi_{G_n}(\eta_n) = \eta_n S_{n,\eta_n}$$

with, for **any**  $\epsilon_n \in [0, 1]$

$$S_{n,\eta_n}(x, \cdot) := \epsilon_n G_n(x) \delta_x + (1 - \epsilon_n G_n(x)) \Psi_{G_n}(\eta_n)$$

⇓

$$\eta_{n+1} = \eta_n (S_{n,\eta_n} M_{n+1}) := \eta_n K_{n+1,\eta_n}$$

## 1 Introduction, motivations

## 2 Mean field particle models

- Nonlinear McKean distribution flows
- Mean field particle interpretations
- The 4 types of particle approximation measures
- Some key advantages

## 3 Convergence analysis

## Nonlinear Markov chains $\eta_n = \text{Law}(\overline{X}_n)$ =Perfect sampling algorithm

- Nonlinear transport formulae :

$$\eta_{n+1} = \eta_n K_{n+1, \eta_n}$$

- Local transitions :

$$\mathbb{P}(\overline{X}_n \in dx_n \mid \overline{X}_{n-1}) = K_{n, \eta_{n-1}}(\overline{X}_{n-1}, dx_n) \quad \text{avec} \quad \eta_{n-1} = \text{Law}(\overline{X}_{n-1})$$

- McKean measures (canonical process) :

$$\mathbb{P}_n(d(x_0, \dots, x_n)) = \eta_0(dx_0) K_{1, \eta_0}(x_0, dx_1) \dots K_{n, \eta_{n-1}}(x_{n-1}, dx_n)$$

Other examples : Gaussian-McKean Vlasov type transitions

$$\overline{X}_{n+1} := d_n(\overline{X}_n, \eta_n) + \mathcal{N}(0, Q_n)$$

## Sampling pb $\Rightarrow$ Mean field particle interpretations

- Markov Chain  $\xi_n = (\xi_n^1, \dots, \xi_n^N) \in E_n^N$  s.t.

$$\eta_n^N := \frac{1}{N} \sum_{1 \leq i \leq N} \delta_{\xi_n^i} \simeq_{N \uparrow \infty} \eta_n$$

- Approximated local transitions ( $\forall 1 \leq i \leq N$ )

$$\xi_{n-1}^i \rightsquigarrow \xi_n^i \sim K_{n, \eta_{n-1}^N}(\xi_{n-1}^i, dx_n)$$

# Feynman-Kac models $\Leftrightarrow$ Genetic type stochastic algo.

$$\begin{bmatrix} \xi_n^1 \\ \vdots \\ \xi_n^i \\ \vdots \\ \xi_n^N \end{bmatrix} \xrightarrow{S_{n,\eta_n^N}} \begin{bmatrix} \widehat{\xi}_n^1 & \xrightarrow{M_{n+1}} & \xi_{n+1}^1 \\ \vdots & & \vdots \\ \widehat{\xi}_n^i & \longrightarrow & \xi_{n+1}^i \\ \vdots & & \vdots \\ \widehat{\xi}_n^N & \longrightarrow & \xi_{n+1}^N \end{bmatrix}$$

Accept/Reject-Selection : [Geometric clocks] [Confinement ex. :  $G_n = 1_A$ ]

$$S_{n,\eta_n^N}(\xi_n^i, \cdot) := \epsilon_n G_n(\xi_n^i) \delta_{\xi_n^i} + (1 - \epsilon_n G_n(\xi_n^i)) \sum_{j=1}^N \frac{G_n(\xi_n^j)}{\sum_{k=1}^N G_n(\xi_n^k)} \delta_{\xi_n^j}$$

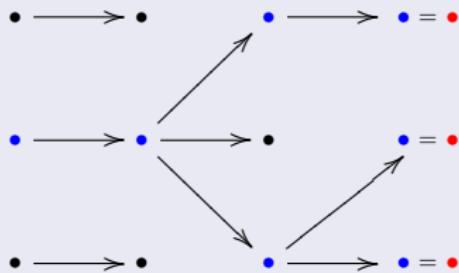
$\oplus$  Unbias particle normalizing Cts

$$\mathcal{Z}_n^{\textcolor{red}{N}} := \prod_{0 \leq p < n} \eta_p^{\textcolor{red}{N}}(G_p) \simeq \mathcal{Z}_n$$

$\supset$  Particle filters, Diffusion Monte Carlo (DMC), Quantum Monte Carlo (QMC), Sequential Monte Carlo methods (SMC), ...

# Interaction/branch. process $\hookrightarrow$ 4 types of occupation measures

$(N = 3)$



- Current population  $\hookrightarrow \frac{1}{N} \sum_{i=1}^N \delta_{\xi_n^i \leftarrow i\text{-th individual at time } n} \simeq \eta_n$
- Genealogical tree  $\hookrightarrow \frac{1}{N} \sum_{i=1}^N \delta_{(\xi_{0,n}^i, \xi_{1,n}^i, \dots, \xi_{n,n}^i) \leftarrow i\text{-th ancestral line}} \simeq \mathbb{Q}_n$
- Complete genealogical tree  $\hookrightarrow \frac{1}{N} \sum_{i=1}^N \delta_{(\xi_0^i, \xi_1^i, \dots, \xi_n^i)} \simeq \text{McKean meas.}$
- Forward particle approximation  $\sim$  complete genealogical tree :

$$\mathbb{Q}_n^N(d(x_0, \dots, x_n)) = \eta_n^N(dx_n) M_{n, \eta_{n-1}^N}(x_n, dx_{n-1}) \dots M_{1, \eta_0^N}(x_1, dx_0)$$

## Some key advantages

- Mean field models = stochastic linearization/perturbation technique :

$$\eta_n^N = \eta_{n-1}^N K_{n,\eta_{n-1}^N} + \frac{1}{\sqrt{N}} W_n^N$$

with [theorem]  $(W_n^N)_n \simeq (W_n)_n$  Indep. Centered Gaussian Fields.

- $\eta_n = \eta_{n-1} K_{n,\eta_{n-1}}$  stable  $\Rightarrow$  No propagation of local sampling errors  
 $\implies$  Uniform control w.r.t. the time horizon

- "No burning, no need to study the stability of MCMC type models".
- PDE viewpoint : Stochastic adaptive grid approximation
- Nonlinear system  $\leadsto$  "positive-benefic interactions".
- Simple and natural sampling algorithm.

1 Introduction, motivations

2 Mean field particle models

3 Convergence analysis

- Feynman-Kac type models
- Concentration inequalities

# Feynman-Kac models = rather complete analysis [LDP,CLT, Propagation of chaos] (FK Springer 2004 + refs)

- Example: Empirical processes  $\mathbb{L}_p$ -mean error estimates

$$\sup_{n \geq 0} \sup_{N \geq 1} \sqrt{N} \mathbb{E} \left( \sup_{f \in \mathcal{F}_n} |\eta_n^N(f) - \eta_n(f)|^p \right) < \infty$$

- (New) Propagations of chaos (+Patras & Rubenthaler (AAP 10))

$$\mathbb{P}_{n,q}^N := \text{Law}(\xi_n^1, \dots, \xi_n^q)$$

$$\simeq \eta_n^{\otimes q} + \frac{1}{N} \partial^1 \mathbb{P}_{n,q} + \dots + \frac{1}{N^k} \partial^k \mathbb{P}_{n,q} + \frac{1}{N^{k+1}} \partial^{k+1} \mathbb{P}_{n,q}^N$$

with  $\sup_{N \geq 1} \|\partial^{k+1} \mathbb{P}_{n,q}^N\|_{\text{tv}} < \infty$  &  $\sup_{n \geq 0} \|\partial^1 \mathbb{P}_{n,q}\|_{\text{tv}} \leq c q^2$ .

- (New) Additive functional (+ Doucet & Singh M2AN 10) :

$$N \mathbb{E} \left( [(\mathbb{Q}_n^N - \mathbb{Q}_n)(F_n)]^2 \right) \leq c \times (1/n + 1/N)$$

# Concentration inequalities

- Large deviation principles

[joint works with D. Dawson (Springer 05), A. Guionnet (SPA 98,IHP 01), T. Zajic (Bernoulli 03)]

$$\rightsquigarrow \sup_{n \geq 0} \limsup_{N \rightarrow \infty} \frac{1}{N} \log \mathbb{P} \left( \sup_{p \leq n} \frac{1}{2} \sum_{1 \leq k \leq d} |\eta_p^N(A_k) - \eta_p(A_k)| \geq \epsilon \right) \leq -\epsilon^2 / \beta(\Phi)$$

with  $\beta(\Phi)$  related to the contraction properties of the sg  $\Phi_{p,n}(\eta_p) = \eta_n$ .

- Non asymptotic estimates

[joint works with M. Ledoux (JTP 00), A. Doucet & S.Singh  
*(Feynman-Kac path space models & Additive functionals)* (M2AN-10)]

$$\rightsquigarrow \sup_{n \geq 0} \frac{1}{N} \log \mathbb{P} \left( |[\mathbb{Q}_n^N - \mathbb{Q}_n](F_n)| \geq \frac{b}{\sqrt{N}} + \epsilon \right) \leq -\epsilon^2 / (2b^2)$$

Concentration inequalities  $\sim$  stability prop. semigroups  $\Phi_{p,n}(\eta_p) = \eta_n$

[+ E. Rio (HAL-INRIA 09 & AAP 10)  $\supset$  FK and McKean-Vlasov type models ]

$$(\mathbf{H}\Phi) \forall \Phi_{p,n} \text{ s.t. } \Phi_{p,n}(\eta) - \Phi_{p,n}(\mu) = [\eta - \mu] \underbrace{D_\mu \Phi_{p,n}}_{\text{1st order op.}} + \underbrace{\mathcal{R}_{p,n}(\eta, \mu)}_{\text{2nd order } (\eta - \mu)^{\otimes 2}(\dots)}$$

Example : FK semigroups:

$$\Phi_{p,n}(\eta)(f) \propto \eta Q_{p,n}(f) \quad \text{with} \quad Q_{p,n}(f) = \mathbb{E}_{p,x_p} \left( f(X_n) \prod_{p \leq q < n} G_q(X_q) \right)$$

**Taylor expansion  $\Rightarrow$  ( $\mathbf{H}\Phi$ )**

$$\begin{aligned} [\Phi_{p,n}(\mu + \epsilon\nu) - \Phi_{p,n}(\mu)](f) &\propto (\cancel{\mu} + \epsilon\nu) Q_{p,n}[f - \Phi_{p,n}(\mu)(f)] \\ &\propto \epsilon \times \nu D_\mu \Phi_{p,n}(f) \end{aligned}$$

with the operator  $D_\mu \Phi_{p,n} \propto Q_{p,n} [Id - \Phi_{p,n}(\mu)]$

## Concentration inequalities $\sim$ stability prop. semigroups $\Phi_{p,n}(\eta_p) = \eta_n$

[Theo:] (**HΦ**)  $\Rightarrow \forall x \geq 0$ , the probability of the next events is  $\geq 1 - e^{-x}$

$$(\eta_n^N - \eta_n)(f) \leq \frac{r_n}{N} (1 + \epsilon_0^{-1}(x)) + \bar{\sigma}_n^2 b_n^* \epsilon_1^{-1} \left( \frac{x}{N \bar{\sigma}_n^2} \right) \quad [\text{Bennett } (r=0)]$$

$$(\eta_n^N - \eta_n)(f) \leq \frac{r_n}{N} (1 + \epsilon_0^{-1}(x)) + \sqrt{\frac{2x}{N}} \beta_n \quad [\text{Hoeffding } (r=0)]$$

with

$$\epsilon_0(\lambda) = \frac{1}{2} (\lambda - \log(1 + \lambda)) , \quad \epsilon_1(\lambda) = (1 + \lambda) \log(1 + \lambda) - \lambda$$

Cts :

$r_n \sim$  bias second order &  $\bar{\sigma}_n, \beta_n, b_n^* \sim$  Dobrushin coef. 1st order operators.

Note : Crude bounds

$$\epsilon_0^{-1}(x) \leq 2x + 2\sqrt{x} \quad \epsilon_1^{-1}(x) \leq x/3 + \sqrt{2x} \quad \rightsquigarrow [\text{Bernstein}]$$

## Application : Time homogeneous Feynman-Kac models $(M, G)$

$(H) \exists m : M^m(x, \cdot) \geq \epsilon M^m(y, \cdot) \quad \text{and} \quad \delta := \sup \prod_{0 \leq p < m} (G(x_p)/G(y_p)) < \infty$

[Corollary:]

$\forall x \geq 0$ , time horizon  $n$ , the probability of the next events is  $\geq 1 - e^{-x}$

$$\begin{aligned} (\eta_n^N - \eta_n)(f) &\leq \frac{4a}{N} (1 + \epsilon_0^{-1}(x)) + 8a \epsilon_1^{-1} \left( \frac{x}{4bN} \right) \\ (\eta_n^N - \eta_n)(f) &\leq \frac{4a}{N} (1 + \epsilon_0^{-1}(x)) + 2\sqrt{\frac{2bx}{N}} \end{aligned}$$

with  $a \leq m (\delta/\epsilon)^5$  and  $b \leq m (\delta/\epsilon)^4$ .