

Particle methods in statistical learning and risk analysis

P. Del Moral

UNSW, School of Mathematics and Statistics

2014 BIG DATA SCIENCE Workshop, UNSW july 1st 2014

Some hyper-refs

- ▶ Feynman-Kac formulae, *Genealogical & Interacting Particle Systems with appl.*, Springer (2004)
- ▶ Mean field simulation for Monte Carlo integration. Chapman - Hall (2013) [+ Refs]
- ▶ More references on website <http://web.maths.unsw.edu.au/~peterdel-moral/simulinks.html> [+ Links]

Stochastic particle sampling methods

Sampling conditional distributions

Some concrete applications

Stochastic particle sampling methods

Sampling conditional distributions

Some concrete applications

Introduction

Stochastic particle methods
=
Universal adaptive sampling technique

2 types of stochastic interacting particle models:

- ▶ Diffusive particle models with mean field drifts
[McKean-Vlasov style]
- ▶ Branching and Interacting jump particle models
[Boltzmann & Feynman-Kac style]

Workshop \subset Interacting jumps models

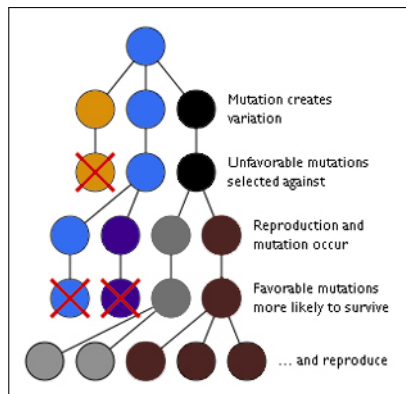


- ▶ Interacting jumps = Recycling transitions =
- ▶ Discrete time models (\Leftrightarrow geometric **rejection/jump** times)



Genetic type interacting particle models

- ▶ **Mutation**-Proposals w.r.t. Markov transitions $X_{n-1} \rightsquigarrow X_n \in E_n$.
- ▶ **Selection**-Rejection-Recycling w.r.t. potential/fitness function G_n .



Equivalent particle algorithms

Sequential Monte Carlo	Sampling	Resampling
Particle Filters	Prediction	Updating
Genetic Algorithms	Mutation	Selection
Evolutionary Population	Exploration	Branching-selection
Diffusion Monte Carlo	Free evolutions	Absorption
Quantum Monte Carlo	Walkers motions	Reconfiguration
Sampling Algorithms	Transition proposals	Accept-reject-recycle

Equivalent particle algorithms

Sequential Monte Carlo	Sampling	Resampling
Particle Filters	Prediction	Updating
Genetic Algorithms	Mutation	Selection
Evolutionary Population	Exploration	Branching-selection
Diffusion Monte Carlo	Free evolutions	Absorption
Quantum Monte Carlo	Walkers motions	Reconfiguration
Sampling Algorithms	Transition proposals	Accept-reject-recycle

More botanical names:

bootstrapping, spawning, cloning, pruning, replenish, multi-level splitting, enrichment, go with the winner, quantum teleportation,...

Equivalent particle algorithms

Sequential Monte Carlo	Sampling	Resampling
Particle Filters	Prediction	Updating
Genetic Algorithms	Mutation	Selection
Evolutionary Population	Exploration	Branching-selection
Diffusion Monte Carlo	Free evolutions	Absorption
Quantum Monte Carlo	Walkers motions	Reconfiguration
Sampling Algorithms	Transition proposals	Accept-reject-recycle

More botanical names:

bootstrapping, spawning, cloning, pruning, replenish, multi-level splitting, enrichment, go with the winner, quantum teleportation,...

1947/1948

(Fermi/Kahn-Harris)

≤ Meta-Heuristic style stochastic algo. ≤ 1996

Equivalent particle algorithms

Sequential Monte Carlo	Sampling	Resampling
Particle Filters	Prediction	Updating
Genetic Algorithms	Mutation	Selection
Evolutionary Population	Exploration	Branching-selection
Diffusion Monte Carlo	Free evolutions	Absorption
Quantum Monte Carlo	Walkers motions	Reconfiguration
Sampling Algorithms	Transition proposals	Accept-reject-recycle

More botanical names:

bootstrapping, spawning, cloning, pruning, replenish, multi-level splitting, enrichment, go with the winner, quantum teleportation,...

1947/1948

(Fermi/Kahn-Harris)

≤ Meta-Heuristic style stochastic algo. ≤ 1996

Convergence/Performance analysis : CLT, LDP, \mathbb{L}_p -estimates, Empirical processes, Moderate deviations, propagations of chaos, unif cv w.r.t. time, new stochastic models....

Concentration analysis = Exponential deviation proba. estimates

Stochastic particle sampling methods

Sampling conditional distributions

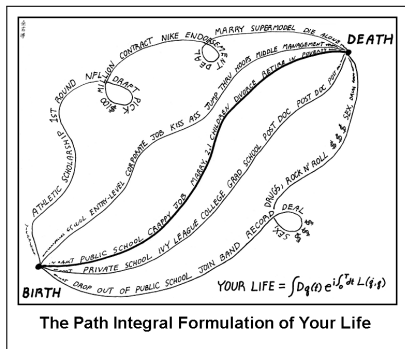
Some concrete applications

A single stochastic model

Particle interpretation of Feynman-Kac path integrals

=

ANY CONDITIONAL DISTRIBUTION



Some conditional distributions

- ▶ **Signal processing**

Law (stoch. process X | partial observations Y)

Ex.: radar/sonar/data assimilation/multiple object tracking

Some conditional distributions

- ▶ **Signal processing**

Law (**stoch. process X** | **partial observations Y**)

Ex.: radar/sonar/data assimilation/multiple object tracking

- ▶ **Information theory - Statistical inference**

Law (**kinetic or stat. parameter Θ** | **partial observations Y**)

Ex.: Calibration of models, model selection, Bayesian inference

Some conditional distributions

- ▶ **Signal processing**

Law (**stoch. process X** | **partial observations Y**)

Ex.: radar/sonar/data assimilation/multiple object tracking

- ▶ **Information theory - Statistical inference**

Law (**kinetic or stat. parameter Θ** | **partial observations Y**)

Ex.: Calibration of models, model selection, Bayesian inference

- ▶ **Black box - risk analysis**

Law (**Inputs/process** | **critical output/rare event**)

Ex.: Uncertainty propagations, sensitivity analysis, ruin processes, rare event simulation

- ▶ **Global optimization**: interacting simulated annealing, ...

Particle algorithms

Law (r.v./process | observations/events)

$\simeq N = \text{number of samples/computational power} \uparrow \infty$

Empirical measure: $\frac{1}{N} \sum_{1 \leq i \leq N} \delta_{X^i}$

Particle algorithms

Law (r.v./process | observations/events)

$\simeq N = \text{number of samples/computational power} \uparrow \infty$

Empirical measure: $\frac{1}{N} \sum_{1 \leq i \leq N} \delta_{X^i}$

- ▶ $X^i =$ Conditional/Posterior "samples"
- ▶ Default/Learning genealogical trees $\Rightarrow X^i \in \{\text{ancestral lines}\}$

Particle algorithms

Law (r.v./process | observations/events)

$\simeq N = \text{number of samples/computational power} \uparrow \infty$

Empirical measure: $\frac{1}{N} \sum_{1 \leq i \leq N} \delta_{X^i}$

- ▶ $X^i = \text{Conditional/Posterior "samples"}$
- ▶ Default/Learning genealogical trees $\Rightarrow X^i \in \{\text{ancestral lines}\}$

&

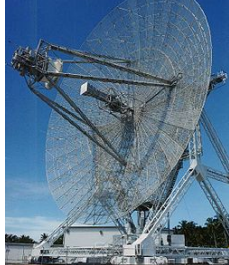
Law (observations/events) $\stackrel{\text{unbias}}{\simeq} \prod \% \text{ success/branching rate}$

Stochastic particle sampling methods

Sampling conditional distributions

Some concrete applications

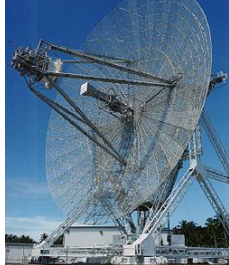
Signal processing & filtering models



Law (Markov process X | Noisy & Partial observations Y)

- ▶ **Signal X** : target evolution (missile, plane, robot, vehicle, image contours), forecasting models, assets volatility, speech signals, ...
- ▶ **Observation Y** : Radar/Sonar/Gps sensors, financial assets prices, image processing, audio receivers, statistical data measurements, ...

Signal processing & filtering models



Law (**Markov process X** | **Noisy & Partial observations Y**)

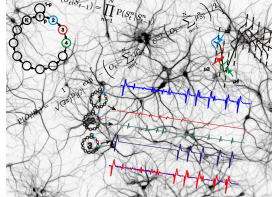
- ▶ **Signal X** : target evolution (missile, plane, robot, vehicle, image contours), forecasting models, assets volatility, speech signals, ...
- ▶ **Observation Y** : Radar/Sonar/Gps sensors, financial assets prices, image processing, audio receivers, statistical data measurements, ...

Industrial transferts & some research funding

- ▶ PhD/LAAS-CNRS-French Defense : 1989-1995.
- ▶ ANR Propagation 2009-2012: 2.3 M euros.
- ▶ DGA, DCNS-SIS, THALES, ASTRIUM (Radar/Sonar/GPS).
- ▶ Météo France (2000-2010) : Forecasting and turbulent fluid models

Hidden Markov chains problems

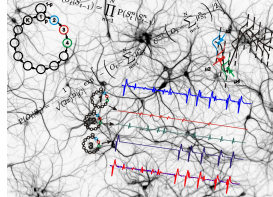
$\Theta \rightsquigarrow$ Signal $X^\Theta \rightsquigarrow$ observations Y^Θ



Law (**fixed parameter** Θ | **Noisy & Partial observations** Y^Θ)

- ▶ **Parameter** Θ : kinetic model unknown parameters, statistical parameters (signal/sensors), hypothesis testing, ..
- ▶ **Signal** X^Θ : Single or multiple targets evolution, forecasting models, financial assets volatility, speech signals, video images, ...
- ▶ **Observation** Y^Θ : Radar/Sonar/Gps sensors, financial assets prices, image processing, statistical data measurements, ...

Hidden Markov chains problems



$\Theta \rightsquigarrow$ Signal $X^\Theta \rightsquigarrow$ observations Y^Θ

Law (**fixed parameter** Θ | **Noisy & Partial observations** Y^Θ)

- ▶ **Parameter** Θ : kinetic model unknown parameters, statistical parameters (signal/sensors), hypothesis testing, ..
- ▶ **Signal** X^Θ : Single or multiple targets evolution, forecasting models, financial assets volatility, speech signals, video images, ...
- ▶ **Observation** Y^Θ : Radar/Sonar/Gps sensors, financial assets prices, image processing, statistical data measurements, ...

Industrial transferts & some research funding

- ▶ Biips Software development (2006-2014).
- ▶ Epidemiology : ANR Viroscopy 2009-2012 (40KE).
- ▶ Food risk, Eco-Microbiology : ARC EPS (2011) (80KE+Post-Doc).

Uncertainty propagations in numerical codes



Law (**Inputs** \mathcal{I} | **Outputs** $\mathcal{O} = C(\mathcal{I}) \in$ **Reference or Critical event**)



$$\left. \begin{array}{l} \mu = \text{Law}(\mathcal{I}) \\ A = \{ \mathcal{I} : C(\mathcal{I}) \in B \} \end{array} \right\} \longrightarrow \mathbb{P}(\mathcal{I} \in A) \ \& \ \text{Law}(\mathcal{I} \mid \mathcal{I} \in A)$$

Uncertainty propagations in numerical codes



Law (**Inputs** \mathcal{I} | **Outputs** $\mathcal{O} = C(\mathcal{I}) \in$ **Reference or Critical event**)



$$\left. \begin{array}{l} \mu = \text{Law}(\mathcal{I}) \\ A = \{ \mathcal{I} : C(\mathcal{I}) \in B \} \end{array} \right\} \longrightarrow \mathbb{P}(\mathcal{I} \in A) \ \& \ \text{Law}(\mathcal{I} \mid \mathcal{I} \in A)$$

Industrial transferts & some research funding

- ▶ ARC INRIA RARE (2009 - 7 INRIA teams collaboration project).
- ▶ Satellite debris tracking/control : ONERA & CNES (40KE+PhD).
- ▶ Nuclear plant security : EDF (40KE+PhD)
- ▶ Offshore structures reliability : IFREMER (20KE).